

## OpenGL Transformations

### Objectives

- Learn how to carry out transformations in OpenGL
  - Rotation
  - Translation
  - Scaling
- Introduce OpenGL matrix modes
  - Model-view
  - Projection

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KENT STATE 1

## OpenGL Matrices

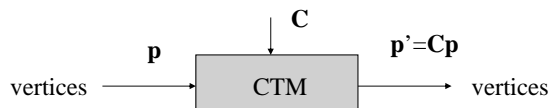
- In OpenGL matrices are part of the state
- Multiple types
  - Model-View (`GL_MODELVIEW`)
  - Projection (`GL_PROJECTION`)
  - Texture (`GL_TEXTURE`) (ignore for now)
  - Color (`GL_COLOR`) (ignore for now)
- Single set of functions for manipulation
- Select which to manipulated by
  - `glMatrixMode(GL_MODELVIEW);`
  - `glMatrixMode(GL_PROJECTION);`

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KENT STATE 2

## Current Transformation Matrix (CTM)

- Conceptually there is a 4 x 4 homogeneous coordinate matrix, the *current transformation matrix* (CTM) that is part of the state and is applied to all vertices that pass down the pipeline
- The CTM is defined in the user program and loaded into a transformation unit



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KENT STATE 3

## CTM operations

- The CTM can be altered either by loading a new CTM or by post-multiplication
  - Load an identity matrix:  $C \leftarrow I$
  - Load an arbitrary matrix:  $C \leftarrow M$
  
  - Load a translation matrix:  $C \leftarrow T$
  - Load a rotation matrix:  $C \leftarrow R$
  - Load a scaling matrix:  $C \leftarrow S$
  
  - Postmultiply by an arbitrary matrix:  $C \leftarrow CM$
  - Postmultiply by a translation matrix:  $C \leftarrow CT$
  - Postmultiply by a rotation matrix:  $C \leftarrow CR$
  - Postmultiply by a scaling matrix:  $C \leftarrow CS$

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KENT STATE 4

## Rotation about a Fixed Point

Start with identity matrix:  $C \leftarrow I$   
Move fixed point to origin:  $C \leftarrow CT$   
Rotate:  $C \leftarrow CR$   
Move fixed point back:  $C \leftarrow CT^{-1}$

Result:  $C = TRT^{-1}$  which is **backwards**.

This result is a consequence of doing postmultiplications.  
Let's try again.

## Reversing the Order

We want  $C = T^{-1}RT$   
so we must do the operations in the following order

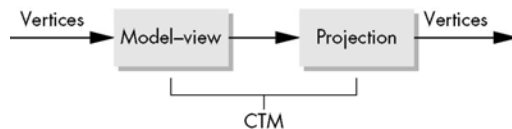
$C \leftarrow I$   
 $C \leftarrow CT^{-1}$   
 $C \leftarrow CR$   
 $C \leftarrow CT$

Each operation corresponds to one function call in the program.

Note that the last operation specified is the first executed in the program

## CTM in OpenGL

- OpenGL has a model-view and a projection matrix in the pipeline which are concatenated together to form the CTM
- Can manipulate each by first setting the correct matrix mode



## Rotation, Translation, Scaling

Load an identity matrix:

```
glLoadIdentity()
```

Multiply on right:

```
glRotatef(theta, vx, vy, vz)
```

$\theta$  in degrees,  $(vx, vy, vz)$  define axis of rotation

```
glTranslatef(dx, dy, dz)
```

```
glScalef(sx, sy, sz)
```

Each has a float (f) and double (d) format (**glScaled**)

## Example

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- Rotation about z axis by 30 degrees with a fixed point of (1.0, 2.0, 3.0)

```
glMatrixMode(GL_MODELVIEW);
glLoadIdentity();
glTranslatef(1.0, 2.0, 3.0);
glRotatef(30.0, 0.0, 0.0, 1.0);
glTranslatef(-1.0, -2.0, -3.0);
```

- Remember that last matrix specified in the program is the first applied

## Arbitrary Matrices

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- Can load and multiply by matrices defined in the application program

```
glLoadMatrixf(m)
glMultMatrixf(m)
```

- The matrix **m** is a one dimension array of 16 elements which are the components of the desired 4 x 4 matrix stored by columns
- In `glMultMatrixf`, **m** multiplies the existing matrix on the right

## Matrix Stacks

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- In many situations we want to save transformation matrices for use later
  - Traversing hierarchical data structures (Chapter 10)
  - Avoiding state changes when executing display lists
- OpenGL maintains stacks for each type of matrix

- Push/Pop present type (as set by `glMatrixMode`)  
by

```
glPushMatrix()
glPopMatrix()
```

## Reading Back Matrices

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- Can also access matrices (and other parts of the state) by *query* functions

```
glGetIntegerv
glGetFloatv
glGetBooleanv
glGetDoublev
glIsEnabled
```

- For matrices, we use as

```
double m[16];
glGetFloatv(GL_MODELVIEW, m);
```

## Using Transformations

- Example: use idle function to rotate a cube and mouse function to change direction of rotation
- Start with a program that draws a cube (`colorcube.c`) in a standard way
  - Centered at origin
  - Sides aligned with axes
  - Will discuss modeling in next lecture

## main.c

```
void main(int argc, char **argv)
{
    glutInit(&argc, argv);
    glutInitDisplayMode(GLUT_DOUBLE | GLUT_RGB |
        GLUT_DEPTH);
    glutInitWindowSize(500, 500);
    glutCreateWindow("colorcube");
    glutReshapeFunc(myReshape);
    glutDisplayFunc(display);
    glutIdleFunc(spinCube);
    glutMouseFunc(mouse);
    glEnable(GL_DEPTH_TEST);
    glutMainLoop();
}
```

## Idle and Mouse callbacks

```
void spinCube()
{
    theta[axis] += 2.0;
    if( theta[axis] > 360.0 ) theta[axis] -= 360.0;
    glutPostRedisplay();
}

void mouse(int btn, int state, int x, int y)
{
    if(btn==GLUT_LEFT_BUTTON && state == GLUT_DOWN)
        axis = 0;
    if(btn==GLUT_MIDDLE_BUTTON && state == GLUT_DOWN)
        axis = 1;
    if(btn==GLUT_RIGHT_BUTTON && state == GLUT_DOWN)
        axis = 2;
}
```

## Display callback

```
void display()
{
    glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
    glLoadIdentity();
    glRotatef(theta[0], 1.0, 0.0, 0.0);
    glRotatef(theta[1], 0.0, 1.0, 0.0);
    glRotatef(theta[2], 0.0, 0.0, 1.0);
    colorcube();
    glutSwapBuffers();
}
```

Note that because of fixed form of callbacks, variables such as `theta` and `axis` must be defined as globals

Camera information is in standard reshape callback

## Using the Model-view Matrix

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- In OpenGL the model-view matrix is used to
  - Position the camera
    - Can be done by rotations and translations but is often easier to use `gluLookAt`
  - Build models of objects
- The projection matrix is used to define the view volume and to select a camera lens

## Model-view and Projection Matrices

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- Although both are manipulated by the same functions, we have to be careful because incremental changes are always made by postmultiplication
  - For example, rotating model-view and projection matrices by the same matrix are not equivalent operations.
  - Postmultiplication of the model-view matrix is equivalent to premultiplication of the projection matrix

## Smooth Rotation

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- From a practical standpoint, we often want to use transformations to move and reorient an object smoothly
  - Problem: find a sequence of model-view matrices  $M_0, M_1, \dots, M_n$  so that when they are applied successively to one or more objects we see a smooth transition
- For orientating an object, we can use the fact that every rotation corresponds to part of a great circle on a sphere
  - Find the axis of rotation and angle
  - Virtual trackball (see text)

## Incremental Rotation

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- Consider the two approaches
  - For a sequence of rotation matrices  $R_0, R_1, \dots, R_n$ , find the Euler angles for each and use  $R_i = R_{iz} R_{iy} R_{ix}$ 
    - Not very efficient
  - Use the final positions to determine the axis and angle of rotation, then increment only the angle
- Quaternions can be more efficient than either

## Quaternions

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- Extension of imaginary numbers from two to three dimensions
- Requires one real and three imaginary components **i, j, k**

$$q = q_0 + q_1\mathbf{i} + q_2\mathbf{j} + q_3\mathbf{k}$$

- Quaternions can express rotations on sphere smoothly and efficiently. Process:
  - Model-view matrix → quaternion
  - Carry out operations with quaternions
  - Quaternion → Model-view matrix

## Interfaces

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- One of the major problems in interactive computer graphics is how to use two-dimensional devices such as a mouse to interface with three dimensional objects
- Example: how to form an instance matrix?
- Some alternatives
  - Virtual trackball
  - 3D input devices such as the spaceball
  - Use areas of the screen
    - Distance from center controls angle, position, scale depending on mouse button depressed