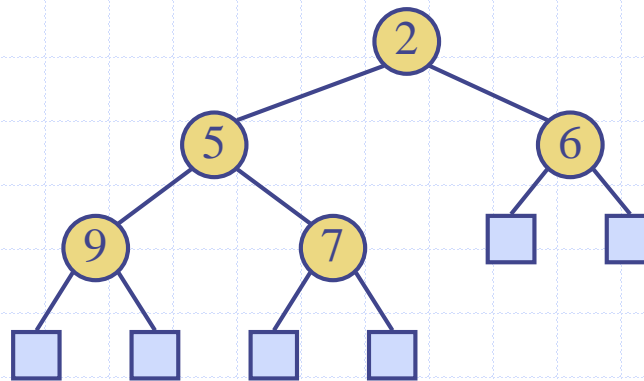


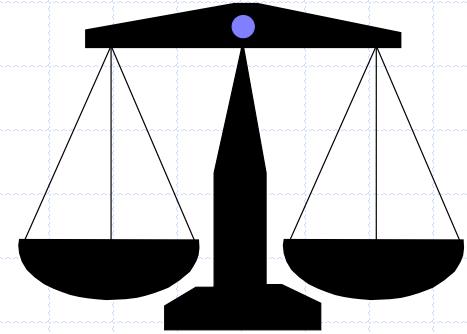
# Heaps and Priority Queues



# Priority Queue ADT (§ 2.4.1)



- ◆ A priority queue stores a collection of items
- ◆ An item is a pair (key, element)
- ◆ Main methods of the Priority Queue ADT
  - **insertItem(k, o)**  
inserts an item with key  $k$  and element  $o$
  - **removeMin()**  
removes the item with smallest key and returns its element
- ◆ Additional methods
  - **minKey()**  
returns, but does not remove, the smallest key of an item
  - **minElement()**  
returns, but does not remove, the element of an item with smallest key
  - **size(), isEmpty()**
- ◆ Applications:
  - Standby flyers
  - Auctions
  - Stock market



# Total Order Relation

- ◆ Keys in a priority queue can be arbitrary objects on which an order is defined
- ◆ Two distinct items in a priority queue can have the same key
- ◆ Mathematical concept of total order relation  $\leq$ 
  - **Reflexive** property:  
 $x \leq x$
  - **Antisymmetric** property:  
 $x \leq y \wedge y \leq x \Rightarrow x = y$
  - **Transitive** property:  
 $x \leq y \wedge y \leq z \Rightarrow x \leq z$

# Comparator ADT (§ 2.4.1)



- ◆ A comparator encapsulates the action of comparing two objects according to a given total order relation
  - ◆ A generic priority queue uses an auxiliary comparator
  - ◆ The comparator is external to the keys being compared
  - ◆ When the priority queue needs to compare two keys, it uses its comparator
- ◆ Methods of the Comparator ADT, all with Boolean return type
    - `isLessThan(x, y)`
    - `isLessThanOrEqualTo(x,y)`
    - `isEqualTo(x,y)`
    - `isGreaterThan(x, y)`
    - `isGreaterThanOrEqualTo(x,y)`
    - `isComparable(x)`

# Sorting with a Priority Queue (§ 2.4.2)



- ◆ We can use a priority queue to sort a set of comparable elements
  - Insert the elements one by one with a series of `insertItem(e, e)` operations
  - Remove the elements in sorted order with a series of `removeMin()` operations
- ◆ The running time of this sorting method depends on the priority queue implementation

## Algorithm *PQ-Sort*( $S, C$ )

**Input** sequence  $S$ , comparator  $C$  for the elements of  $S$

**Output** sequence  $S$  sorted in increasing order according to  $C$

$P \leftarrow$  priority queue with comparator  $C$

**while**  $\neg S.isEmpty()$

$e \leftarrow S.remove(S.first())$

$P.insertItem(e, e)$

**while**  $\neg P.isEmpty()$

$e \leftarrow P.removeMin()$

$S.insertLast(e)$

# Sequence-based Priority Queue

- ◆ Implementation with an unsorted list



- ◆ Performance:

- **insertItem** takes  $O(1)$  time since we can insert the item at the beginning or end of the sequence
- **removeMin**, **minKey** and **minElement** take  $O(n)$  time since we have to traverse the entire sequence to find the smallest key

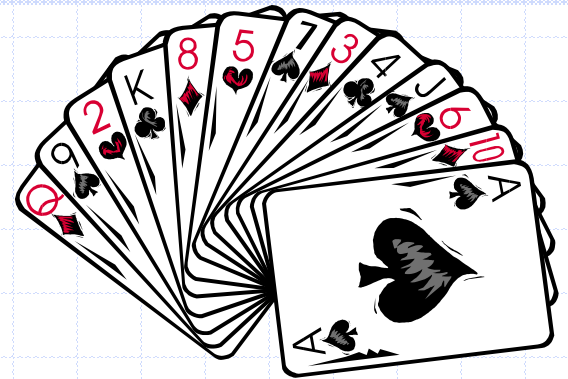
- ◆ Implementation with a sorted list



- ◆ Performance:

- **insertItem** takes  $O(n)$  time since we have to find the place where to insert the item
- **removeMin**, **minKey** and **minElement** take  $O(1)$  time since the smallest key is at the beginning of the sequence

# Selection-Sort



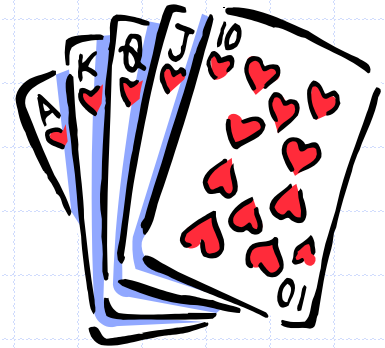
- ◆ Selection-sort is the variation of PQ-sort where the priority queue is implemented with an unsorted sequence



- ◆ Running time of Selection-sort:
  - Inserting the elements into the priority queue with  $n$  **insertItem** operations takes  $O(n)$  time
  - Removing the elements in sorted order from the priority queue with  $n$  **removeMin** operations takes time proportional to

$$1 + 2 + \dots + n$$

- ◆ Selection-sort runs in  $O(n^2)$  time



# Insertion-Sort

- ◆ Insertion-sort is the variation of PQ-sort where the priority queue is implemented with a sorted sequence



- ◆ Running time of Insertion-sort:
  - Inserting the elements into the priority queue with  $n$  **insertItem** operations takes time proportional to
$$1 + 2 + \dots + n$$
  - Removing the elements in sorted order from the priority queue with a series of  $n$  **removeMin** operations takes  $O(n)$  time
- ◆ Insertion-sort runs in  $O(n^2)$  time

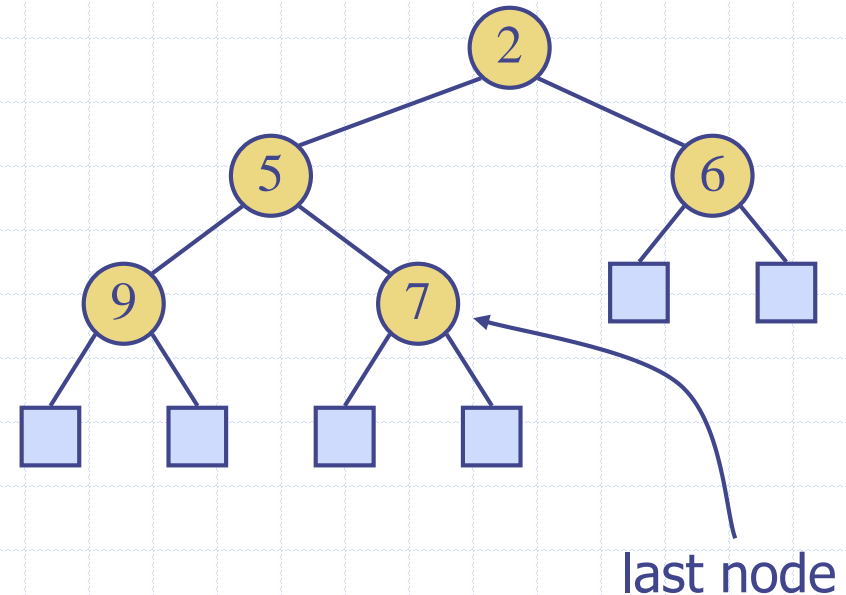


# What is a heap (§2.4.3)



- ◆ A heap is a binary tree storing keys at its internal nodes and satisfying the following properties:
  - **Heap-Order:** for every internal node  $v$  other than the root,  $key(v) \geq key(parent(v))$
  - **Complete Binary Tree:** let  $h$  be the height of the heap
    - ◆ for  $i = 0, \dots, h - 1$ , there are  $2^i$  nodes of depth  $i$
    - ◆ at depth  $h - 1$ , the internal nodes are to the left of the external nodes

- ◆ The last node of a heap is the rightmost internal node of depth  $h - 1$



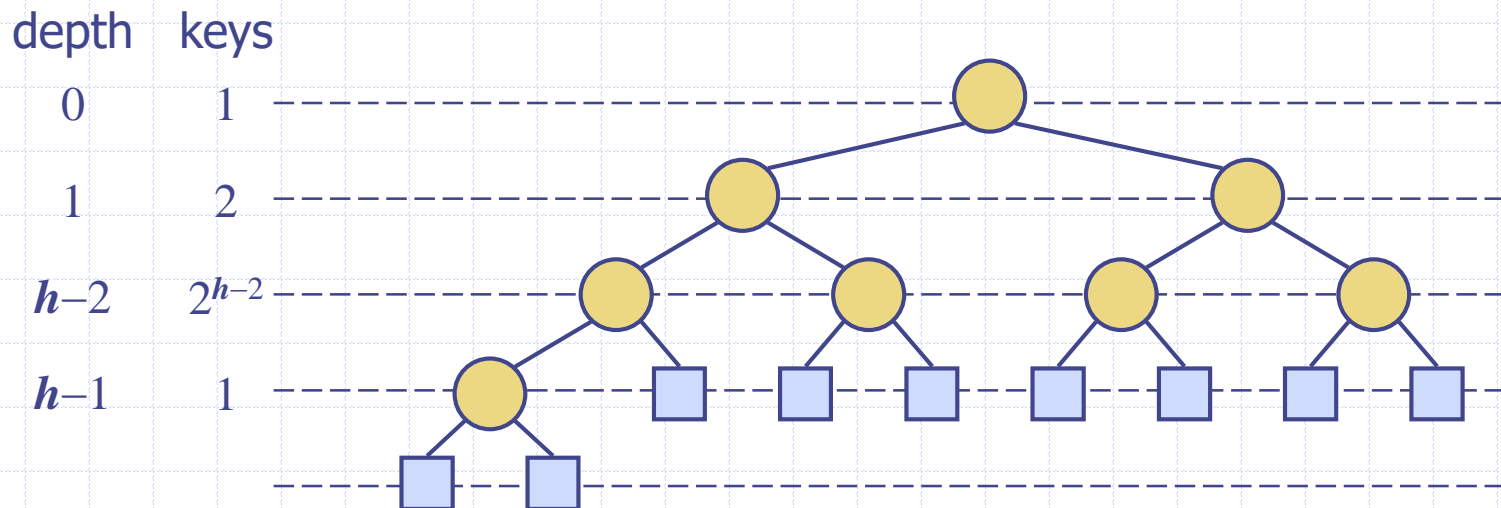
# Height of a Heap (§2.4.3)



◆ **Theorem:** A heap storing  $n$  keys has height  $O(\log n)$

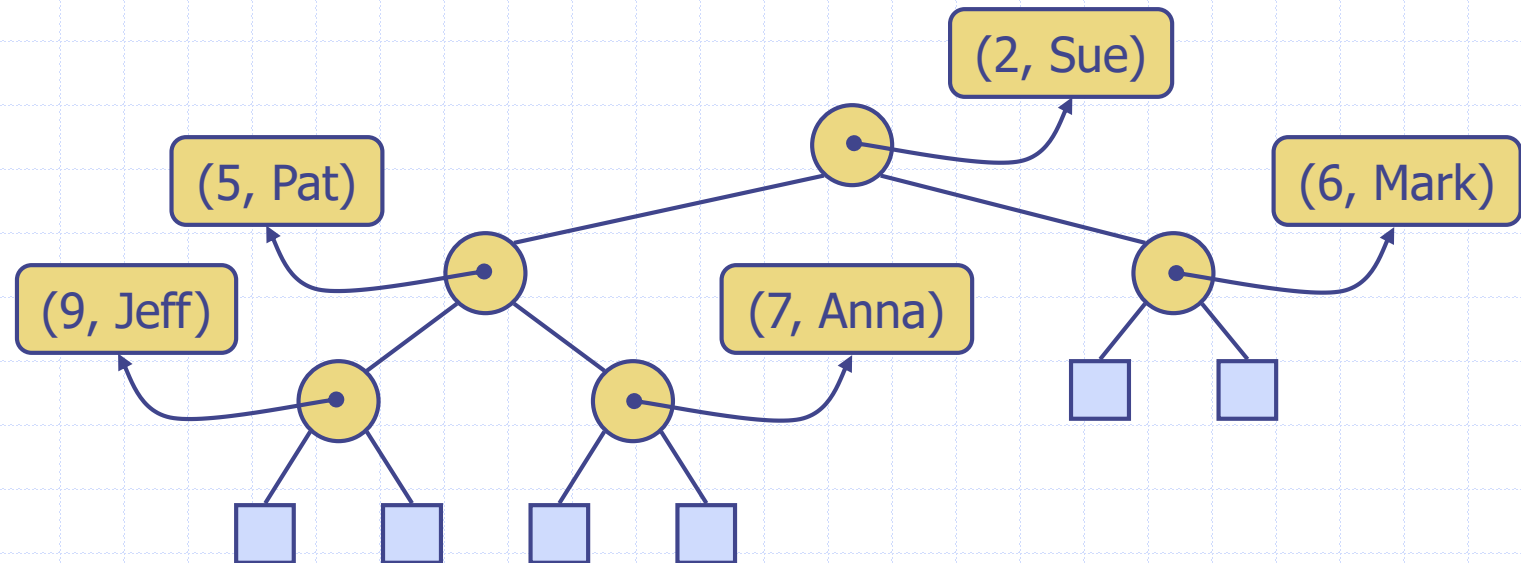
Proof: (we apply the complete binary tree property)

- Let  $h$  be the height of a heap storing  $n$  keys
- Since there are  $2^i$  keys at depth  $i = 0, \dots, h - 2$  and at least one key at depth  $h - 1$ , we have  $n \geq 1 + 2 + 4 + \dots + 2^{h-2} + 1$
- Thus,  $n \geq 2^{h-1}$ , i.e.,  $h \leq \log n + 1$



# Heaps and Priority Queues

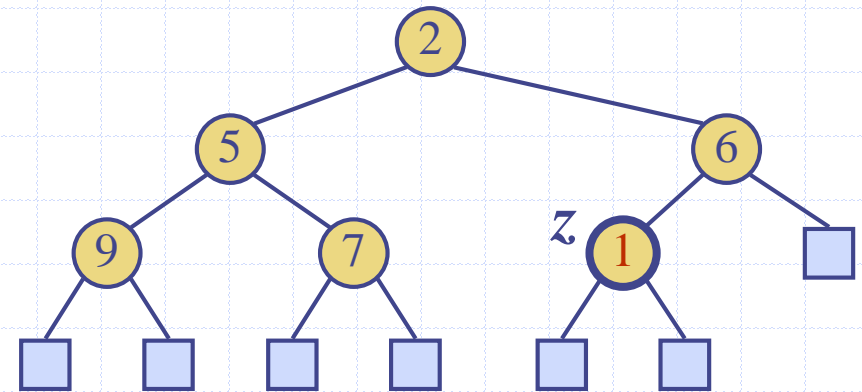
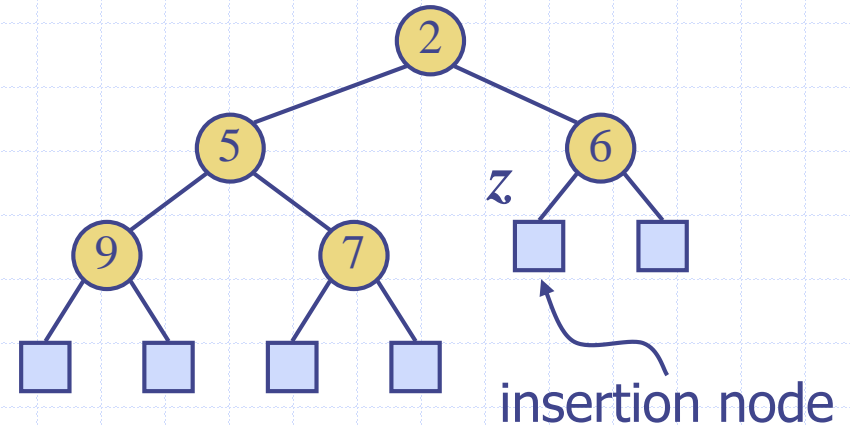
- ◆ We can use a heap to implement a priority queue
- ◆ We store a (key, element) item at each internal node
- ◆ We keep track of the position of the last node
- ◆ For simplicity, we show only the keys in the pictures



# Insertion into a Heap (§2.4.3)

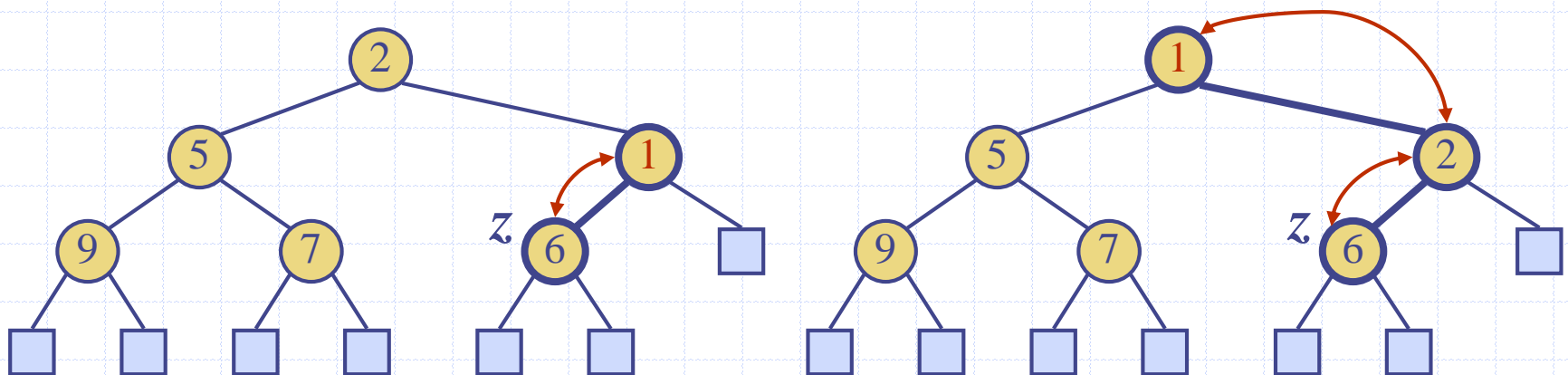


- ◆ Method `insertItem` of the priority queue ADT corresponds to the insertion of a key  $k$  to the heap
- ◆ The insertion algorithm consists of three steps
  - Find the insertion node  $z$  (the new last node)
  - Store  $k$  at  $z$  and expand  $z$  into an internal node
  - Restore the heap-order property (discussed next)



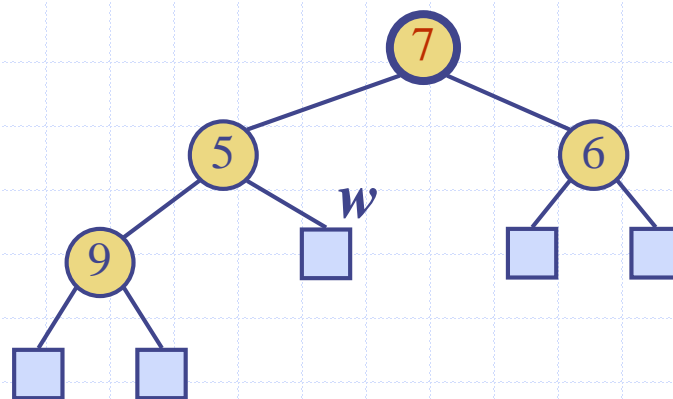
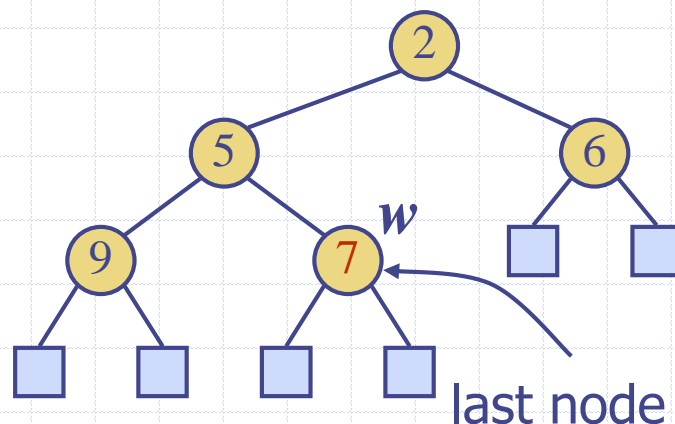
# Upheap

- ◆ After the insertion of a new key  $k$ , the heap-order property may be violated
- ◆ Algorithm upheap restores the heap-order property by swapping  $k$  along an upward path from the insertion node
- ◆ Upheap terminates when the key  $k$  reaches the root or a node whose parent has a key smaller than or equal to  $k$
- ◆ Since a heap has height  $O(\log n)$ , upheap runs in  $O(\log n)$  time



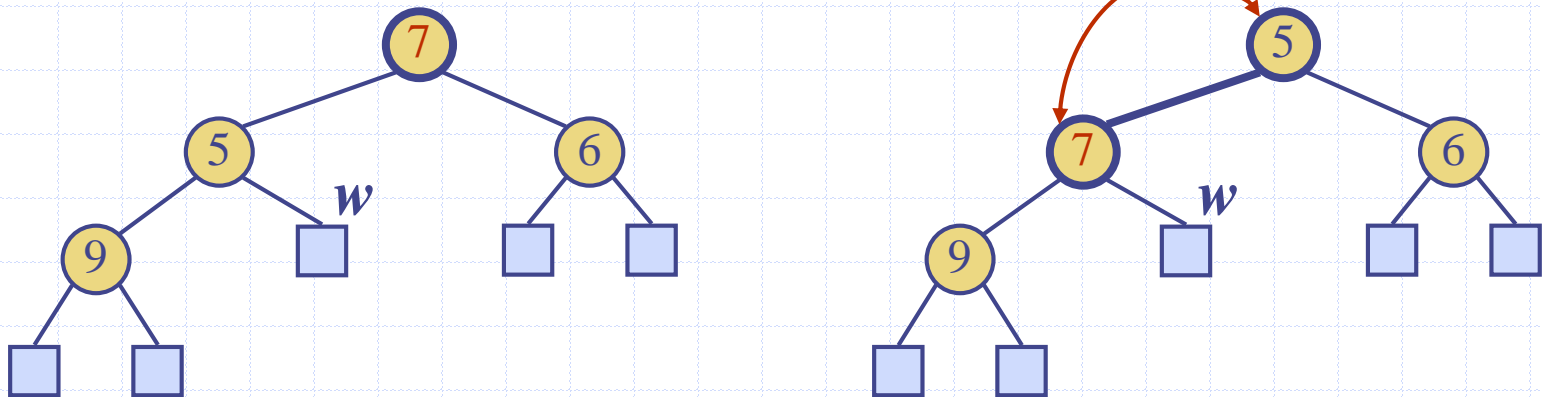
# Removal from a Heap (§2.4.3)

- ◆ Method `removeMin` of the priority queue ADT corresponds to the removal of the root key from the heap
- ◆ The removal algorithm consists of three steps
  - Replace the root key with the key of the last node  $w$
  - Compress  $w$  and its children into a leaf
  - Restore the heap-order property (discussed next)



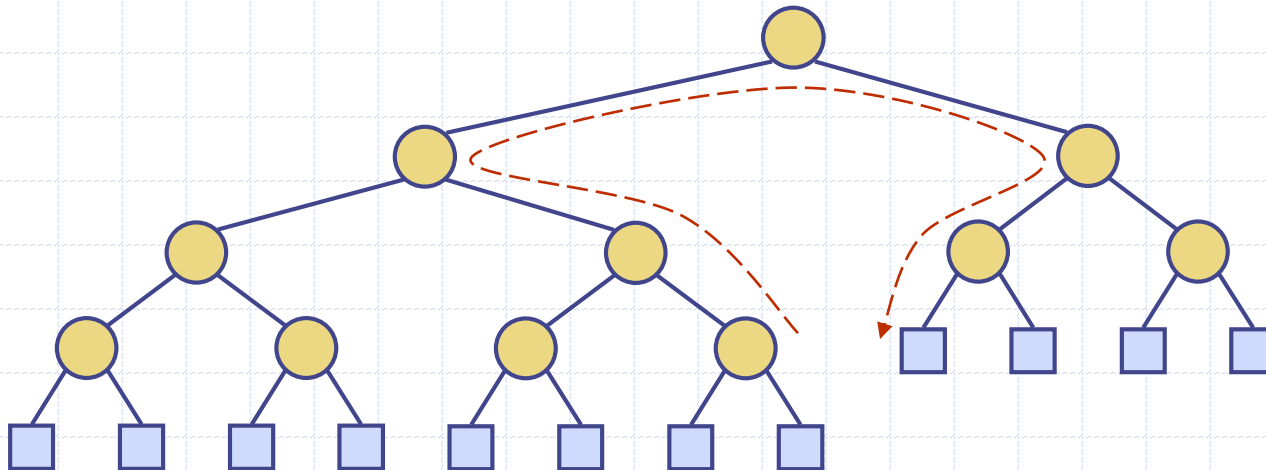
# Downheap

- ◆ After replacing the root key with the key  $k$  of the last node, the heap-order property may be violated
- ◆ Algorithm downheap restores the heap-order property by swapping key  $k$  along a downward path from the root
- ◆ Upheap terminates when key  $k$  reaches a leaf or a node whose children have keys greater than or equal to  $k$
- ◆ Since a heap has height  $O(\log n)$ , downheap runs in  $O(\log n)$  time



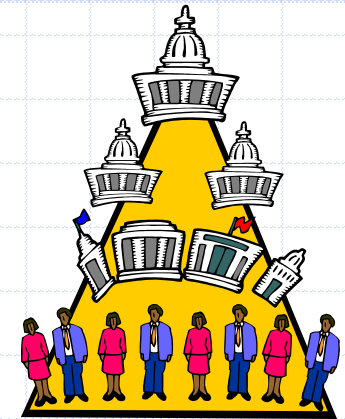
# Updating the Last Node

- ◆ The insertion node can be found by traversing a path of  $O(\log n)$  nodes
  - While the current node is a right child, go to the parent node
  - If the current node is a left child, go to the right child
  - While the current node is internal, go to the left child
- ◆ Similar algorithm for updating the last node after a removal





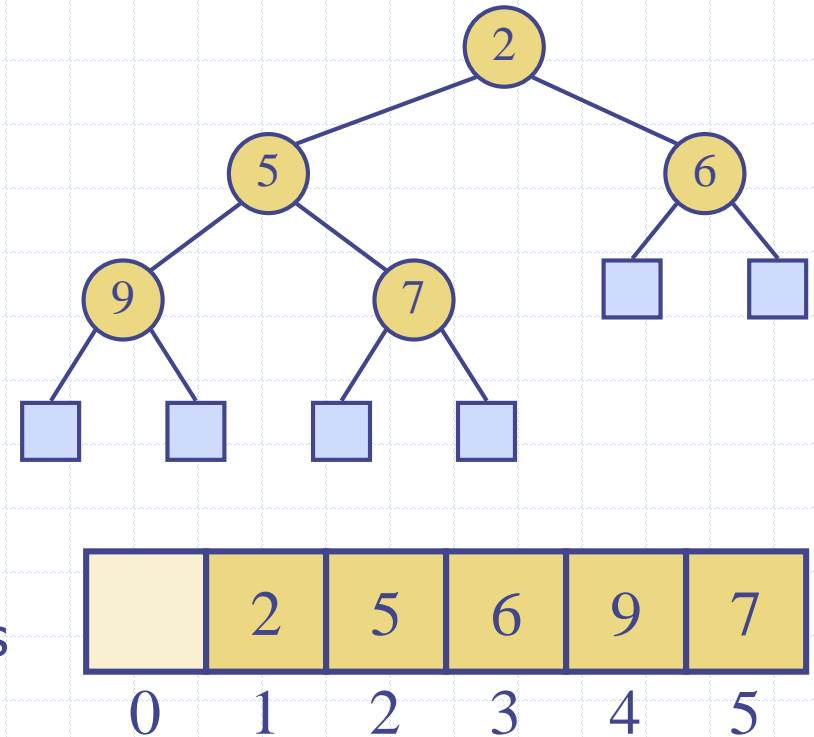
# Heap-Sort (§2.4.4)



- ◆ Consider a priority queue with  $n$  items implemented by means of a heap
  - the space used is  $O(n)$
  - methods **insertItem** and **removeMin** take  $O(\log n)$  time
  - methods **size**, **isEmpty**, **minKey**, and **minElement** take time  $O(1)$  time
- ◆ Using a heap-based priority queue, we can sort a sequence of  $n$  elements in  $O(n \log n)$  time
- ◆ The resulting algorithm is called heap-sort
- ◆ Heap-sort is much faster than quadratic sorting algorithms, such as insertion-sort and selection-sort

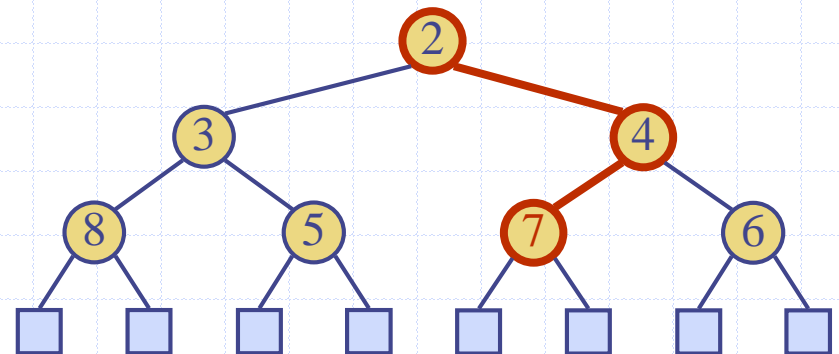
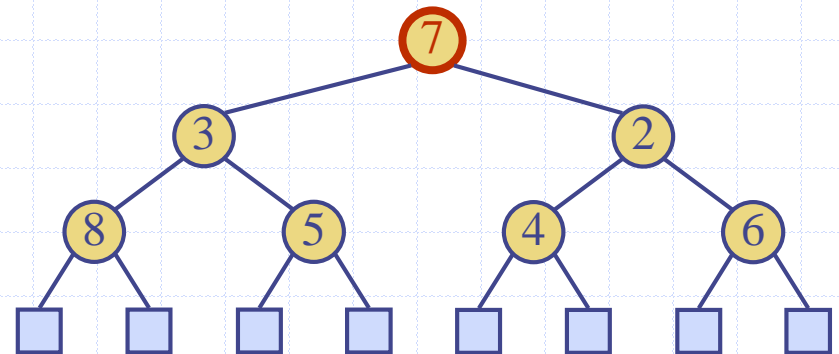
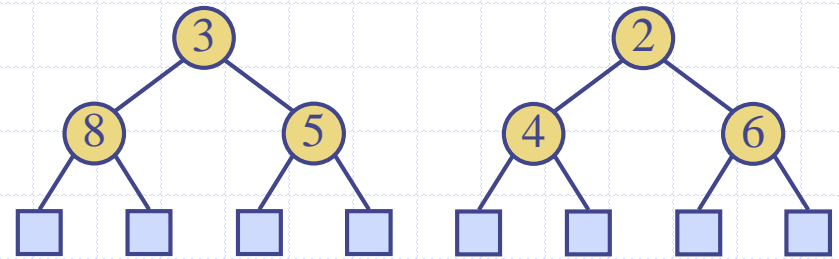
# Vector-based Heap Implementation (§2.4.3)

- ◆ We can represent a heap with  $n$  keys by means of a vector of length  $n + 1$
- ◆ For the node at rank  $i$ 
  - the left child is at rank  $2i$
  - the right child is at rank  $2i + 1$
- ◆ Links between nodes are not explicitly stored
- ◆ The leaves are not represented
- ◆ The cell at rank 0 is not used
- ◆ Operation `insertItem` corresponds to inserting at rank  $n + 1$
- ◆ Operation `removeMin` corresponds to removing at rank  $n$
- ◆ Yields in-place heap-sort



# Merging Two Heaps

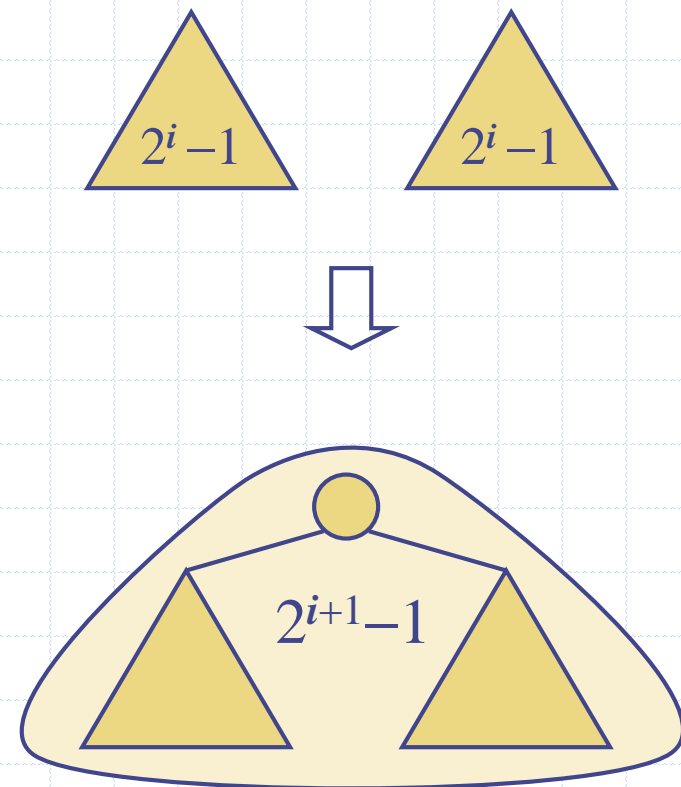
- ◆ We are given two two heaps and a key  $k$
- ◆ We create a new heap with the root node storing  $k$  and with the two heaps as subtrees
- ◆ We perform downheap to restore the heap-order property



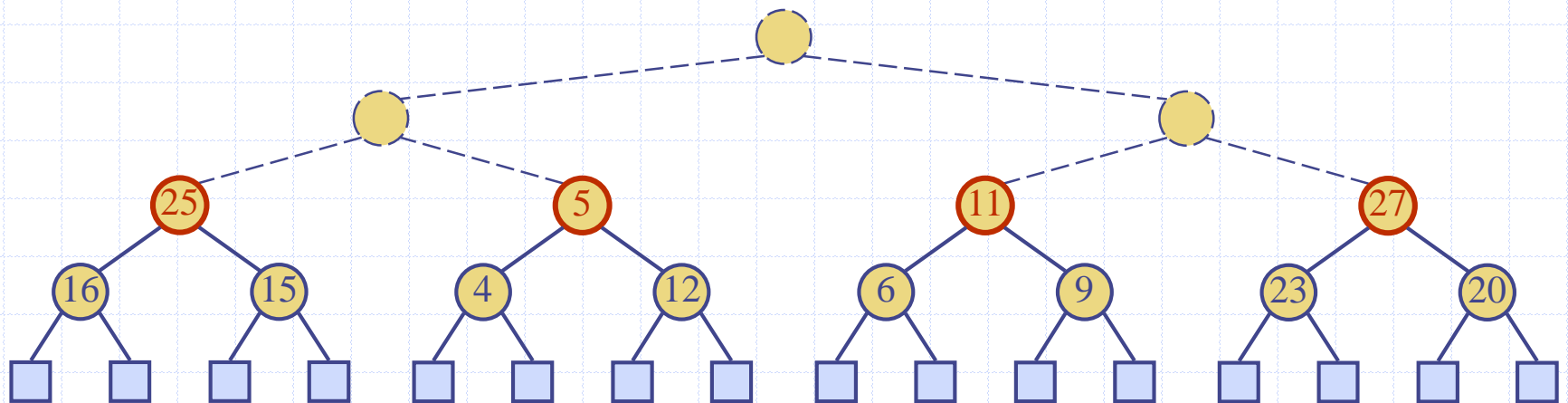
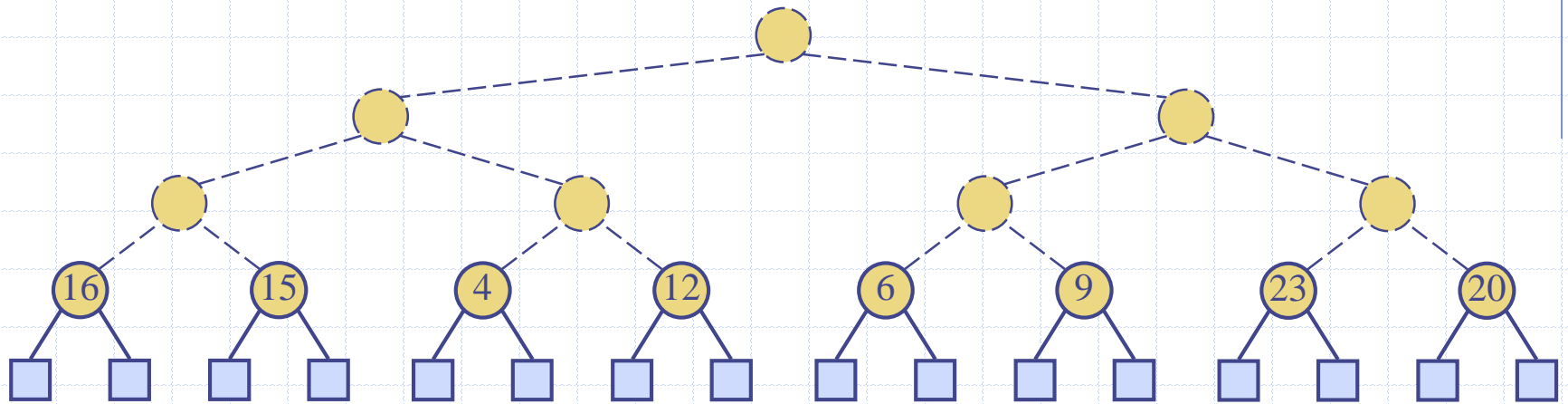
# Bottom-up Heap Construction (§2.4.3)



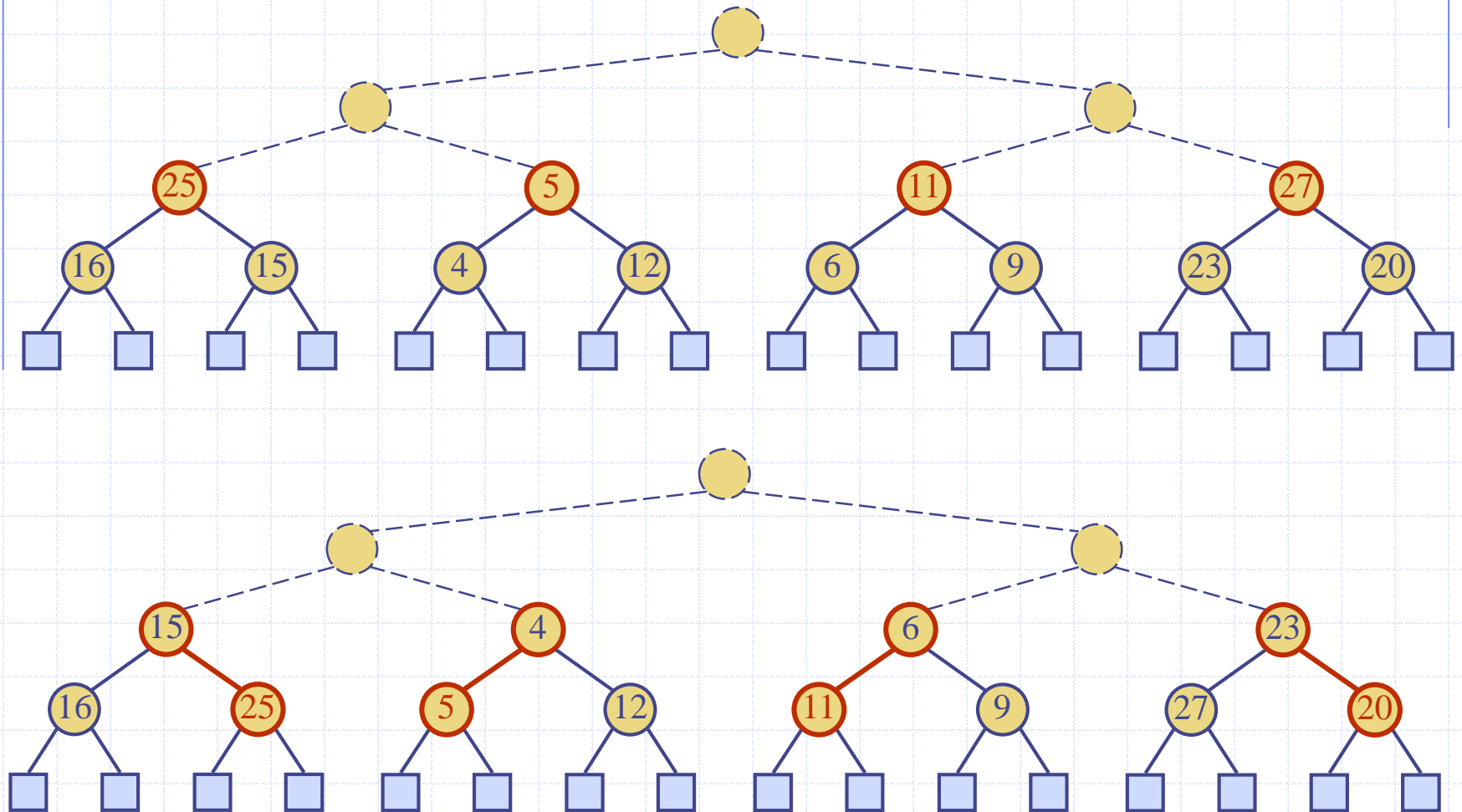
- ◆ We can construct a heap storing  $n$  given keys in using a bottom-up construction with  $\log n$  phases
- ◆ In phase  $i$ , pairs of heaps with  $2^i - 1$  keys are merged into heaps with  $2^{i+1} - 1$  keys



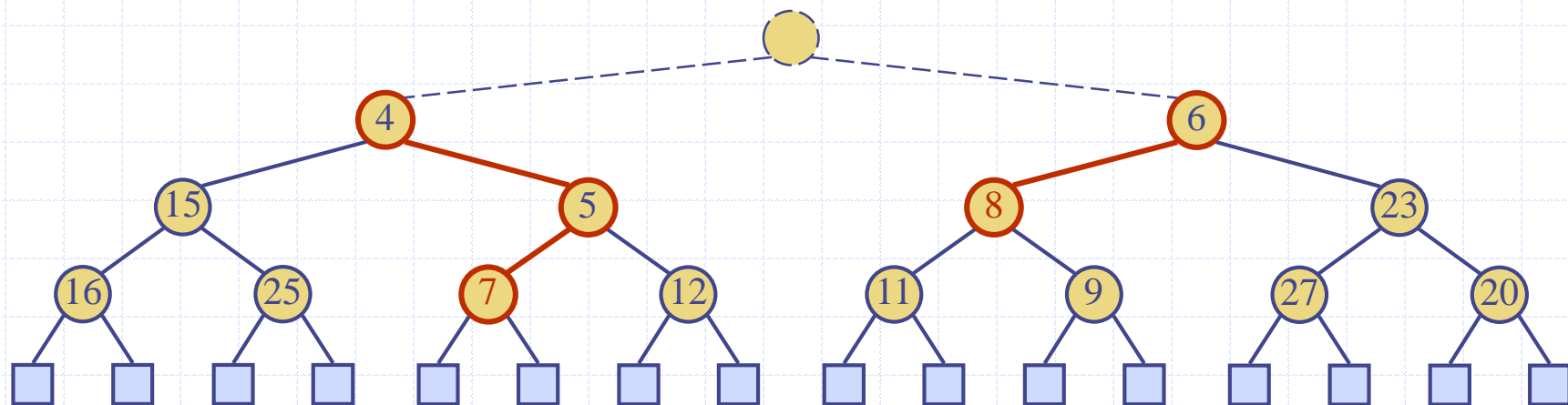
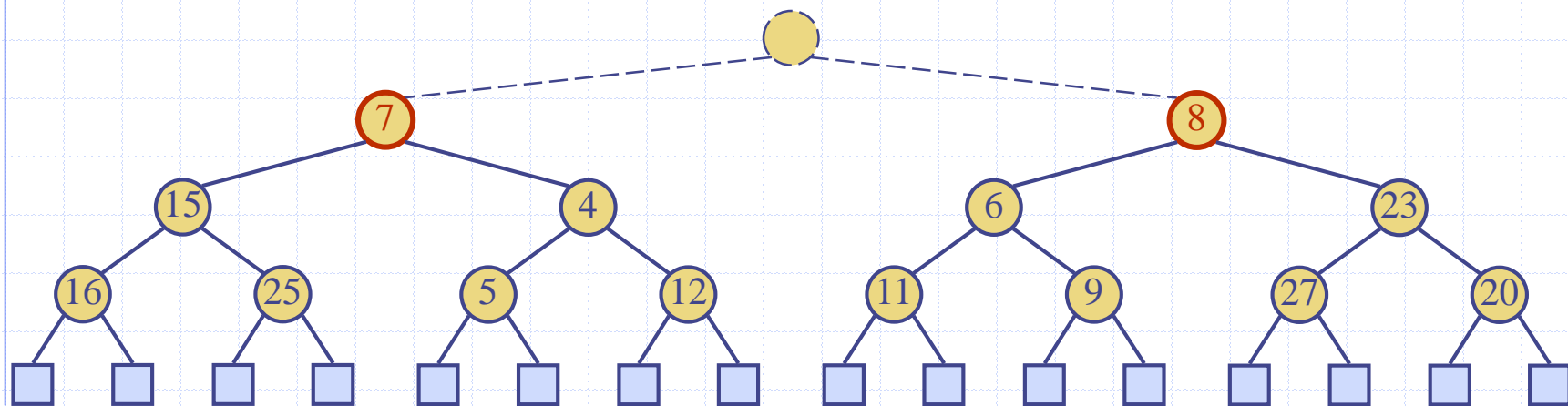
# Example



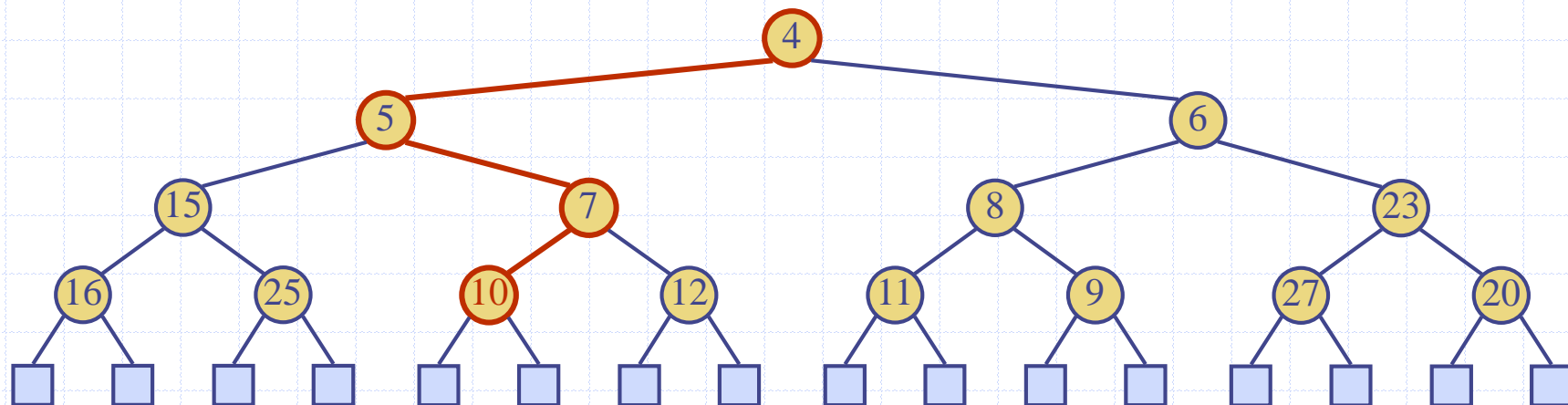
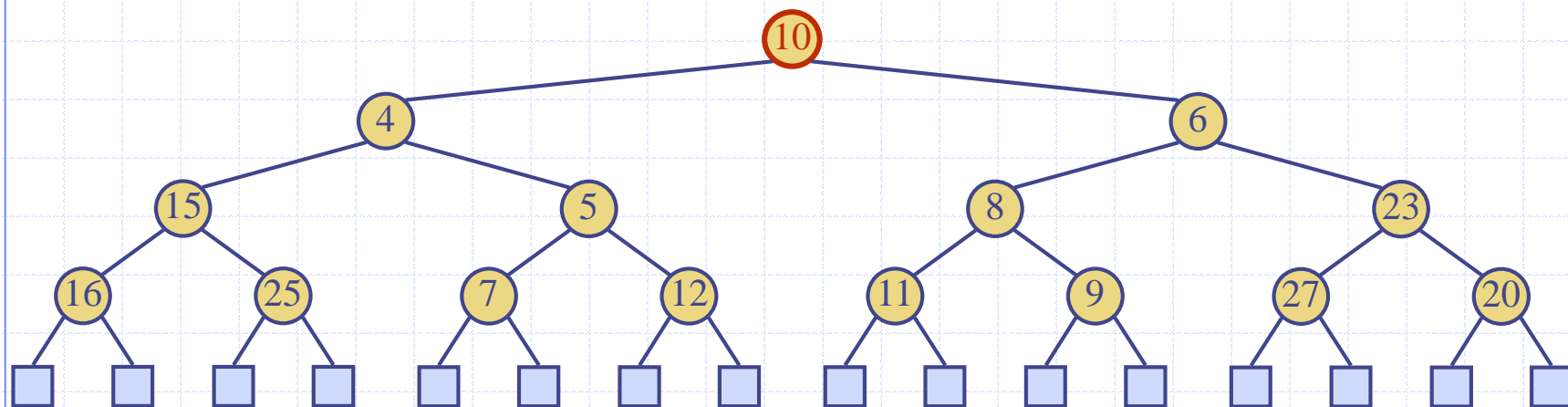
# Example (contd.)



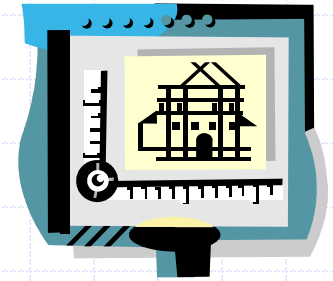
# Example (contd.)



# Example (end)







# Analysis

- ◆ We visualize the worst-case time of a downheap with a proxy path that goes first right and then repeatedly goes left until the bottom of the heap (this path may differ from the actual downheap path)
- ◆ Since each node is traversed by at most two proxy paths, the total number of nodes of the proxy paths is  $O(n)$
- ◆ Thus, bottom-up heap construction runs in  $O(n)$  time
- ◆ Bottom-up heap construction is faster than  $n$  successive insertions and speeds up the first phase of heap-sort

