NP-Completeness

P: is the set of decision problems (or languages) that are solvable in polynomial time.

NP: is the set of decision problems (or languages) that can be verified in polynomial time. **Polynomial reduction:** $L1 \prec_p L2$ means that there is a polynomial time computable function f such that $x \in L1$ if and only if $f(x) \in L2$. A more intuitive to think about this, is that if we had a subroutine to solve L2 in polynomial time, then we could use it to solve L1 in polynomial time

> Lemma: If $L1 \prec_P L2$ and $L2 \in P$ then $L1 \in P$. Lemma: If $L1 \prec_P L2$ and $L1 \notin P$ then $L2 \notin P$.

• Polynomial reductions are transitive, that is, if $L1 \prec_P L2$ and $L2 \prec_P L3$, then $L1 \prec_P L3$.

NPHard: *L* is **NPhard** if for all $L \in \mathbf{NP}$, $L' \prec_P L$. Thus, if we could solve *L* in polynomial time, we could solve all **NP** problems in polynomial time.

NPComplete: *L* is **NPcomplete** if (1) $L \in \mathbb{NP}$ and (2) *L* is **NPhard**.

• The importance of **NPcomplete** problems should now be clear. If any **NPcomplete** problem (and generally any **NPhard** problem) is solvable in polynomial time, then every **NPcomplete** problem (and in fact every problem in **NP**) is also solvable in polynomial time.

• Conversely, if we can prove that any **NPcomplete** problem cannot be solved in polynomial time, then every **NPcomplete** problem (and generally every **NPhard** problem) cannot be solved in polynomial time.

• Thus all **NPcomplete** problems are equivalent to one another (in that they are either all solvable in polynomial time, or none are).

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Cook-Levin's Theorem and Reductions

• Unfortunately, to use this lemma, we need to have *at least one* **NPcomplete** problem to start the ball rolling. Stephen Cook and Leonid Levin showed (~ 1970) that such a problem existed. Cook-Levin's theorem is rather complicated to prove. First we'll try to give a brief intuitive argument as to why such a problem might exist.

• For a problem to be in NP, it must have an efficient verification procedure.

• Virtually all **NP** problems can be stated in the form, ``does there exists *X* such that P(X)", where *X* is some structure (e.g. a set, a path, a partition, an assignment, etc.) and P(X) is some property that *X* must satisfy (e.g. the set of objects must fill the knapsack, or the path must visit every vertex, or you may use at most *k* colors and no two adjacent vertices can have the same color).

• In showing that such a problem is in **NP**, the certificate consists of giving *X*, and the verification involves testing that P(X) holds.

• In general, any set *X* can be described by choosing a set of objects, which in turn can be described as choosing the values of some Boolean variables.

• Similarly, the property P(X) that you need to satisfy, can be described as a Boolean formula.

• Cook and Levin were looking for the *most* general possible property he could, since this should represent the *hardest* problem in **NP** to solve.

• They reasoned that computers (which represent the most general type of computational devices known) could be described entirely in terms of Boolean circuits, and hence in terms of Boolean formulas.

• If any problem were hard to solve, it would be one in which *X* is an assignment of Boolean values (true/false, 0/1) and P(X) could be any Boolean formula. This suggests the following problem, called the *Boolean satisfiability problem*. Theory of Computation, Feodor F. Dragan, Kent State University

Boolean Satisfiability Problem

SAT: Given a Boolean formula, is there some way to assign truth values (0/1, true/false) to the variables of the formula, so that the formula evaluates to true?

• A *Boolean formula* is a logical formula which consists of variables x_i , and the logical operations \overline{x} meaning the *negation* of *x*, *Boolean or* $(x \lor y)$ and *Boolean and* $(x \land y)$.

• Given a Boolean formula, we say that it is *satisfiable* if there is a way to assign truth values (0 or 1) to the variables such that the final result is 1. (As opposed to the case where no matter how you assign truth values the result is always 0.)

For example, $(\mathbf{x}_1 \wedge (\mathbf{x}_2 \vee \overline{\mathbf{x}}_3)) \wedge ((\overline{\mathbf{x}}_2 \wedge \overline{\mathbf{x}}_3) \vee \overline{\mathbf{x}}_1)$

is satisfiable, by the assignment $x_1 = 1, x_2 = 0, x_3 = 0$. On the other hand,

 $(\overline{\mathbf{x}}_1 \lor (\mathbf{x}_2 \land \mathbf{x}_3)) \land (\mathbf{x}_1 \lor (\overline{\mathbf{x}}_2 \land \overline{\mathbf{x}}_3)) \land (\mathbf{x}_2 \lor \mathbf{x}_3) \land (\overline{\mathbf{x}}_2 \lor \overline{\mathbf{x}}_3)$

is not satisfiable. (Observe that the last two clauses imply that one of x_2 and x_3 must be true and the other must be false. This implies that neither of the subclauses involving x_2 and x_3 in the first two clauses can be satisfied, but x_1 cannot be set to satisfy them either.)

Cook-Levin's Theorem: SAT is NP-complete.

We will not prove this theorem. The proof would take about a full lecture.

• The proof and many other interesting results on complexities are given in the *Theory of Computation II* course.

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3Conjunctive Normal Form (3CNF)

• In fact, it turns out that a even more restricted version of the satisfiability problem is **NPcomplete**.

• A *literal* is a variable or its negation, x or \overline{x} .

• A formula is in *3conjunctive normal form (3CNF)* if it is the Booleanand of clauses where each clause is the Booleanor of exactly 3 literals.

• For example $(x_1 \lor x_2 \lor \overline{x}_3) \land (\overline{x}_1 \lor x_3 \lor x_4) \land (x_2 \lor \overline{x}_3 \lor \overline{x}_4)$ is in 3CNF form.

3SAT is the problem of determining whether a formula in 3CNF is satisfiable.

• It turns out that it is possible to modify the proof of Cook's theorem to show that *3SAT* is also **NPcomplete**.

• As an aside, note that if we replace the 3 in **3SAT** with a 2, then everything changes. If a Boolean formula is given in **2SAT**, then it is possible to determine its satisfiability in polynomial time. (It turns out that the problem can be reduced to computing the strong components in a directed graph.)

• Thus, even a seemingly small change can be the difference between an efficient algorithm and none.

NPcompleteness proofs

Now that we know that **3SAT** is **NPcomplete**, we can use this fact to prove that other problems are **NPcomplete**. We will start with the *independent set problem*.

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Independent Set (reduction)

• Secondly, we need to establish that *IS* is **NPhard**, which can be done by showing that some known **NPcomplete** problem (*3SAT*) is polynomialtime reducible to *IS*, that is, $3SAT \prec_P IS$.

• Let *F* be a boolean formula in *3CNF* form. We wish to find a polynomial time computable function *f* that maps *F* into an input for the *IS* problem, a graph *G* and integer *k*. That is, f(F) = (G, k), such that *F* is satisfiable if and only if *G* has an independent set of size *k*.

• This will mean that if we can solve the independent set problem for *G* and *k* in polynomial time, then we would be able to solve *3SAT* in polynomial time.

• An important aspect to reductions is that we do not attempt to solve the satisfiability problem. (It is **NPcomplete**, and there is not likely to be any polynomial time solution.)

• So the function f must operate without knowledge of whether F is satisfiable. The idea is to *translate* the similar elements of the satisfiable problem to corresponding elements of the independent set problem.

What is to be selected?

3SAT: Which variables are to be assigned the value true, or equivalently, which literals will be true and which will be false.

IS: Which vertices will be placed in V'.

Requirements:

3SAT: Each clause must contain at least one true valued literal. **IS:** V' must contain at least k vertices.

Restrictions:

3SAT: If x is assigned true, then \overline{x} must be false, and vice versa. **IS:** If u is selected to be in V', and v is a neighbor of u, then v cannot be in V'.

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Independent Set (reduction: cont.) • We want a function f, which given any 3CNF boolean formula F, converts it into a pair (G, k) such that the above elements are translated properly. • Our strategy will be to turn each literal into a vertex. The vertices will be in *clause clusters* of three, one for each clause. • Selecting a true literal from some clause will correspond to selecting a vertex to add to V'We will set k equal to the number of clauses, to force the independent set subroutine to select one true literal from each clause. • To keep the IS subroutine from selecting two literals from one clause and none from some other, we will connect all the vertices in each clause cluster with edges. • To keep the IS subroutine from selecting a literal and its complement to be true, we will put an edge between each literal and its complement. • A formal description of the reduction is given below. The input is a boolean formula F in 3-*CNF*, and the output is a graph *G* and integer *k*. • If *F* has *k* clauses, then *G* has $k \leftarrow$ number of clauses in F; for each clause C in F { exactly 3k vertices. create a *clause cluster* of 3 vertices from the literals of C; • Given any reasonable encoding of F, it is an easy programming exercise to create G (say as an for each clause cluster (x_1, x_2, x_3) { create an edge (x_i, x_j) between all pairs of vertices in the cluster; adjacency matrix) in polynomial time. for each vertex x_i { create edges between x_i and all its complement vertices \overline{x}_i ; • We claim that F is satisfiable if and only if G has an independent return (G,k);set of size k. Theory of Computation, Feodor F. Dragan, Kent State University 8





Correctness Proof

• We claim that F is satisfiable if and only if G has an independent set of size k.

- If *F* is satisfiable, then each of the *k* clauses of *F* must have at least one true literal.
- Let *V*' denote the corresponding vertices from each of the clause clusters (one from each cluster).

• Because we take vertices from each cluster, there are no intercluster edges between them, and because we cannot set a variable and its complement to both be true, there can be no edge of the form (x_i, \bar{x}_i) between the vertices of V'. Thus, V' is an independent set of size k.

• Conversely, if G has an independent set V' of size k. First observe that we must select a vertex from each clause cluster, because there are k clusters, and we cannot take two vertices from the same cluster (because they are all interconnected).

• Consider the assignment in which we set all of these literals to 1. This assignment is logically consistent, because we cannot have two vertices labeled x_i and \overline{x}_i in the same cluster.

• Finally the transformation clearly runs in polynomial time. This completes the NP-completeness proof.

• Observe that our reduction did not attempt to solve the IS problem nor to solve the 3SAT.

• Also observe that the reduction had *no knowledge* of the solution to either problem. (We did not assume that the formula was satisfiable, nor did we assume we knew which variables to set to 1.) This is because computing these things would require exponential time (by the best known algorithms).

• Instead the reduction simply *translated* the input from one problem into an equivalent input to the other problem, while preserving the critical elements to each problem.

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Clique and Vertex Cover Problems

• Now we give a few more examples of reductions.

• Recall that to show that a problem is **NPcomplete** we need to show (1) that the problem is in **NP** (i.e. we can verify when an input is in the language), and (2) that the problem is **NP**-hard, by showing that some known **NPcomplete** problem can be reduced to this problem (there is a polynomial time function that transforms an input for one problem into an equivalent input for the other problem).

Some Easy Reductions: We consider some closely related NPcomplete problems next.

Clique (CLIQUE): The clique problem is: given an undirected graph G = (V, E) and an integer k, does G have a subset V' of k vertices such that for each distinct $u, v \in V'$, $\{u, v\} \in E$. In other words, does G have a k vertex subset whose induced subgraph is complete.

Vertex Cover (VC): A vertex cover in an undirected graph G = (V, E) is a subset of vertices

 $V' \subseteq V$ such that every edge in *G* has at least one endpoint in *V*'. The vertex cover problem (*VC*) is: given an undirected graph *G* and an integer *k*, does *G* have a vertex cover of size *k*?

• Don't confuse the clique (*CLIQUE*) problem with the cliquecover (*CCov*) problem that we discussed in an earlier lecture. The clique problem seeks to find a single clique of size k, and the cliquecover problem seeks to partition the vertices into k groups, each of which is a clique.

• We have discussed the facts that cliques are of interest in applications dealing with clustering.

• The vertex cover problem arises in various servicing applications. For example, you have a computer network and a program that checks the integrity of the communication links. To save the space of installing the program on every computer in the network, it suffices to install it on all the computers forming a vertex cover. From these nodes all the links can be tested. Theory of Computation, Feodor F. Dragan, Kent State University



Clique and Vertex Cover (NP-completeness)

• Thus, if we had an algorithm for solving any one of these problems, we could easily translate it into an algorithm for the others. In particular, we have the following.

Theorem: CLIQUE is NPcomplete.

CLIQUE \in **NP**: The certificate consists of the *k* vertices in the clique. Given such a certificate we can easily verify in polynomial time that all pairs of vertices in the set are adjacent.

 $IS \prec_p CLIQUE$: We want to show that given an instance of the *IS* problem (*G*, *k*), we can produce an equivalent instance of the *CLIQUE* problem (*G'*,*k'*) in polynomial time.

• (Important: We do not know whether G has an independent set, and we do not have time to compute it.)

• Given G and k, set $G' = \overline{G}$ and k' = k, and output the pair (G', k'). By the above lemma, this instance is equivalent.

Theorem: VC is NPcomplete.

 $VC \in \mathbf{NP}$: The certificate consists of the *k* vertices in the vertex cover. Given such a certificate we can easily verify in polynomial time that every edge is incident to one of these vertices.

 $IS \prec_P VC$: We want to show that given an instance of the IS problem (G, k), we can produce an equivalent instance of the VC problem (G', k') in polynomial time. We set G' = G and k' = n - k. By the above lemma, these instances are equivalent.

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