

A PTAS for the Sparsest Spanners Problem on Apex-Minor-Free Graphs

Feodor F. Dragan¹ Fedor V. Fomin² Petr A. Golovach²

¹Department of Computer Science, Kent State University

²Department of Informatics, University of Bergen

The 33rd International Symposium on Mathematical
Foundations of Computer Science, Toruń, 2008

Outline

- 1 Introduction**
 - Multiplicative spanners
 - History and related work
 - Our results

- 2 A PTAS for the Sparsest Spanners Problem**
 - Graphs of bounded local treewidth
 - Partial spanners
 - Idea of the algorithm
 - Apex-minor-free graphs

t -spanners

Definition (t -spanner)

Let t be a positive integer. A subgraph S of G , such that $V(S) = V(G)$, is called a (*multiplicative*) t -spanner, if $\text{dist}_S(u, v) \leq t \cdot \text{dist}_G(u, v)$ for every pair of vertices u and v . The parameter t is called the *stretch factor* of S .

t -spanners

Definition (t -spanner)

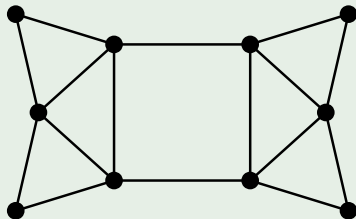
Let t be a positive integer. A subgraph S of G , such that $V(S) = V(G)$, is called a (*multiplicative*) t -spanner, if $\text{dist}_S(u, v) \leq t \cdot \text{dist}_G(u, v)$ for every pair of vertices u and v . The parameter t is called the *stretch factor* of S .

Observation (t -spanner)

Let G be a connected graph, and t be a positive integer. A spanning subgraph S of G is a t -spanner of G if and only if for every edge (x, y) of G , $\text{dist}_S(x, y) \leq t$.

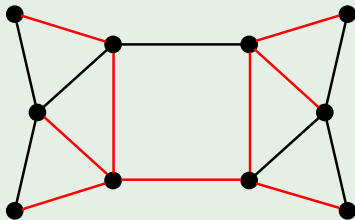
Examples of spanners

3 and 2-spanners



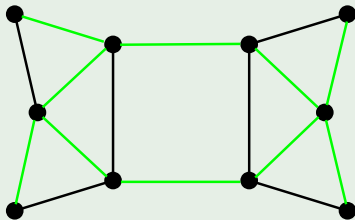
Examples of spanners

3 and 2-spanners



Examples of spanners

3 and 2-spanners



History and related work

- D. Peleg and J. D. Ullman, 1987

History and related work

- D. Peleg and J. D. Ullman, 1987
- D. Peleg and A. A. Schäffer, 1989: It is NP-complete to decide whether there is a t -spanner with at most m edges.

History and related work

- D. Peleg and J. D. Ullman, 1987
- D. Peleg and A. A. Schäffer, 1989: It is NP-complete to decide whether there is a t -spanner with at most m edges.
- G. Kortsarz, 2001: For every $t \geq 2$, there is a constant $c < 1$ such that it is NP-hard to approximate the sparsest t -spanner with the ratio $c \cdot \log n$.

History and related work

- D. Peleg and J. D. Ullman, 1987
- D. Peleg and A. A. Schäffer, 1989: It is NP-complete to decide whether there is a t -spanner with at most m edges.
- G. Kortsarz, 2001: For every $t \geq 2$, there is a constant $c < 1$ such that it is NP-hard to approximate the sparsest t -spanner with the ratio $c \cdot \log n$.
- U. Brandes and D. Handke, 1998: For every $t \geq 5$, it is NP-complete to decide whether there is a t -spanner with at most m edges for planar graphs.

History and related work

- D. Peleg and J. D. Ullman, 1987
- D. Peleg and A. A. Schäffer, 1989: It is NP-complete to decide whether there is a t -spanner with at most m edges.
- G. Kortsarz, 2001: For every $t \geq 2$, there is a constant $c < 1$ such that it is NP-hard to approximate the sparsest t -spanner with the ratio $c \cdot \log n$.
- U. Brandes and D. Handke, 1998: For every $t \geq 5$, it is NP-complete to decide whether there is a t -spanner with at most m edges for planar graphs.
- F. F. Dragan, F. V. Fomin and P. A. Golovach, 2008: For any fixed t and nonnegative integer r , it is possible to decide in a polynomial time whether an apex-minor-free graph G has a t -spanner with at most $n - 1 + r$ edges.

History and related work

- D. Peleg and J. D. Ullman, 1987
- D. Peleg and A. A. Schäffer, 1989: It is NP-complete to decide whether there is a t -spanner with at most m edges.
- G. Kortsarz, 2001: For every $t \geq 2$, there is a constant $c < 1$ such that it is NP-hard to approximate the sparsest t -spanner with the ratio $c \cdot \log n$.
- U. Brandes and D. Handke, 1998: For every $t \geq 5$, it is NP-complete to decide whether there is a t -spanner with at most m edges for planar graphs.
- F. F. Dragan, F. V. Fomin and P. A. Golovach, 2008: For any fixed t and nonnegative integer r , it is possible to decide in a polynomial time whether an apex-minor-free graph G has a t -spanner with at most $n - 1 + r$ edges.
- W. Duckworth, N. C. Wormald, and M. Zito, 2003: A PTAS for the sparsest 2-spanner problem on 4-connected planar triangulations.

Sparsest spanners for planar graphs

Problem (Sparsest t -spanner)

The SPARSEST t -SPANNER problem asks to find, for a given graph G and an integer t , a t -spanner of G with the minimum number of edges.

Sparsest spanners for planar graphs

Problem (Sparsest t -spanner)

The SPARSEST t -SPANNER problem asks to find, for a given graph G and an integer t , a t -spanner of G with the minimum number of edges.

Theorem (PTAS)

For every $t \geq 1$, the SPARSEST t -SPANNER problem admits a PTAS with linear running time for the class of apex-minor-free graphs (and, hence, for the planar graphs and for the graphs with bounded genus).

Graphs of bounded local treewidth

Definition (Graphs of bounded local treewidth)

A graph class \mathcal{G} has bounded local treewidth if there is function $f(r)$ (which depends only on r) such that for any graph G in \mathcal{G} , the treewidth of the subgraph of G induced by the set of vertices at distance at most r from any vertex is bounded above by $f(r)$.

Partial spanners

Definition (Partial t -spanners)

Let $A \subseteq E(G)$. We call a subgraph S of G , such that for every edge $(x, y) \in A$ $\text{dist}_S(x, y) \leq t$, a *partial t -spanner for A* .

Partial spanners

Definition (Partial t -spanners)

Let $A \subseteq E(G)$. We call a subgraph S of G , such that for every edge $(x, y) \in A$ $\text{dist}_S(x, y) \leq t$, a *partial t -spanner for A* .

Lemma

Let k and t be positive integers. Let also G be a graph of treewidth at most k , and let $A \subseteq E(G)$. The SPARSEST PARTIAL t -SPANNER problem can be solved by a linear-time algorithm (the constant which is used in the bound of the running time depends only on k and t) if a corresponding tree decomposition of G is given.

Idea of the algorithm

Definition (BFS decomposition)

Let u be a vertex of a graph G . For $i \geq 0$ we denote by L_i the i -th level of breadth first search, i.e. the set of vertices at distance i from u . We call the partition of the vertex set $V(G)$

$$\mathcal{L}(G, u) = \{L_0, L_1, \dots, L_r\}$$

breadth first search (BFS) decomposition of G .

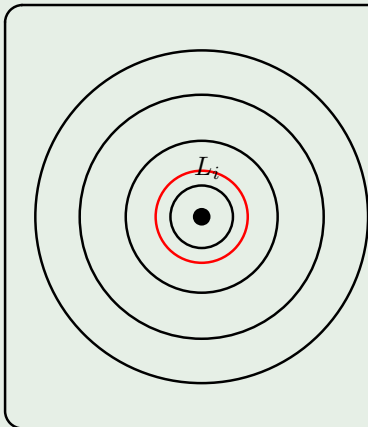
Idea of the algorithm

Lemma

Let S be a sparsest t -spanner of G , $S_i = S[V(G'_i)]$. If S'_i is a sparsest partial t -spanner in G'_i for $A = E(G_i)$ then $|E(S'_i)| \leq |E(S_i)|$.

Idea of the algorithm

Construction of a spanner



$$i = 0, 1, \dots, k - 2$$

Idea of the algorithm

Lemma

The spanner S' has at most $(1 + \frac{t+1}{k-1})\text{OPT}(G)$ edges, where $\text{OPT}(G)$ is the number of edges in the solution of the SPARSEST t -SPANNER problem on G .

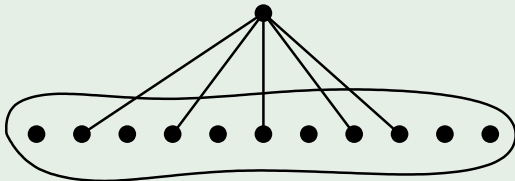
Definition (Apex graphs)

An *apex graph* is a graph obtained from a planar graph G by adding a vertex and making it adjacent to some vertices of G .

Definition (Apex graphs)

An *apex graph* is a graph obtained from a planar graph G by adding a vertex and making it adjacent to some vertices of G .

Apex graphs



Definition (Apex graphs)

An *apex graph* is a graph obtained from a planar graph G by adding a vertex and making it adjacent to some vertices of G .

Definition (Apex-minor-free graphs)

A graph class \mathcal{G} is *apex-minor-free* if \mathcal{G} excludes a fixed apex graph H as a minor.

Definition (Apex graphs)

An *apex graph* is a graph obtained from a planar graph G by adding a vertex and making it adjacent to some vertices of G .

Definition (Apex-minor-free graphs)

A graph class \mathcal{G} is *apex-minor-free* if \mathcal{G} excludes a fixed apex graph H as a minor.

Theorem (Eppstein)

All minor-closed graph classes that have bounded local treewidth are exactly apex-minor-free graph classes.

Thank you!