

# Collective Tree Spanners of Graphs with Bounded Parameters

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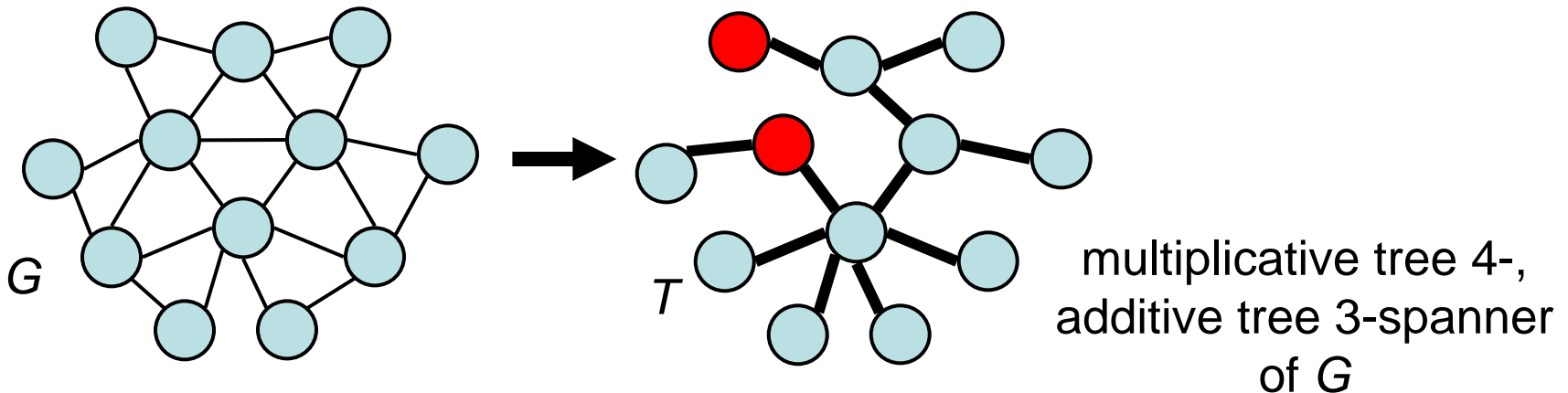
# Well-known Tree $t$ -Spanner Problem

Given unweighted undirected graph  $G=(V,E)$  and integers  $t,r$ .  
Does  $G$  admit a spanning tree  $T=(V,E')$  such that

$\forall u,v \in V, \text{dist}_T(v,u) \leq t \times \text{dist}_G(v,u)$  (a *multiplicative tree  $t$ -spanner* of  $G$ )

or

$\forall u,v \in V, \text{dist}_T(u,v) - \text{dist}_G(u,v) \leq r$  (an *additive tree  $r$ -spanner* of  $G$ )?



# Some known results for the tree spanner problem

(mostly multiplicative case)

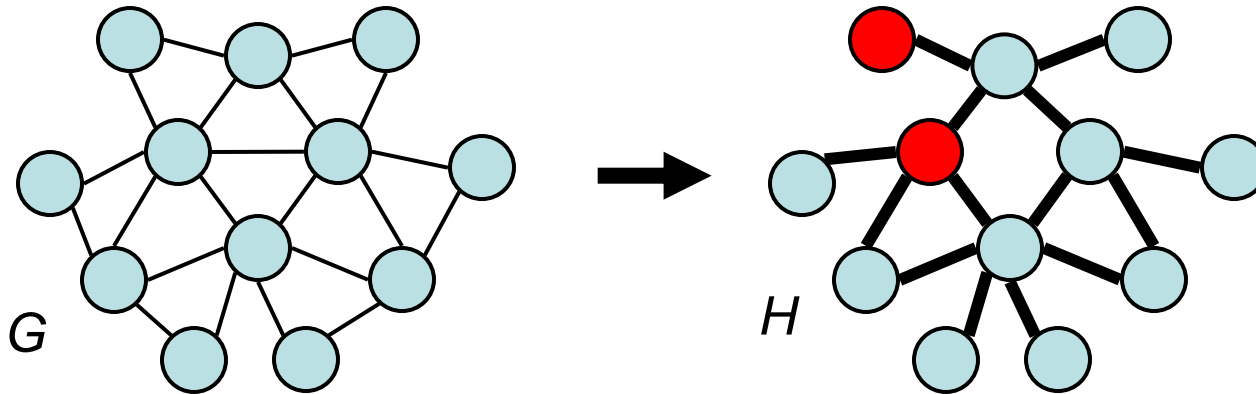
- general graphs [CC'95]
  - $t \geq 4$  is NP-complete. ( $t=3$  is still open,  $t \leq 2$  is P)
- approximation algorithm for general graphs [EP'04]
  - $O(\log n)$  approximation algorithm
- chordal graphs [BDLL'02]
  - $t \geq 4$  is NP-complete. ( $t=3$  is still open.)
- planar graphs [FK'01]
  - $t \geq 4$  is NP-complete. ( $t=3$  is polynomial time solvable.)
- easy to construct for some special families of graphs.

# Well-known Sparse $t$ -Spanner Problem

Given unweighted undirected graph  $G=(V,E)$  and integers  $t,m,r$ .  
Does  $G$  admit a spanning graph  $H=(V,E')$  with  $|E'| \leq m$  s.t.

$\forall u,v \in V, \text{dist}_H(v,u) \leq t \times \text{dist}_G(v,u)$  (a *multiplicative  $t$ -spanner* of  $G$ )  
**or**

$\forall u,v \in V, \text{dist}_H(u,v) - \text{dist}_G(u,v) \leq r$  (an *additive  $r$ -spanner* of  $G$ )?



multiplicative 2- and additive 1-spanner of  $G$

# Some known results for sparse spanner problems

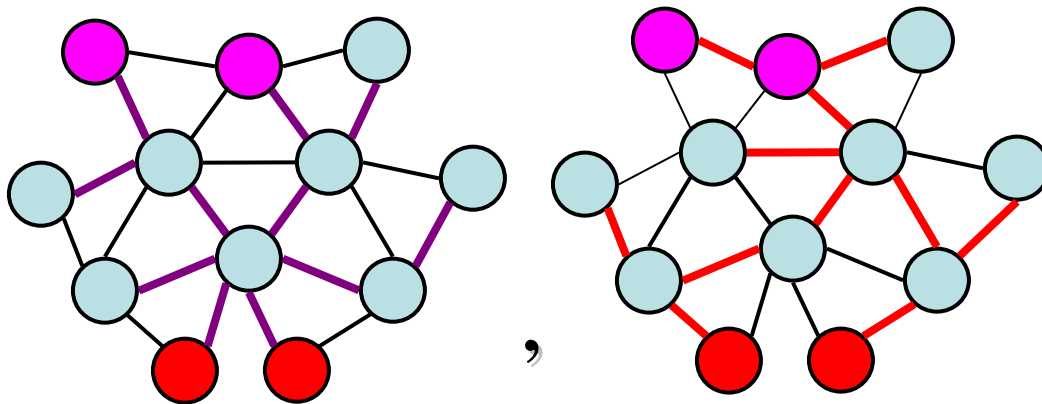
- general graphs
  - $t, m \geq 1$  is NP-complete [PS'89]
  - multiplicative  $(2k-1)$ -spanner with  $n^{1+1/k}$  edges [TZ'01, BS'03]
- $n$ -vertex chordal graphs (multiplicative case) [PS'89]  
( $G$  is chordal if it has no chordless cycles of length  $>3$ )
  - multiplicative 3-spanner with  $O(n \log n)$  edges
  - multiplicative 5-spanner with  $2n-2$  edges
- $n$ -vertex  $c$ -chordal graphs (additive case) [CDY'03, DYL'04]  
( $G$  is  $c$ -chordal if it has no chordless cycles of length  $>c$ )
  - additive  $(c+1)$ -spanner with  $2n-2$  edges
  - additive  $(2 \lfloor c/2 \rfloor)$ -spanner with  $n \log n$  edges
  - ➔ For chordal graphs: additive 4-spanner with  $2n-2$  edges, additive 2-spanner with  $n \log n$  edges

# New **Collective Additive Tree $r$ -Spanners Problem**

Given unweighted undirected graph  $G=(V,E)$  and integers  $\mu, r$ .  
 Does  $G$  admit a system of  $\mu$  collective additive tree  $r$ -spanners  
 $\{T_1, T_2, \dots, T_\mu\}$  such that

$$\forall u, v \in V \text{ and } \exists 0 \leq i \leq \mu, \text{dist}_{T_i}(v, u) - \text{dist}_G(v, u) \leq r$$

(a system of  $\mu$  collective additive tree  $r$ -spanners of  $G$ )?



**2 collective additive tree 2-spanners**

↑  
**surplus**

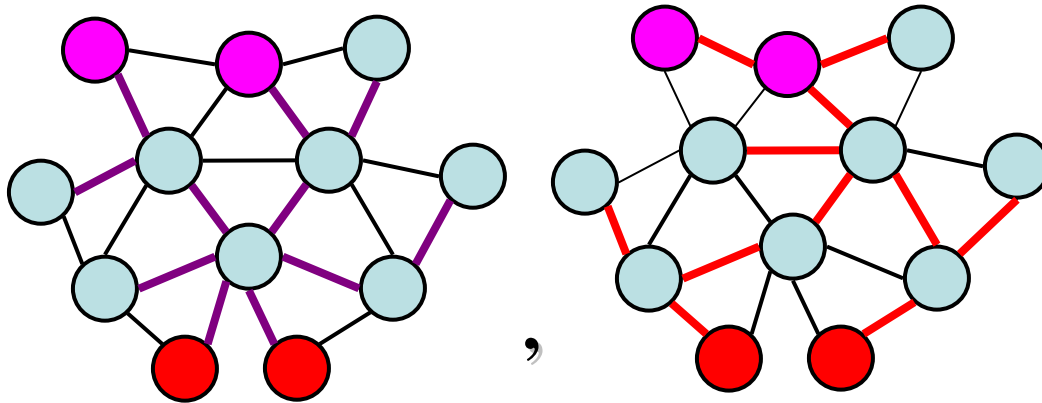
collective multiplicative  
 tree  $t$ -spanners  
 can be defined similarly

# New Collective Additive Tree $r$ -Spanners Problem

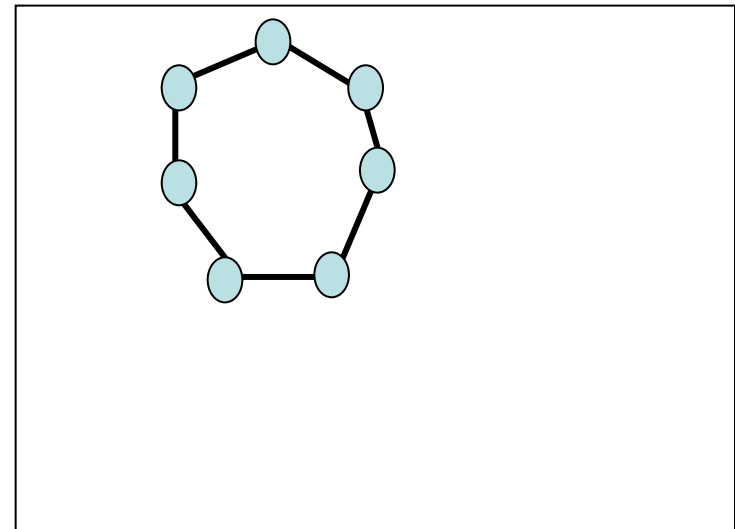
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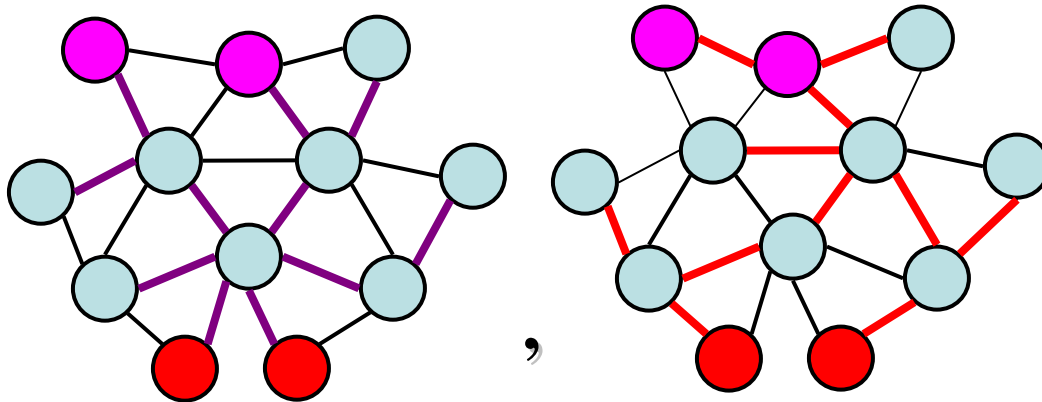


# New Collective Additive Tree $r$ -Spanners Problem

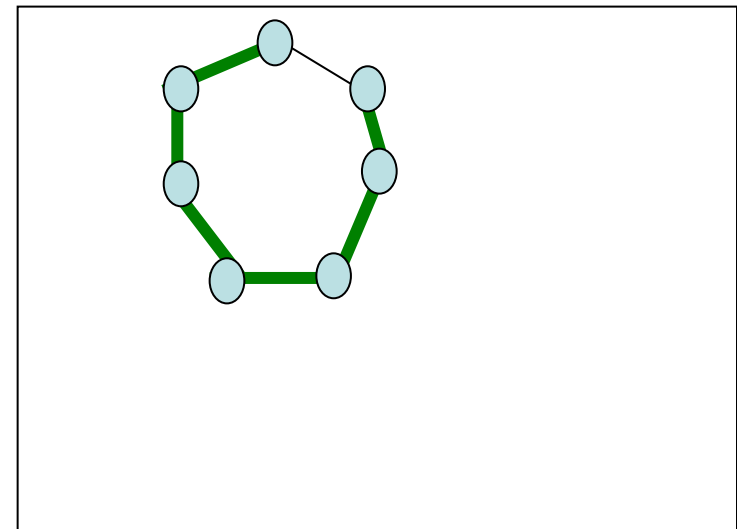
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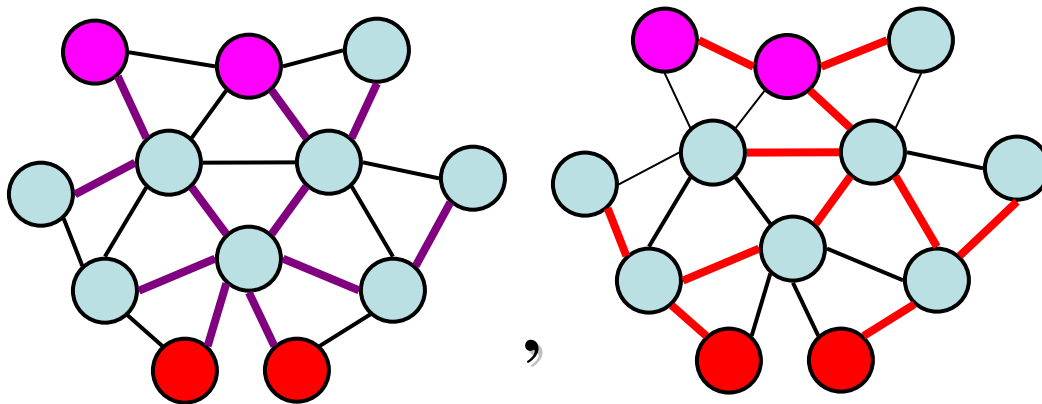


# New **Collective Additive Tree $r$ -Spanners Problem**

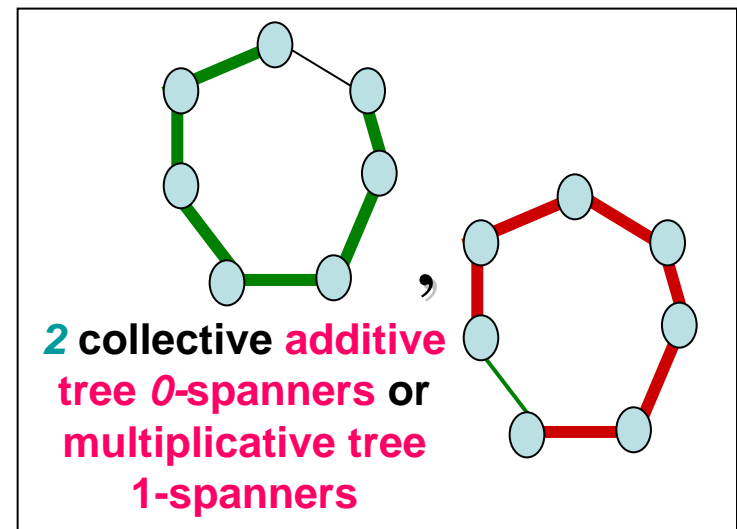
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(a system of  $\mu$  collective *additive tree  $r$ -spanners* of  $G$  )?



**2 collective additive tree 2-spanners**



**2 collective additive tree 0-spanners or multiplicative tree 1-spanners**

# Applications of Collective Tree Spanners

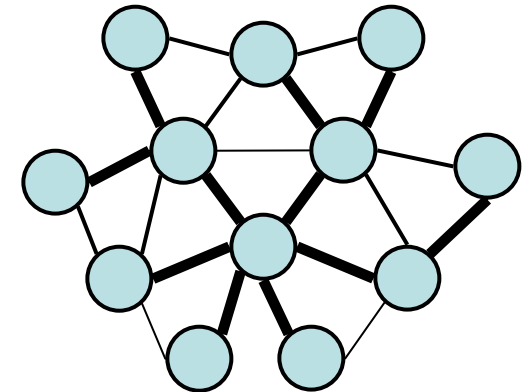
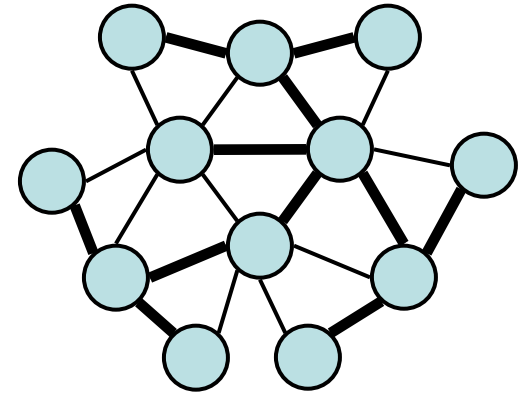
- **message routing in networks**

Efficient routing schemes are known for **trees** but not for general **graphs**. For **any two nodes**, we can route the message between them in **one of the trees** which approximates the distance between them.

- $(\mu \log^2 n / \log \log n)$ -bit labels,
- $O(\mu)$  initiation,  $O(1)$  decision

- **solution for sparse  $t$ -spanner problem**

If a graph admits a system of  $\mu$  **collective additive tree  $r$ -spanners**, then the graph admits a **sparse additive  $r$ -spanner** with at most  $\mu(n-1)$  edges, where  $n$  is the number of nodes.



**2 collective tree 2-spanners for  $G$**

# Previous results on the collective tree spanners problem

(Dragan, Yan, Lomonosov [SWAT'04])

(Corneil, Dragan, Köhler, Yan [WG'05])

- chordal graphs, chordal bipartite graphs
  - $\log n$  collective additive tree 2-spanners in polynomial time
  - $\Omega(n^{1/2})$  or  $\Omega(n)$  trees necessary to get +1
  - no constant number of trees guarantees +2 (+3)
- circular-arc graphs
  - 2 collective additive tree 2-spanners in polynomial time
- $c$ -chordal graphs
  - $\log n$  collective additive tree  $2 \lfloor c/2 \rfloor$ -spanners in polynomial time
- interval graphs
  - $\log n$  collective additive tree 1-spanners in polynomial time
  - no constant number of trees guarantees +1

# Previous results on the collective tree spanners problem

(Dragan, Yan, Corneil [WG'04])

- AT-free graphs
  - include: interval, permutation, trapezoid, co-comparability
  - 2 collective additive tree 2-spanners in linear time
  - an additive tree 3-spanner in linear time (before)
- graphs with a dominating shortest path
  - an additive tree 4-spanner in polynomial time (before)
  - 2 collective additive tree 3-spanners in polynomial time
  - 5 collective additive tree 2-spanners in polynomial time
- graphs with asteroidal number  $an(G)=k$ 
  - $k(k-1)/2$  collective additive tree 4-spanners in polynomial time
  - $k(k-1)$  collective additive tree 3-spanners in polynomial time

# Previous results on the collective tree spanners problem

(Gupta, Kumar, Rastogi [SICOMP'05])

- the only paper (before) on collective **multiplicative** tree spanners in **weighted planar graphs**
- any **weighted planar graph** admits a system of  $O(\log n)$  collective **multiplicative tree 3-spanners**
- they are called there the **tree-covers**.
- it follows from (Corneil, Dragan, Köhler, Yan [WG'05]) that
  - **no constant number** of trees guaranties **+c** (for any constant **c**)

# New results on collective **additive** tree spanners of **weighted** graphs with **bounded** parameters

Graph class	$\mu$	$r$
<b>planar</b>	$O(\sqrt{n})$	$0$
<b>with genus <math>g</math></b>	$O(\sqrt{gn})$	$0$
<b>W/o an <math>h</math>-vertex minor</b>	$O(\sqrt{h^3 n})$	$0$
$tw(G) \leq k-1$	$k \log_2 n$	$0$
$cw(G) \leq k$	$k \log_{3/2} n$	$2w$
<b><math>c</math>-chordal</b>	<i>next</i>	<i>slide</i>

$\Omega(\sqrt{n} \log \log n / \log^2 n)$  to get +0  
 $\Omega(n)$  to get +1

No constant number of trees guaranties  $+r$  for any constant  $r$  even for outer-planar graphs

- $w$  is the length of a longest edge in  $G$

# New results on collective additive tree spanners of weighted $c$ -chordal graphs

Graph class	$\mu$	$r$
<b><i>c</i>-chordal</b> ( $c > 4$ )	$\log_2 n$	$2 \left\lfloor \frac{c}{2} \right\rfloor w$
	$4 \log_2 n$	$2 \left( \left\lfloor \frac{c}{3} \right\rfloor + 1 \right) w$
	$5 \log_2 n$	$2 \left\lfloor \frac{c+2}{3} \right\rfloor w$
<b><i>4</i>-chordal</b>	$6 \log_2 n$	$2w$
<b><i>weakly chordal</i></b>	$4 \log_2 n$	$2w$

No constant number of trees guaranties  $+r$  for any constant  $r$  even for weakly chordal graphs

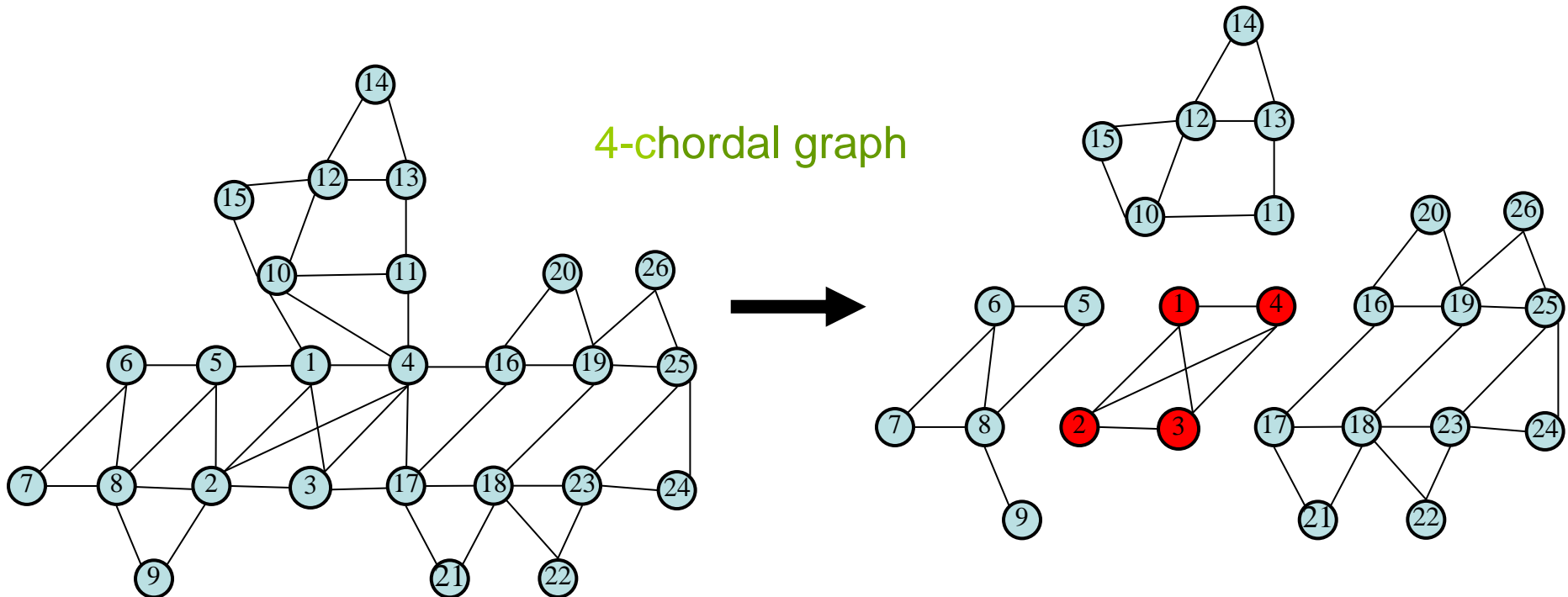
# $(\alpha, \gamma, r)$ -Decomposable Graphs

- A graph  $G=(V, E)$  is  $(\alpha, \gamma, r)$ -decomposable if there exists a vertex-separator  $S$  in  $G$  such that

Balanced separator: each conn. comp. of  $G-S$  has  $\leq \alpha n$  vertices;

Bounded  $r$ -dominating set:  $S$  has an  $r$ -dominating set  $D$  in  $G$  with  $|D| \leq \gamma$ ;

Hereditary family: any induced subgraph of  $G$  is  $(\alpha, \gamma, r)$ -decomposable.





# Main Results of the Paper

**Theorem:** Any  $(\alpha, \gamma, r)$ -decomposable graph admits a system of at most  $\gamma \log_{1/\alpha} n$  collective additive tree  $2r$ -spanners.

Graph class	decomposition
planar	$(2/3, \sqrt{6n}, 0)$
with genus $g$	$(2/3, O(\sqrt{gn}), 0)$
W/o an $h$ -vertex minor	$(2/3, O(\sqrt{h^3 n}), 0)$
$tw(G) \leq k-1$	$(1/2, k, 0)$
$cw(G) \leq k$	$(2/3, k, w)$
$c$ -chordal	$(1/2, 1, \lfloor c/2 \rfloor w),$ $(1/2, 5, \lfloor (c+2)/3 \rfloor w),$ $(1/2, 4, (\lfloor c/3 \rfloor + 1)w)$

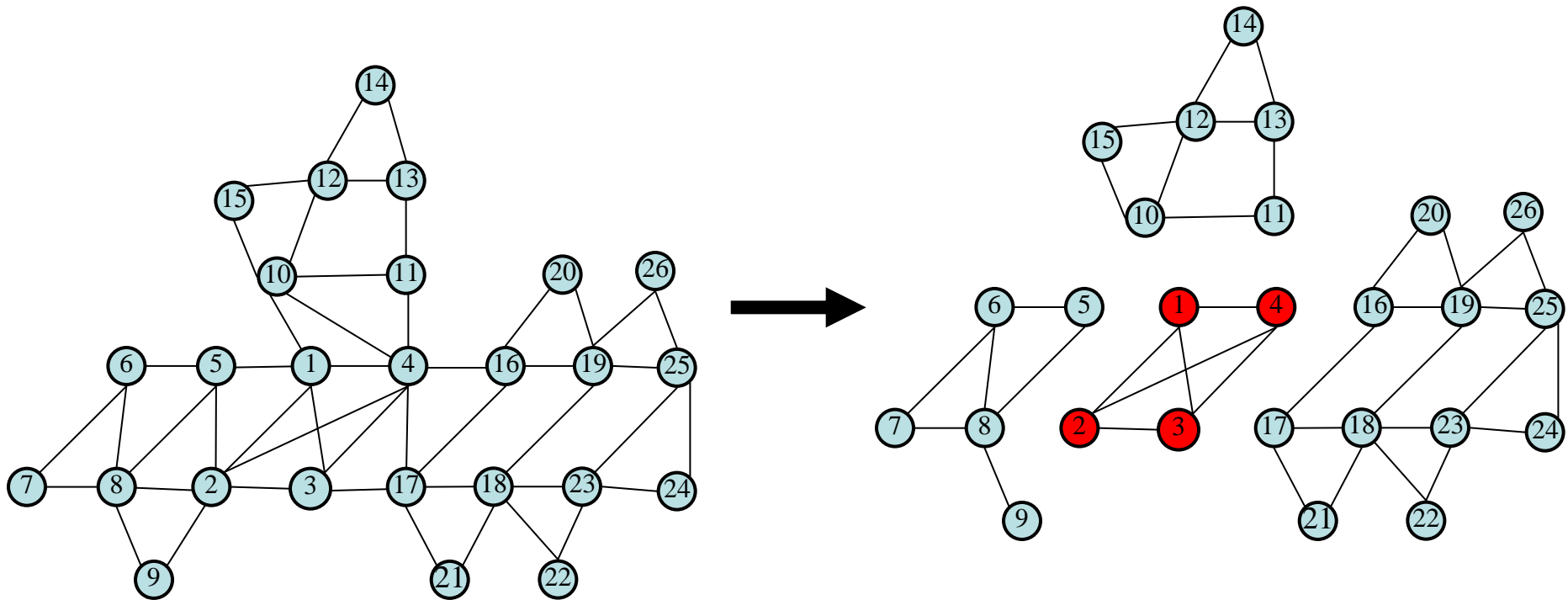
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Polynomial  
time  
constructions

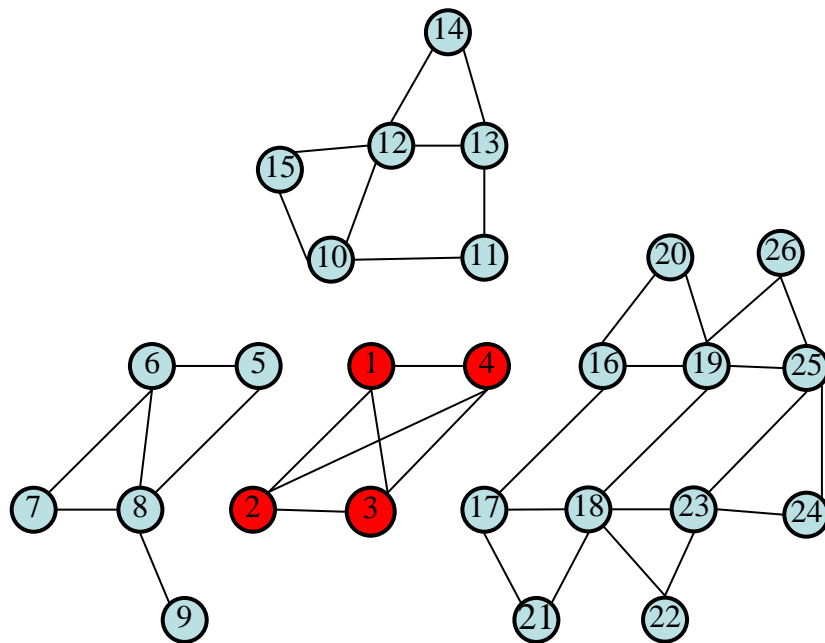
# Constructing a Rooted Balanced Decomposition Tree for an $(\alpha, \gamma, r)$ -Decomposable Graph

- Find a good *balanced separator*  $S$  of  $G$ .



# Constructing a Rooted Balanced Decomposition Tree for an $(\alpha, \gamma, r)$ -Decomposable Graph

- Use  $S$  as the *root* of the *rooted balanced decomposition tree*.

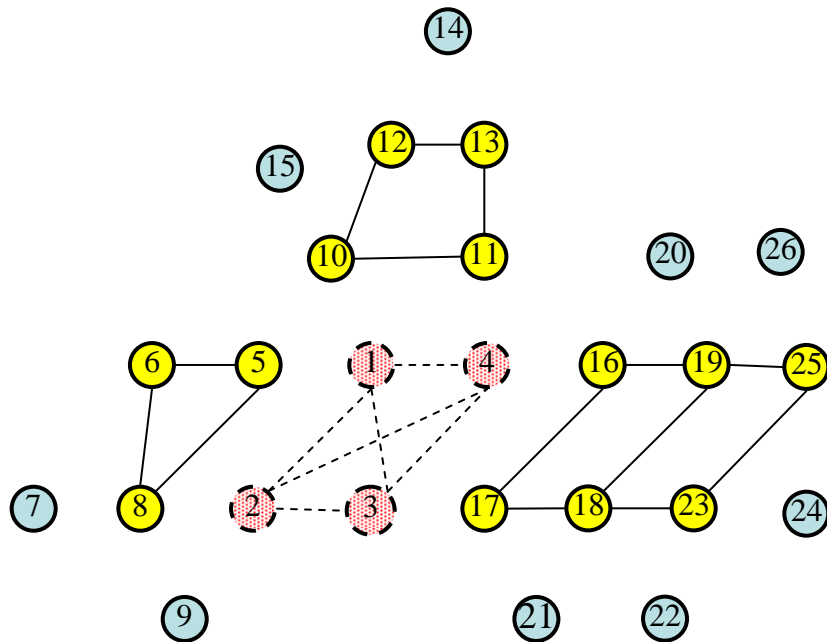


1, 2, 3, 4

# Constructing a Rooted Balanced Decomposition Tree for an $(\alpha, \gamma, r)$ -Decomposable Graph

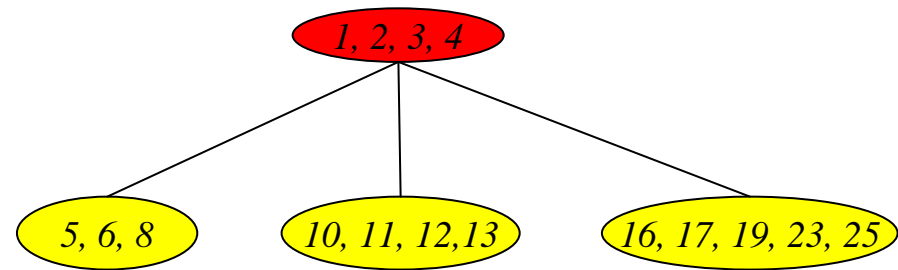
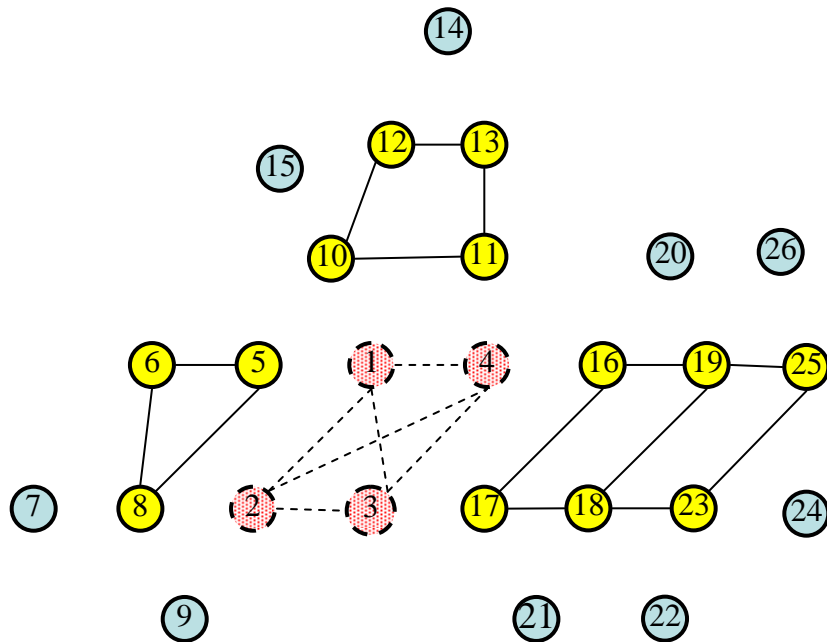
- For each connected component of  $G-S$ , find its good *balanced separator*.

1, 2, 3, 4



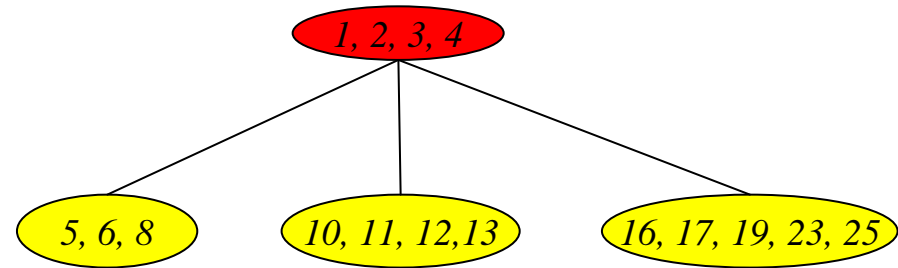
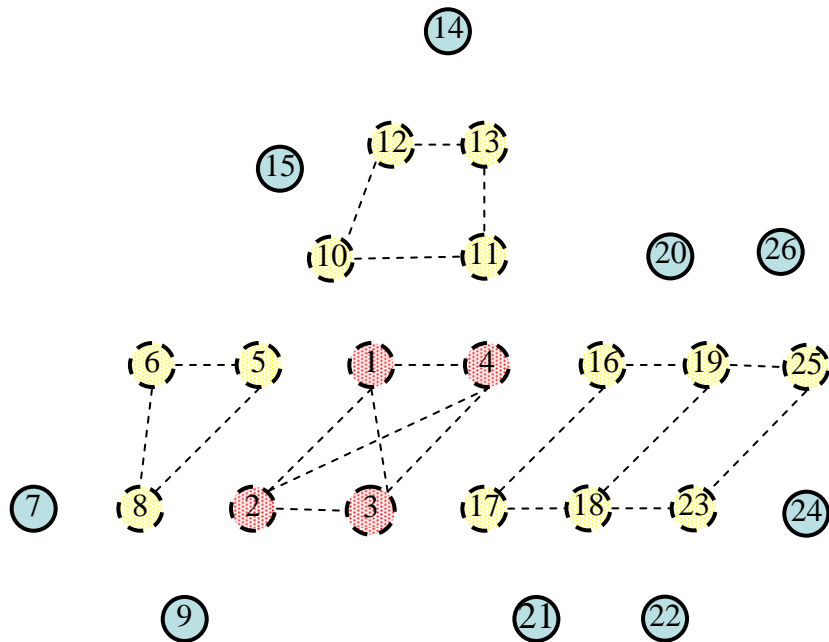
# Constructing a Rooted Balanced Decomposition Tree for an $(\alpha, \gamma, r)$ -Decomposable Graph

- Use the separators as nodes of the *rooted balanced decomposition tree* and let  $S$  be their father.



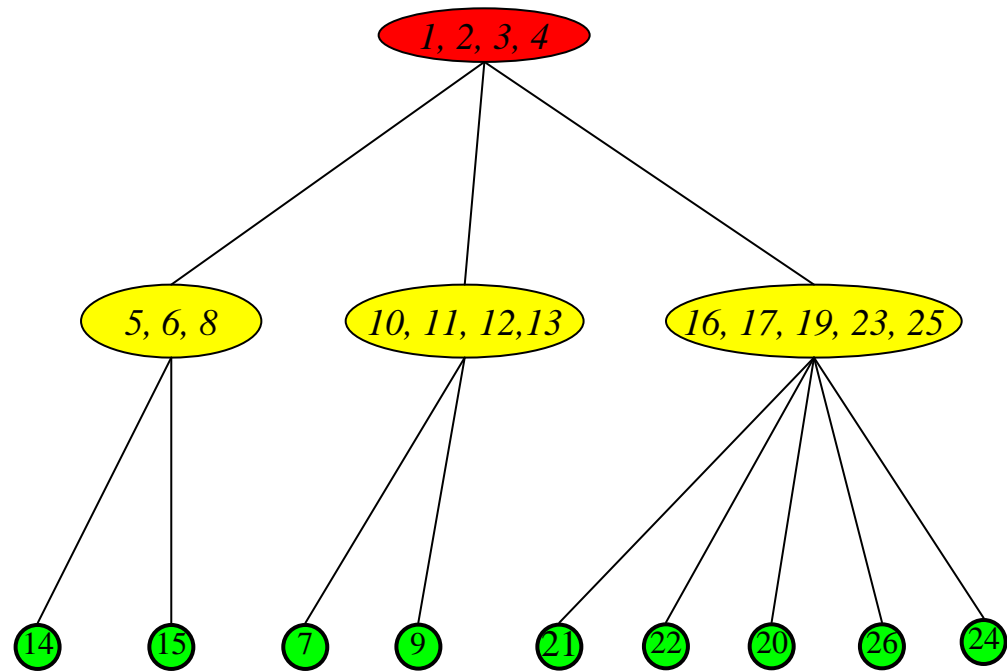
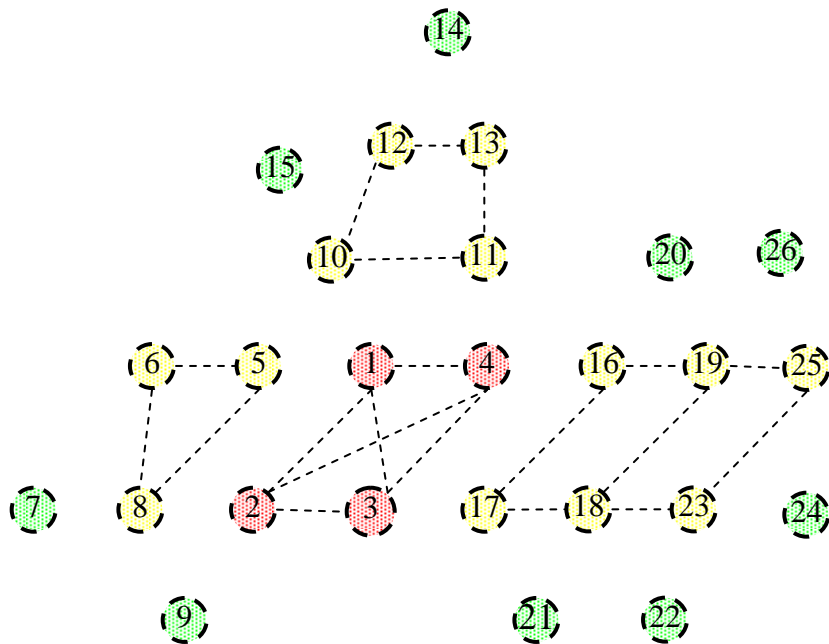
# Constructing a Rooted Balanced Decomposition Tree for an $(\alpha, \gamma, r)$ -Decomposable Graph

- **Recursively repeat** previous procedure until each connected component has an  $r$ -dominating set of size at most  $\gamma$ .

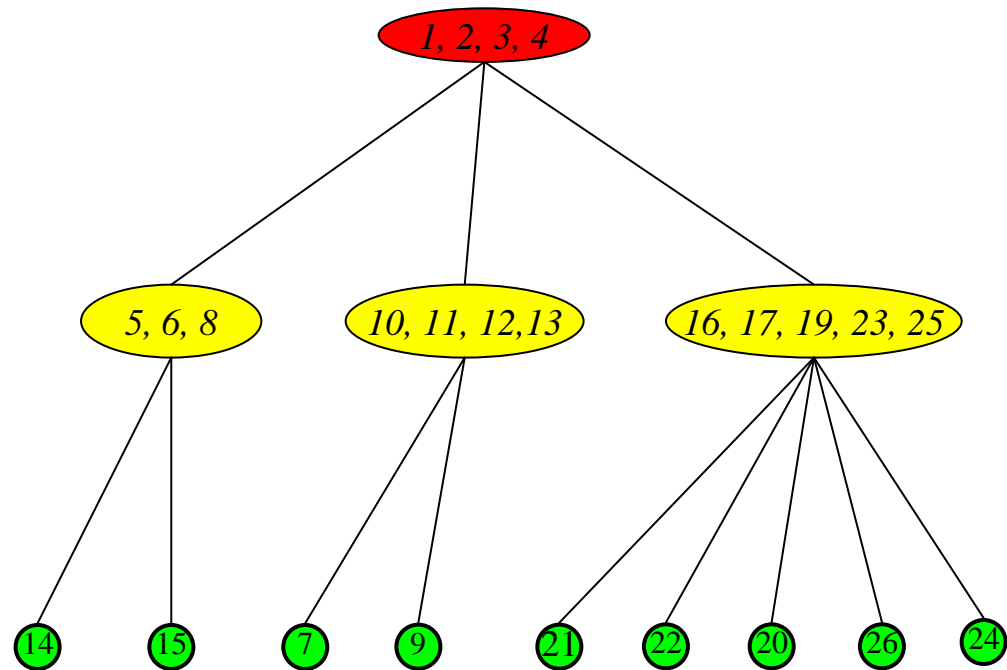
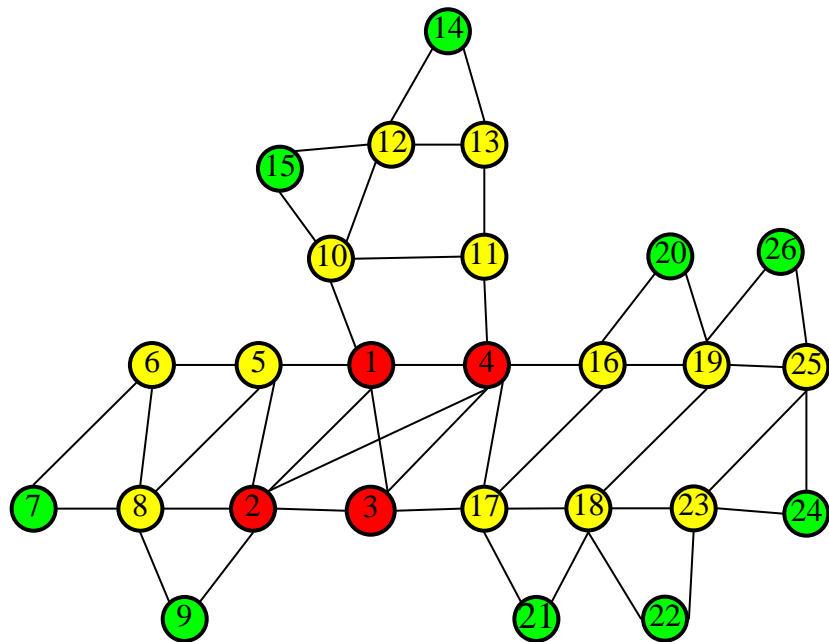


# Constructing a Rooted Balanced Decomposition Tree for an $(\alpha, \gamma, r)$ -Decomposable Graph

- Get the *rooted balanced decomposition tree*.



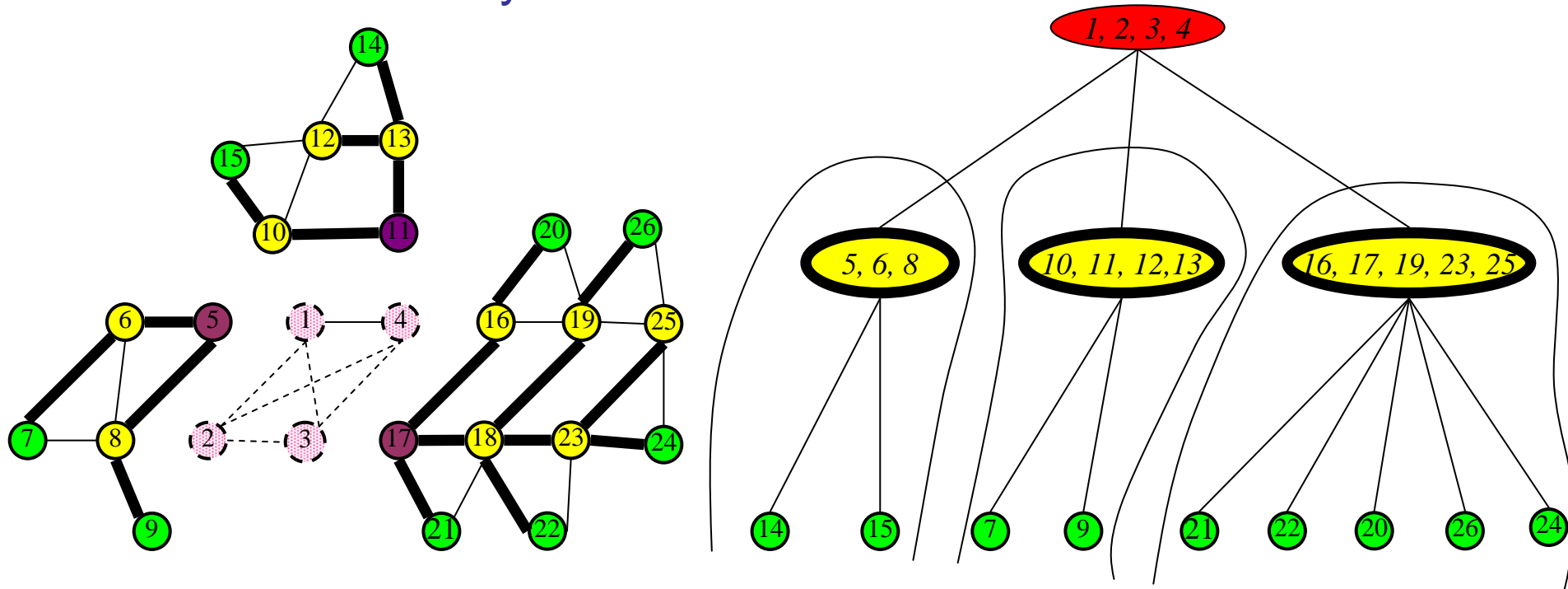
# Rooted Balanced Decomposition Tree





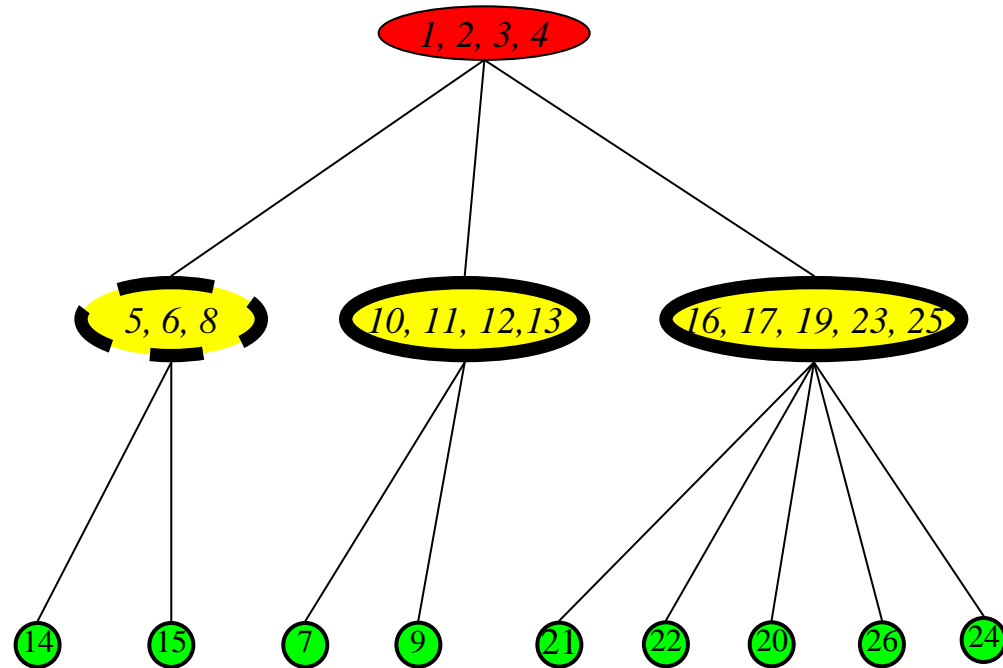
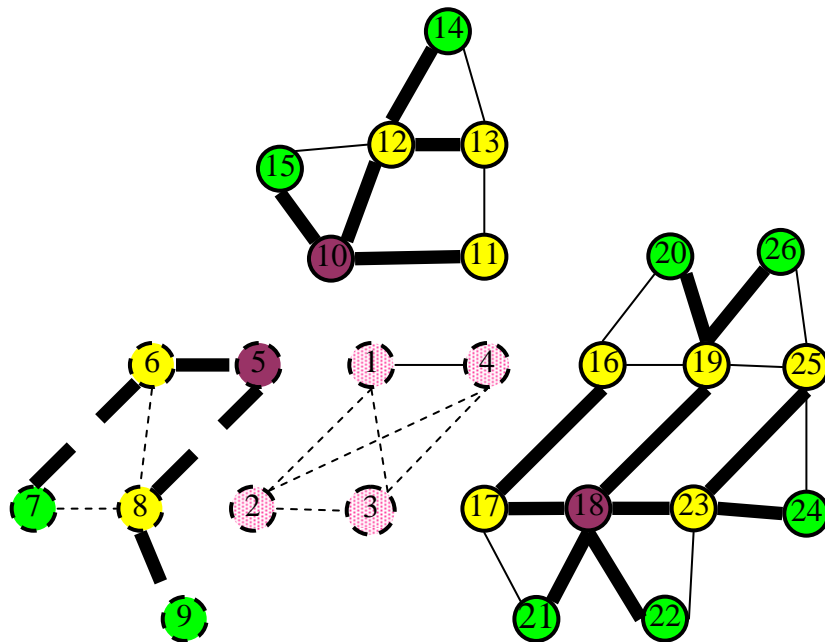
# Constructing Local Spanning Trees

- for each layer of the decomposition tree, construct *local spanning trees* (shortest path trees in the subgraph).
- we use *second layer* for illustration.



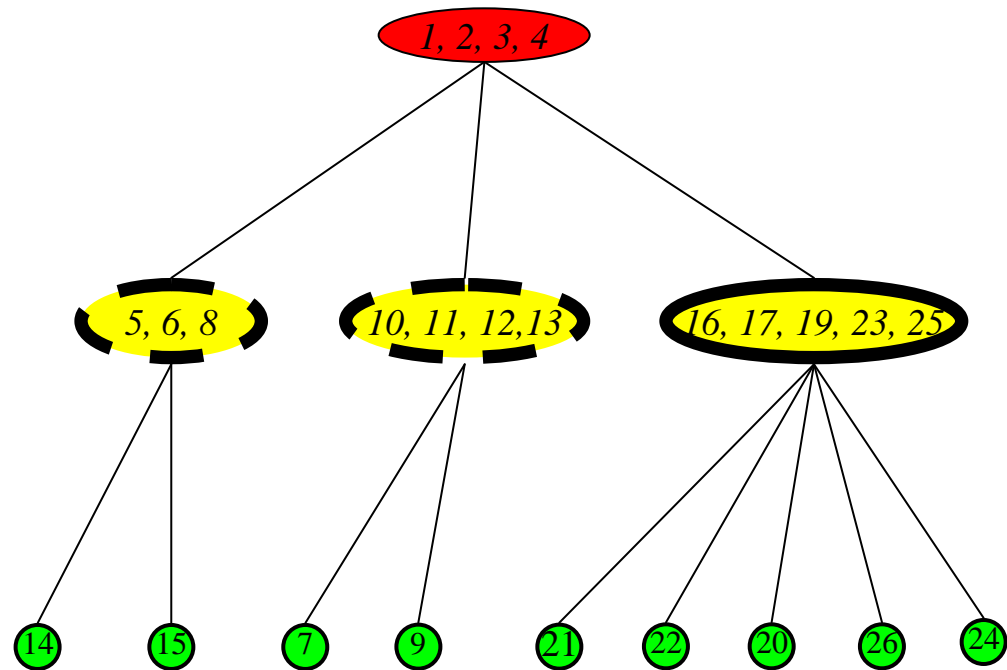
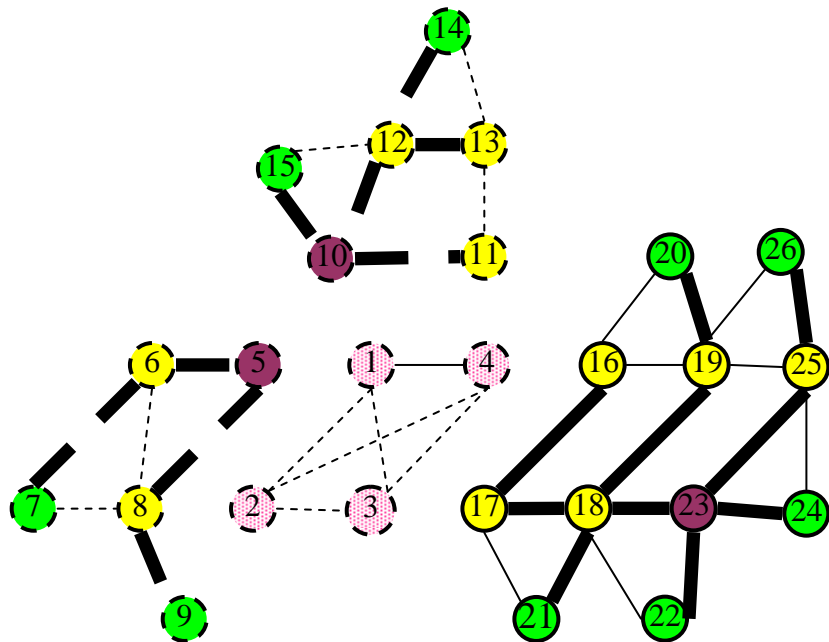
# Constructing Local Spanning Trees

- each time, pick a different vertex from the  $r$ -dominating set to grow a shortest path tree in the subgraph.

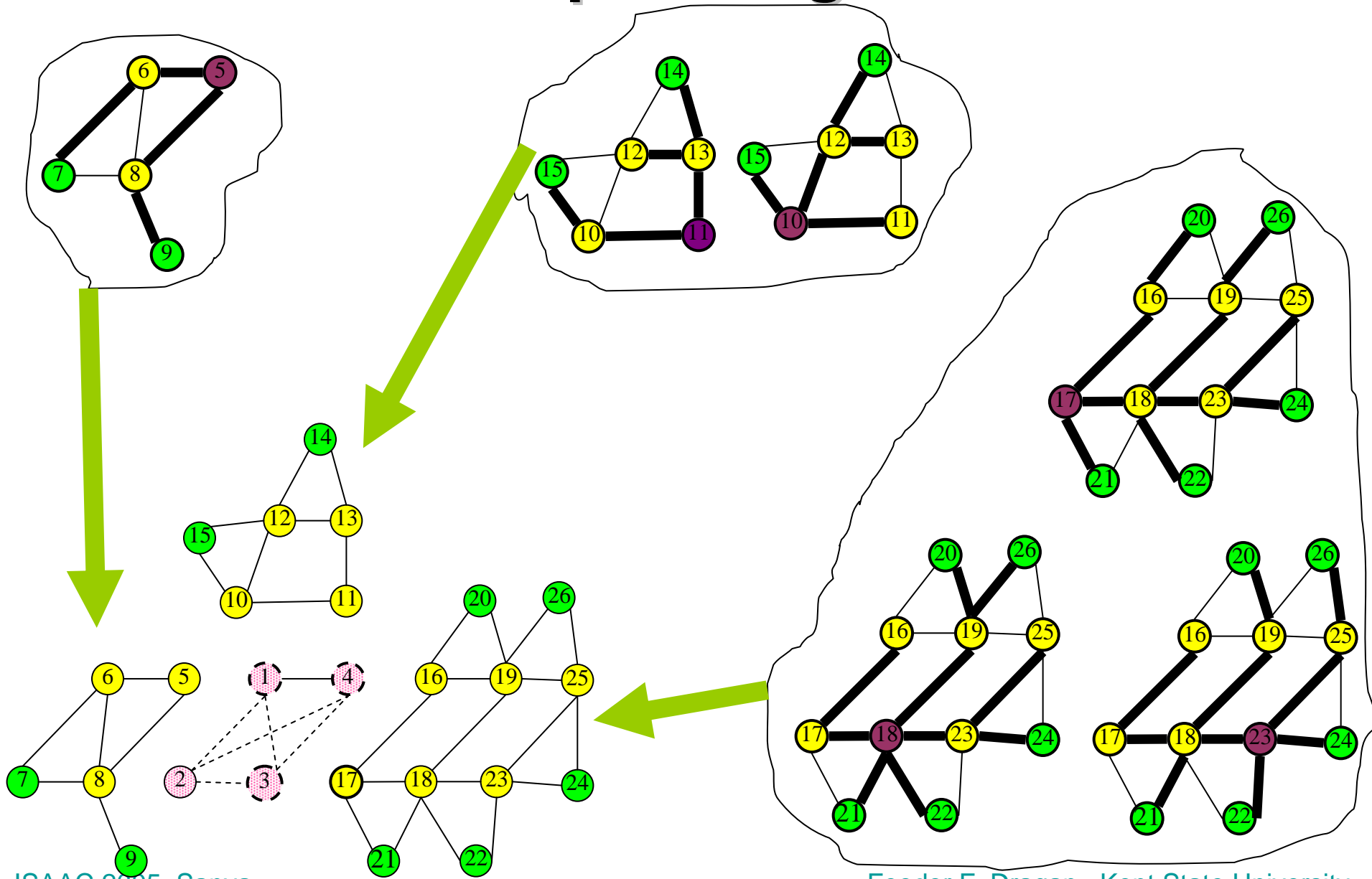


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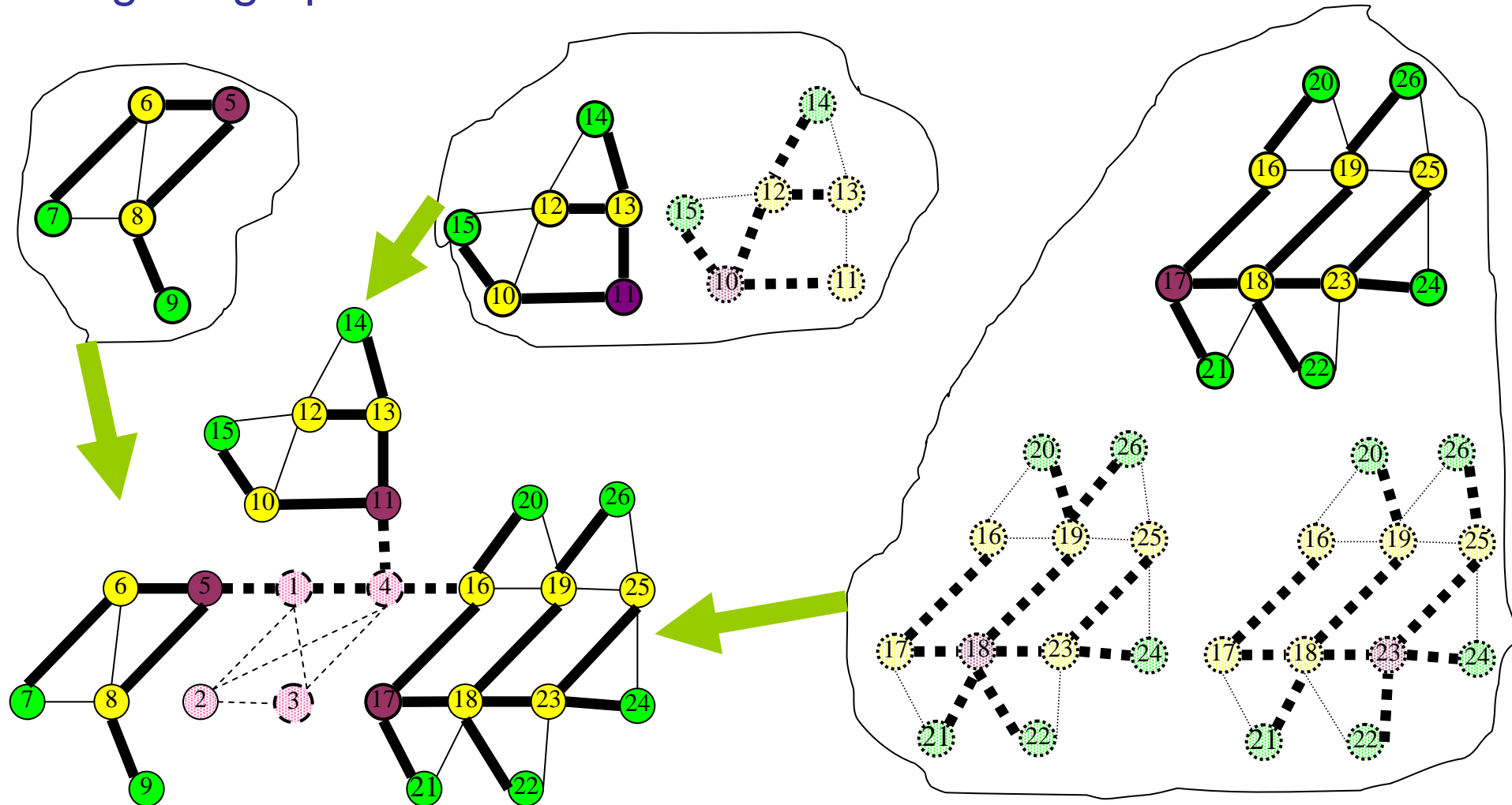


# Local Spanning Trees



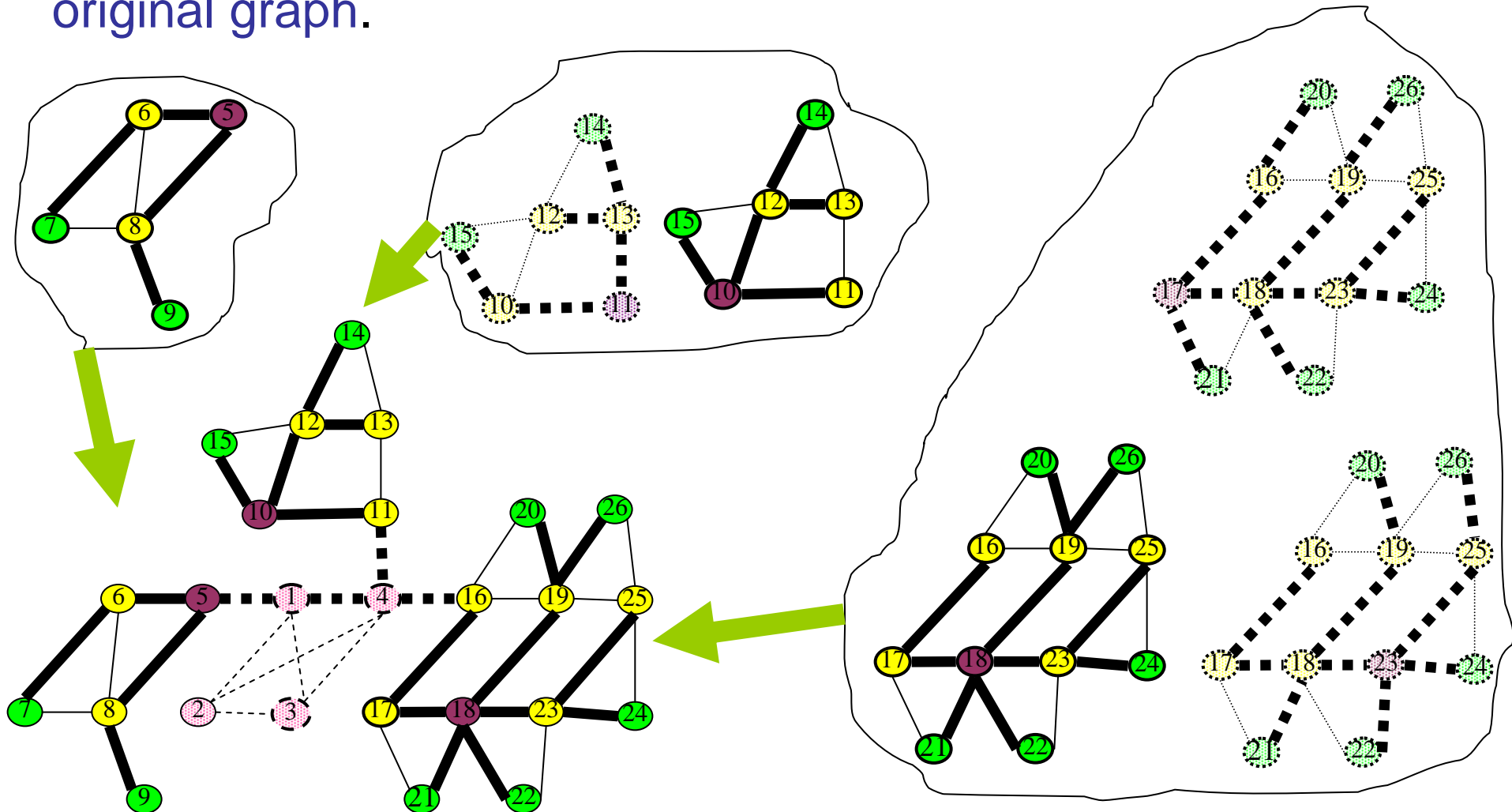
# Spanning Trees Construction

- Connect *local spanning trees* to form *spanning trees* for the original graph.



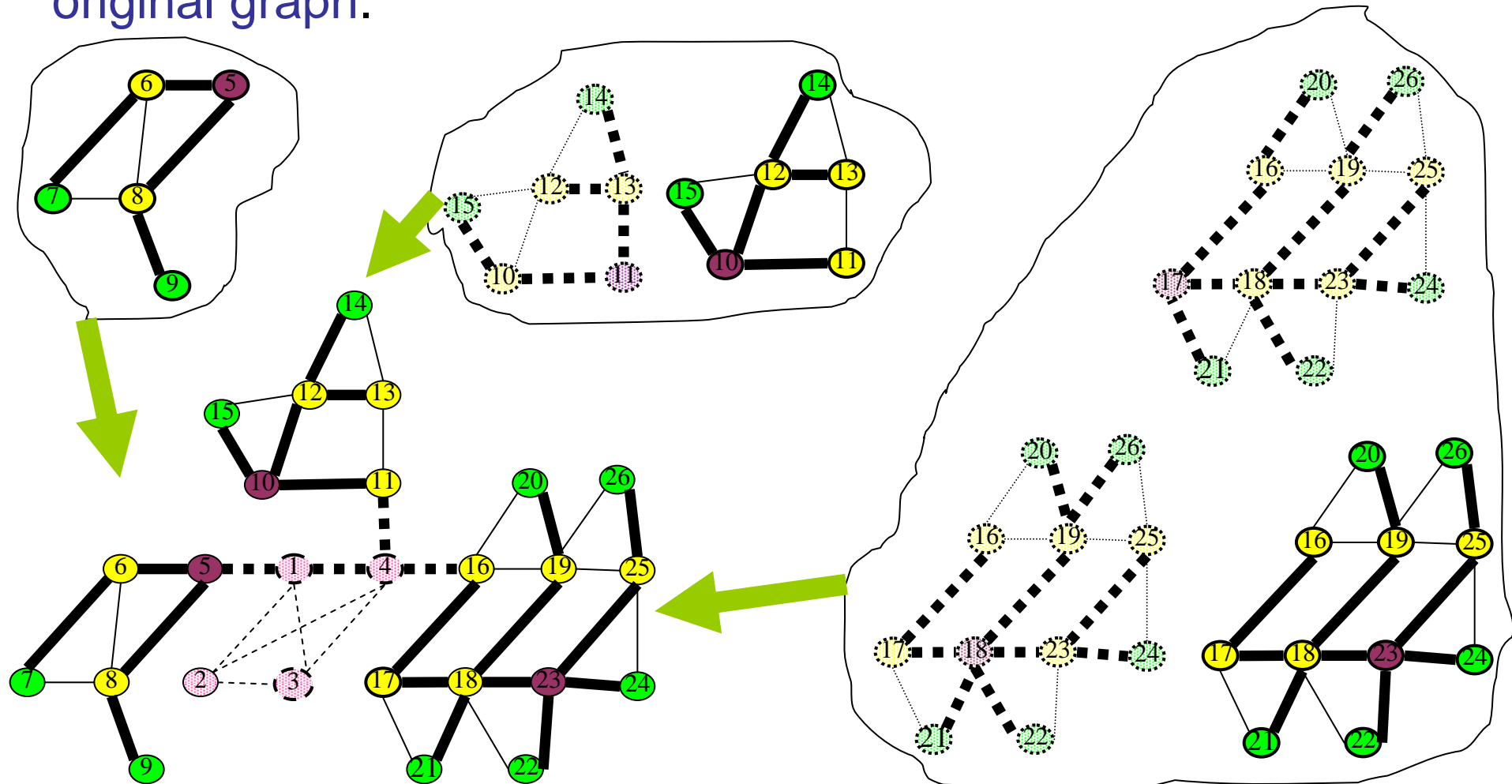
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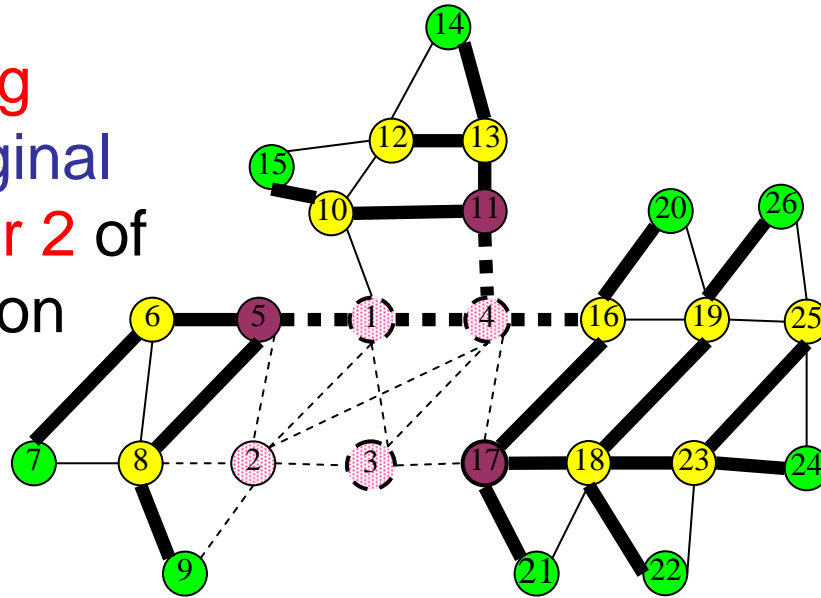
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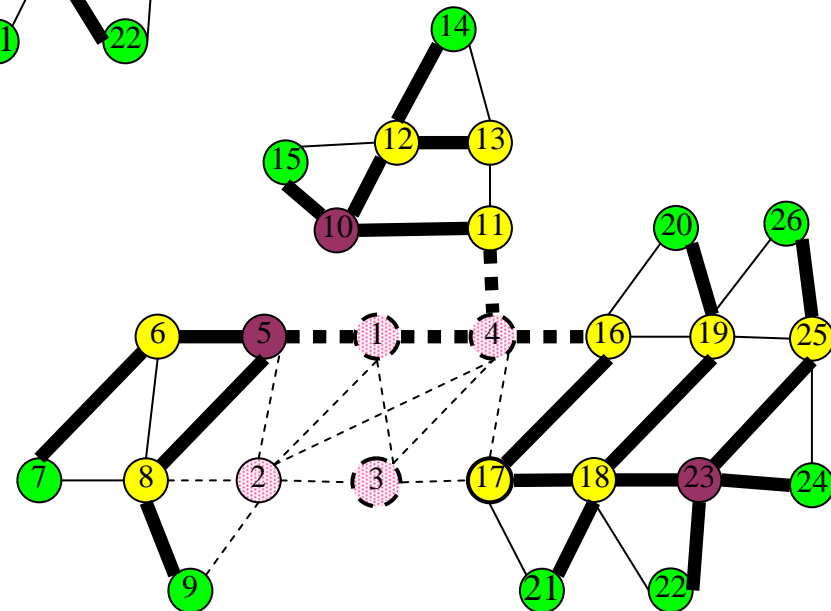
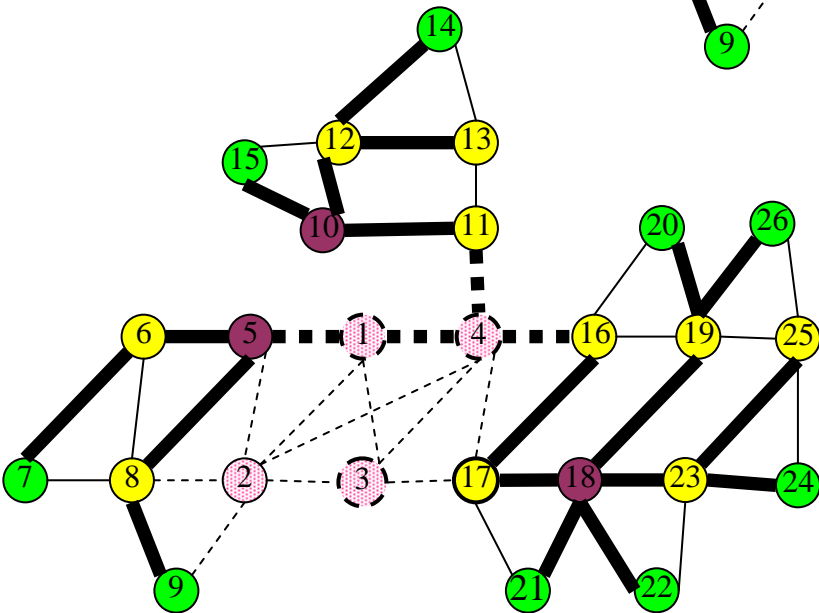


# Spanning Trees Construction

- **Three spanning trees** for the **original graph** w.r.t. **layer 2** of the decomposition tree.



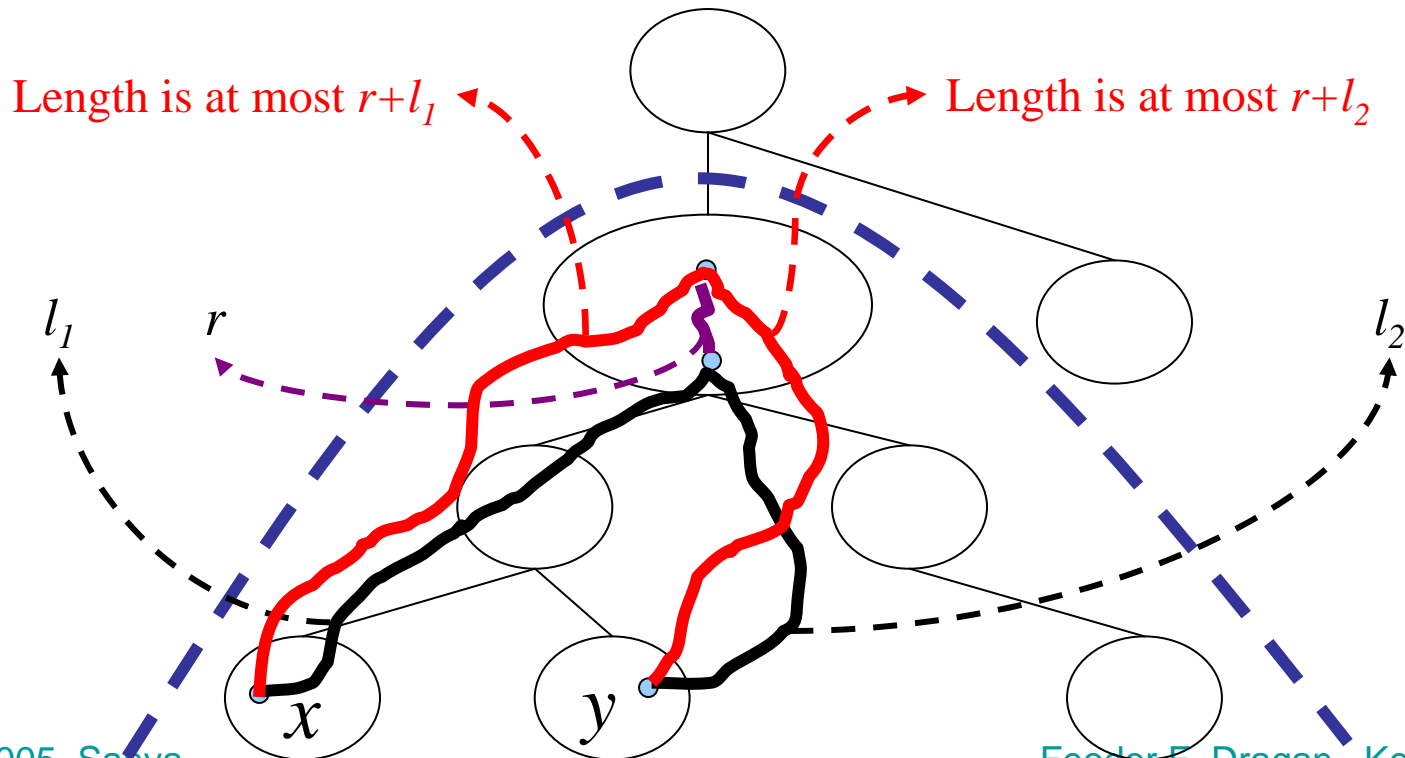
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# Analysis

**Theorem:** Any  $(\alpha, \gamma, r)$ -decomposable graph admits a system of at most  $\gamma \log_{1/\alpha} n$  collective additive tree  $2r$ -spanners.



# Further Results

→ Any  $(\alpha, \gamma, r)$ -decomposable graph  $G$  admits an additive  $2r$ -spanner with at most  $\gamma n \log_{1/\alpha} n$  edges which can be constructed in polynomial time.

→ Any  $(\alpha, \gamma, r)$ -decomposable graph  $G$  admits a routing scheme of deviation  $2r$  and with labels of size  $O(\gamma \log_{1/\alpha} n \log^2 n / \log \log n)$  bits per vertex. Once computed by the sender in  $\gamma \log_{1/\alpha} n$  time, headers never change, and the routing decision is made in constant time per vertex.

# Open questions and future plans

- Given a graph  $G=(V, E)$  and two integers  $\mu$  and  $r$ , what is the complexity of finding a system of  $\mu$  collective additive (multiplicative) tree  $r$ -spanner for  $G$ ? (Clearly, for most  $\mu$  and  $r$ , it is an NP-complete problem.)
- Find better trade-offs between  $\mu$  and  $r$  for planar graphs, genus  $g$  graphs and graphs w/o an  $h$ -minor.
- We may consider some other graph classes. What's the optimal  $\mu$  for each  $r$ ?
- More applications of collective tree spanner...

**Thank You**