# Collective Tree Spanners of Unit 

 Disk Graphs with Applications toCompact and Low Delay Routing

## Labeling Schemes

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## Well-known Tree $t$-Spanner Problem

Given unweighted undirected graph $G=(V, E)$ and integers $t, r$.
Does $G$ admit a spanning tree $T=\left(V, E^{\prime}\right)$ such that
$\forall u, v \in V, \operatorname{dist}_{T}(v, u) \leq t \times \operatorname{dist}_{G}(v, u) \quad$ (a multiplicative tree $t$-spanner of $G$ ) or
$\forall u, v \in V, \operatorname{dist}_{T}(u, v)-\operatorname{dist}_{G}(u, v) \leq r \quad($ an additive tree $r$-spanner of $G)$ ?


## Some known results for the tree spanner problem <br> (mostly multiplicative case)

- general graphs [CC'95]
- $t \geq 4$ is NP-complete. ( $t=3$ is still open, $t \leq 2$ is P )
- approximation algorithm for general graphs [EP'04]
- O(logn) approximation algorithm
- chordal graphs [BDLL'02]
$-t \geq 4$ is NP-complete. ( $t=3$ is still open.)
- planar graphs
- arbitrary $t \geq 4$, is NP-complete. ( $t=3$ is polyl time solvable.) [FK'01]
- for each fixed $t$, is linear time solvable [DFG'08]
- easy to construct for some special families of graphs.


## Well-known Sparse t-Spanner Problem

Given unweighted undirected graph $G=(V, E)$ and integers $t, m, r$. Does $G$ admit a spanning graph $H=\left(V, E^{\prime}\right)$ with $\left|E^{\prime}\right| \leq m \quad$ s.t.
$\forall u, v \in V, \operatorname{dist}_{H}(v, u) \leq t \times \operatorname{dist}_{G}(v, u)$ (a multiplicative $t$-spanner of $G$ ) or
$\forall u, v \in V, \operatorname{dist}_{H}(u, v)-\operatorname{dist}_{G}(u, v) \leq r \quad$ (an additive $r$-spanner of $G$ )?

multiplicative 2 - and additive 1 -spanner of $G$

## Some known results for sparse spanner problems

- general graphs
- $t, m \geq 1$ is NP-complete [PS'89]
- multiplicative (2k-1)-spanner with $n^{l+1 / k}$ edges [TZ'01, BS'03]
- $n$-vertex chordal graphs (multiplicative case) [PS'89]
( $G$ is chordal if it has no chordless cycles of length $>3$ )
- multiplicative 3 -spanner with $O(n \log n)$ edges
- multiplicative 5 -spanner with $2 n$-2 edges
- $n$-vertex $c$-chordal graphs (additive case) [CDY'03, DYL'04]
( $G$ is $c$-chordal if it has no chordless cycles of length $>\mathrm{C}$ )
- additive (c+1)-spanner with 2n-2 edges
- additive (2 Lc/2」) -spanner with $n \log n$ edges

玉 For chordal graphs: additive 4 -spanner with $2 n-2$ edges, additive 2 spanner with $n \log n$ edges

- planar graphs
- If $t, m \geq 1$ are constants, then in linear time [DFG'08]
- PTAS for every $t \geq 1$ [DFG'08]


## Relatively new Collective $\mathcal{A}$ dditive $\operatorname{Tr}$ ree

 $r$-Spanners ProblemGiven unweighted undirected graph $G=(V, E)$ and integers $\mu$, $r$. Does $G$ admit a system of $\mu$ collective additive tree $r$-spanners

$$
\left\{T_{1}, T_{2}^{\prime} \ldots, T \mu\right\}
$$

such that
$\forall u, v \in V$ and $\exists 0 \leq i \leq \mu, \operatorname{dist}_{T_{i}}(v, u)-\operatorname{dist}_{G}(v, u) \leq r$ (a system of $\mu$ collective additive tree $r$-spanners of $G$ )?


## collective multiplicative tree $t$-spanners can be defined similarly

$\square$
surplus

2 collective additive tree 2-spanners

## Relatively new Collective $\mathcal{A}$ dditive Tree

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2 collective additive tree 2-spanners


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## Applications of Collective Tree Spanners

- message routing in networks

Efficient routing schemes are known for trees but not for general graphs. For any two nodes, we can route the message between them in one of the trees which approximates the distance between them.

- ( $\mu \log ^{2} n$ )-bit labels,
- $O(\mu)$ initiation, $O(1)$ decision
- solution for sparse $t$-spanner problem
If a graph admits a system of $\mu$ collective additive tree $r$-spanners, then the graph admits a sparse additive $r$-spanner with at most $\mu(n-1)$ edges, where $n$ is the number of nodes.


2 collective tree 2spanners for $G$

## Previous results on the collective tree spanners problem (Dragan, Yan, Lomonosov [SWAT'04]) (Corneil, Dragan, Köhler, Yan [WG’05])

- chordal graphs, chordal bipartite graphs
- log n collective additive tree 2-spanners in polynomial time
- $\Omega\left(n^{1 / 2}\right)$ or $\Omega^{\prime}(n)$ trees necessary to get +1
- no constant number of trees guaranties +2 (+3)
- circular-arc graphs
- 2 collective additive tree 2-spanners in polynomial time
- c-chordal graphs
- $\log n$ collective additive tree $2 / c / 2\rfloor$-spanners in polynomial time
- interval graphs
- $\log n$ collective additive tree 1-spanners in polynomial time
- no constant number of trees guaranties +1


## Previous results on the collective tree spanners problem (Dragan, Yan, Corneil [WG'04])

- AT-free graphs
- include: interval, permutation, trapezoid, co-comparability
- 2 collective additive tree 2-spanners in linear time
- an additive tree 3 -spanner in linear time (before)
- graphs with a dominating shortest path
- an additive tree 4 -spanner in polynomial time (before)
- 2 collective additive tree 3 -spanners in polynomial time
- 5 collective additive tree 2-spanners in polynomial time
- graphs with asteroidal number $\operatorname{an}(\mathrm{G})=k$
- $k(k-1) / 2$ collective additive tree 4-spanners in polynomial time
- $k(k-1)$ collective additive tree 3 -spanners in polynomial time


## Previous results on the collective tree spanners problem (Gupta, Kumar,Rastogi [SICOMP’05])

- the only paper (before) on collective multiplicative tree spanners in weighted planar graphs
- any weighted planar graph admits a system of $O(\log n)$ collective multiplicative tree 3-spanners
- they are called there the tree-covers.
- it follows from (Corneil, Dragan, Köhler, Yan [WG'05]) that
- no constant number of trees guaranties +c (for any constant c)


## Some results on collective additive tree spanners of weighted graphs with bounded parameters <br> (Dragan, Yan [ISAAC’04])

| Graph class | $\mu$ | $r$ | $\} \begin{gathered} \Omega\left(\sqrt{n} \log \log n / \log ^{2} n\right) \\ \text { to get }+0 \end{gathered}$ |
| :---: | :---: | :---: | :---: |
| planar | $O(\sqrt{n})$ | 0 |  |
| with genus $g$ | $O(\sqrt{g n})$ | 0 | No constant number of |
| W/o an $\boldsymbol{h}$-vertex minor | $O\left(\sqrt{h^{3} n}\right)$ | 0 | trees guaranties $+r$ for any constant $r$ even for |
| $t w(G) \leq k-1$ | $k \log _{2} n$ | 0 | outer-planar graphs |
| $c w(G) \leq k$ | $k \log _{3 / 2} n$ | 2w | $\} \Omega(n)$ to get +1 |
| c-chordal | next | slide |  |

- $w$ is the length of a longest edge in $G$

Some results on collective additive tree spanners of weighted c-chordal graphs (Dragan, Yan [ISAAC'04])

| Graph class | $\mu$ | $r$ |
| :---: | :---: | :---: |
| $\begin{gathered} c \text {-chordal } \\ (c>4) \end{gathered}$ | $\begin{aligned} & \log _{2} n \\ & 4 \log _{2} n \\ & 5 \log _{2} n \end{aligned}$ | $\begin{aligned} & 2\left\lfloor\frac{c}{2}\right\rfloor w \\ & 2\left(\left\lfloor\frac{c}{3}\right\rfloor+1\right) w \\ & 2\left\lfloor\frac{c+2}{3}\right\rfloor w \end{aligned}$ |
| 4-chordal | $6 \log _{2} n$ | $2 w$ |
| weakly chordal | $4 \log _{2} n$ | $2 w$ |

No constant number of trees guaranties $+r$ for any constant $r$ even for weakly chordal graphs

## Unit Disk Graphs

- Unit Disk Graphs are the intersection graphs of equal sized circles in the plane.


Model
wireless
networks


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$\mathcal{K}$ nown Sparse spanners for UDGs

| Spanner | Length <br> Stretch <br> Factor | Hop Stretch <br> Factor |
| :---: | :---: | :---: |
| Gabriel <br> Graph | $\frac{4 \pi \sqrt{2 n-4}}{3}$ | - |
| Yao Graph | $\frac{1}{1-2 \sin \frac{\pi}{k}}$ | - |
| Unit Del | $\frac{4 \sqrt{3}}{9} \pi$ | - |
| LDel | $\frac{4 \sqrt{3}}{9} \pi$ | Very Large <br> Constant |



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## Unit Delaunay Triangulation and Greedy Routing



- [KG'92] showed that Unit Delaunay triangulation is a length tspanner for $\approx \approx 2.42$.
- (Localized) Unit Delaunay triangulation with Greedy Routing (no guarantee of delivery).
- Face greedy routing by [BMSU'99] guarantees delivery (4m moves)


## $\mathcal{N}$ ew results on collective tree spanners of Unit Disk Graphs

Definition: A graph $G$ admits a system of $\mu$ collective tree $(t, r)$-spanners if there is a system $\mathscr{T}(G)$ of at most $\mu$ spanning trees of G such that for any two vertices $x, y$ of $G$ a spanning tree $T \in \mathscr{T}(G)$ exists such that

$$
d_{T}(x, y) \leq t d_{G}(x, y)+r .
$$

Theorem: Any Unit Disk Graph admits a system of at most $2 \log _{3 / 2} n+2$ collective tree $(3,12)$ spanners. Construction is in $O((C+m) \log n)$ time where $C$ is the number of crossings in $G$.

## Planar Graphs

In balanced separator
$O(\sqrt{ } n)$ trees giving to Lipton\&Tarjan $O(\log n)$ trees giving 3


## Unit Disk Graphs

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## Finding a Balanced Separator in a Unit Disk Graph

1. Build a layering spanning tree $T$ for $G$.
2. Convert the Unit Disk Graph $G$ into a planar graph $G_{p}$ and $T$ into a spanning tree $T_{p}$ for $G_{p}$.
3. Apply Lipton\&Tarjan's separator theorem to the planar graph $G_{p}$ and spanning tree $T_{p}$ to find a balanced separator $S_{p}$ for $G_{p}$.
4. (The most important Step) From $S_{p}$, reconstruct a balanced separator $S$ for $G$.

## Step 1: Build a layering spanning tree $T$ for $G$



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Step 2: Convert the Unit Disk Graph G into a planar graph $G_{p}$ and $T$ into a spanning tree $T_{p}$ for $G_{p}$


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Challenging problem: an edge has multiple intersections in $\mathcal{G}$

- Our algorithm can deal with this case. For Example:


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Step 3: Apply Lipton\&Tarjan's separator theorem to the planar graph $G_{p}$ and spanning tree $T_{p}$ to find a balanced separator $S_{p}$ for $G_{p}$


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## Step 4: From $S_{p}$, reconstruct a balanced separator $S$ for $G$



Our algorithm will decide either to put acd or abd into $P$ to make $S=N^{3}\left[P_{1} \cup P_{2}\right]$ a balanced separator.

## Separator theorem

- $S=N^{3}{ }_{G}\left[P_{1} U P_{2}\right]$ is a balanced separator for $G$ with $2 / 3$-split, i.e., removal of $S$ from $G$ leaves no connected component with more than $2 / 3 n$ vertices


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## Constructing two spanning

 trees for a balanced separator

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## Lemma for the two spanning trees

- Let $x, y$ be two arbitrary vertices of $G$ and $P(x, y)$ be a (hop-) shortest path between $x$ and $y$ in $G$. If $P(x, y) \cap S \neq \varnothing$, then
$-d_{T 1}(x, y) \leq 3 d_{G}(x, y)+12$ or
$-d_{T 2}(x, y) \leq 3 d_{G}(x, y)+12$




## Constructing two spanning

 trees per level of decomposition- For each layer of the decomposition tree, construct local spanning trees (shortest path trees in the subgraph)



# Theorem for collective tree spanners 

- Any unit disk graph $G$ with $n$ vertices and $m$ edges admits a system $\mathscr{J}(G)$ of at most $2 \log _{3 / 2} n+2$ collective tree ( 3,12 )-spanners, i.e., for any two vertices $x$ and $y$ in $G$, there exists a spanning tree $T \in \mathscr{T}(G)$ with $d_{T}(x, y) \leq 3 d_{G}(x, y)+12$


## Applications: Distance Labeling

 Scheme and Routing Labefing Scheme- Distance Labeling Scheme: The family of $n$ vertex unit disk graphs admits an $O\left(\log ^{2} n\right)$ bit $(3,12)$-approximate distance labeling scheme with $O(\log n)$ time distance decoder.
- Routing Labeling Scheme: The family of nvertex unit disk graphs admits an $O(\log n)$ bit routing labeling scheme. The Scheme has hop $(3,12)$-route-stretch. Once computed by the sender in $O(\log n)$ time, headers never change, and the routing decision is made in constant time per vertex.


# Extension to routing labeling 

 scheme with bounded length routestretch- The family of $n$-vertex unit disk graphs admits an $O(\log n)$ bit routing labeling scheme. The scheme has length $(5,13)$ -route-stretch. Once computed by the sender in $O(\log n)$ time, headers never change, and the routing decision is made in constant time per vertex.


## Open questions

- Does there exist a distance or a routing labeling scheme that can be locally constructed for Unit Disk Graphs?
- Does there exist a balanced separator of form $S=N_{G}\left[P_{1} U P_{2}\right]$ ?


## Thank <br> You

