Mutual Exclusion in a Distributed Environment

- Mutual exclusion
 - Centralized algorithms
 - Central physical clock
 - Central coordinator
 - Distributed algorithms
 - Time-based event ordering
 - Lamport's algorithm (logical clocks)
 - Ricart & Agrawala's algorithm (" ")
 - Suzuki & Kasimi's algorithm (broadcast)
 - Token passing
 - Le Lann's token-ring algorithm (logical ring)
 - Raymond's tree algorithm (logical tree)
 - Sharing K identical resources
 - Raymond's extension to Ricart & Agrawala's time-based algorithm
 - Atomic transactions (later in course)
- Related self-stabilizing algorithms, election, agreement, deadlock

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Mutual Exclusion in a Distributed Environment — General Requirements

- N processes share a single resource, and require mutually-exclusive access
- Conditions to satisfy:
 - A process holding the resource must release it before it can be granted to another process
 - If every process granted the resource eventually releases it, then every request will be eventually granted
 - Requests for the resource must be granted in the order in which they're made
- Assumptions made:
 - Each process can send a message to any other process
 - Messages between two processes are received in the order they are sent
 - Every message is eventually received

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Central Physical Clock

- Provide a single central physical clock, just like in a centralized system
 - Processes request physical timestamps from this clock and use them to order events
- ✔ Advantages:
 - Simplicity

X Disadvantages:

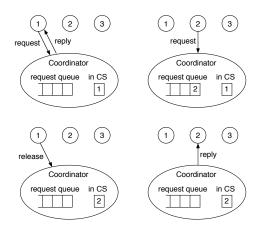
- Clock must always be available to provide the requested timestamps
- Transmission errors can prevent the proper ordering from taking place
- An accurate estimation of transmission delays is required
- The degree of accuracy may not be as high as desired

Central Coordinator

- To enter the critical section, a thread sends a *request* message to the central coordinator, and waits for a reply
- When the coordinator receives a request:
 - If no other thread is in the critical section, it sends back a reply message
 - If another thread is in the critical section, the coordinator adds the request to the tail of its gueue, and does not respond
- When the requesting thread receives the reply message from the coordinator, it enters the critical section
 - When it leaves the critical section, it sends a *release* message to coordinator
 - When the coordinator receives a release message, it removes the request from the head of the queue, and sends a reply message to that thread

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Central Coordinator (cont.)



■ Evaluation:

- 3 messages required to enter CS
 - release, request, reply
- ✗ Coordinator is a performance bottleneck
- ✗ Coordinator is a single point of failure
- ✗ Delay is unconstrained

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Lamport's Algorithm (1978)

- Each process maintains a request queue, ordered by timestamp value
- Requesting the critical section (CS):
 - When a thread wants to enter the CS, it:
 - Adds the request to its own request queue
 - Sends a timestamped *request* message to all threads in that CS's request set
 - When a thread receives a request message, it:
 - Adds the request to its own request queue
 - Returns a timestamped reply message
- Executing the CS:
 - A thread enters the CS when both:
 - Its own request is at the top of its own request queue (its request is earliest)
 - It has received a reply message with a timestamp larger than its request from all other threads in the request set

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Lamport's Algorithm (cont.)

- Releasing the CS:
 - When a thread leaves the CS, it:
 - Removes its own (satisfied) request from the top of its own request queue
 - Sends a timestamped release message to all threads in the request set
 - When a thread receives a release message, it:
 - Removes the (satisfied) request from its own request queue
 - (Perhaps raising its own message to the top of the queue, enabling it to finally enter the CS)

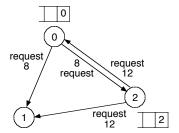
■ Evaluation:

- 3(N−1) messages required to enter CS
 - (N-1) release, (N-1) request, (N-1) reply

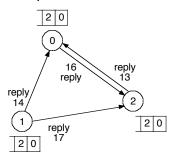
X Later...

Lamport's Algorithm (cont.)

■ Both threads 0 and 2 request the CS:

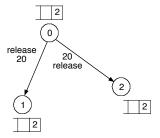


■ Everyone replies, thread 0 enters the CS since its request was first:



Lamport's Algorithm (cont.)

■ Thread 0 releases the CS, thread 2 enters it:



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Ricart and Agrawala's Algorithm (1981)

- Requesting the critical section (CS):
 - When a thread wants to enter the CS, it:
 - Sends a timestamped request message to all threads in that CS's request set
 - When a thread receives a request message:
 - If it is neither requesting nor executing the CS, it returns a *reply* message
 - If it is requesting the CS, but the timestamp on the incoming request is smaller than the timestamp on its own request, it returns a reply message
 - Means the other thread requested first
 - Otherwise, it defers answering the request
- Executing the CS:
 - A thread enters the CS when:
 - It has received a reply message from all other threads in the request set

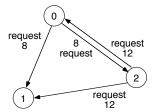
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Ricart and Agrawala's Algorithm (cont.)

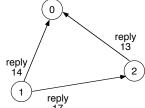
- Releasing the CS:
 - When a thread leaves the CS, it:
 - Sends a reply message to all the deferred requests
 - (Thread with next earliest request will now received its last reply message and enter the CS)
- Evaluation:
 - 2(N−1) messages required to enter CS
 - (N-1) reply, (N-1) request
- Evaluation (Lamport, Ricart & Agawala):
 - ✗ Distributed performance bottleneck
 - X Now N points of failure
 - If a thread crashes, it fails to reply, which is interpreted as a denial of permission to enter the CS, so everyone waits...
 - ✗ Need up-to-date group communication

Ricart and Agrawala's Algorithm (cont.)

■ Both threads 0 and 2 request the CS:



■ Threads 1 and 2 reply, thread 0 defers and enters the CS since its request was first:



■ After leaving the CS, thread 0 replies to thread 2, which enters the CS

Raymond's Extension For Sharing K Identical Resources (1987)

- K identical resources, which must be shared among N processes
- Raymond's extension to Ricart and Agrawala's algorithm:
 - A process can enter the CS as soon as it has received N–K reply messages
 - Algorithm is generally the same as R&A, with one difference:
 - R&A *reply* messages arrive only when process is waiting to enter CS
 - Raymond
 - N–K reply messages arrive when process is waiting to enter CS
 - Remaining K-1 reply messages can arrive when process is in the CS, after it leaves the CS, or when it's waiting to enter the CS again
 - Must keep a count of number of outstanding reply messages, and not count those toward next set of replies

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