Details of Semaphore Operation	Two Versions of Semaphores
Semaphore "s" is initially 1	 Semaphores from last time (simplified): wait (s): signal (s):
Before entering the critical section, a thread calls "P(s)" or "wait(s)"	$s = s - 1$ $s = s + 1$ if $(s < 0)$ if $(s \le 0)$
 wait (s): s = s - 1 if (s < 0) block the thread that called wait(s) on a queue associated with semaphore s 	block the thread wake up one of that called wait(s) the waiting threads otherwise continue into CS
 otherwise let the thread that called wait(s) continue into the critical section 	"Classical" version of semaphores:
 After leaving the critical section, a thread calls "V(s)" or "signal(s)" signal (s): s = s + 1 	wait (s):signal (s):if (s \leq 0)if (a thread is waiting)block the threadwake up one ofthat called wait(s)the waiting threadss = s - 1s = s + 1continue into CS
 ■ if (s ≤ 0), then wake up one of the threads that called wait(s), and run it so that it can continue into the critical section 1 	Do both work? What is the difference?? 2 Spring 2000, Lecture 10
Semaphores in Nachos	Semaphores in Nachos
The class Semaphore is defined in threads/synch.h and synch.cc	void Semaphore::P()
 The classes Lock and Condition are also defined, but their member functions are empty (implementation left as exercise) 	{ IntStatus oldLevel = interrupt-> SetLevel(IntOff); // disable interrupts
	while (value == 0) { // sema not avail
 Interesting functions: Semaphores: Semaphore::Semaphore() — creates a semaphore with specified name & value Semaphore::P() — semaphore wait Semaphore::V() — semaphore signal Locks: Lock::Acquire() Lock::Release() Condition variables: 	<pre>while (value == 0) { // sema not avail queue-> // so go to sleep Append((void *)currentThread); currentThread->Sleep(); } value; // semaphore available, // consume its value (void) interrupt-> // re-enable interrupts SetLevel(oldLevel);</pre>

Semaphores in Nachos (cont.)	The Coke Machine (Bounded-Buffer Producer-Consumer)
<pre>void Semaphore::V() { Thread *thread; IntStatus oldLevel = interrupt-> SetLevel(IntOff); thread = (Thread *)queue->Remove(); if (thread != NULL) // make thread ready,</pre>	<pre>/* number of full slots (Cokes) in machine */ semaphore fullSlot = 0; /* number of empty slots in machine */ semaphore emptySlot = 100; /* only one person accesses machine at a time */ semaphore mutex = 1; DeliveryPerson() { emptySlot->P(); /* empty slot avail? */ mutex->P(); /* exclusive access */ put 1 Coke in machine mutex->V(); fullSlot->V(); /* another full slot! */ } ThirstyPerson() { fullSlot->P(); /* full slot (Coke)? */ mutex->P(); /* exclusive access */ get 1 Coke from machine mutex->V(); emptySlot->V(); /* another empty slot! */</pre>
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From Semaphores to Locks and Condition Variables	Locks
 A semaphore serves two purposes: Mutual exclusion — protect shared data mutex in Coke machine milk in Too Much Milk Always a binary semaphore 	 Locks provide mutually exclusive access to shared data: A lock can be "locked" or "unlocked" (sometimes called "busy" and "free")
 Synchronization — temporally coordinate events (one thread waits for something, other thread signals when it's available) fullSlot and emptySlot in Coke machine Either a binary or counting semaphore 	 Operations on locks (Nachos syntax): Lock(*name) — create a new (initially unlocked) Lock with the specified name Lock::Acquire() — wait (block) until the lock is unlocked; then lock it
 Idea — two separate constructs: Locks — provide mutually exclusion Condition variables — provide synchronization 	 Lock::Release() — unlock the lock; then wake up (signal) any threads waiting on it in Lock::Acquire() Can be implemented:

• Trivially by binary semaphores (create a private lock semaphore, use P and V)

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• By lower-level constructs, much like semaphores are implemented

synchronization

environments

• Like semaphores, locks and condition

are available in many programming

variables are language-independent, and

Locks (cont.)

Conventions:

- Before accessing shared data, call Lock::Acquire() on a specific lock
 - Complain (via ASSERT) if a thread tries to Acquire a lock it already has
- After accessing shared data, call Lock:: Release() on that same lock
 - Complain if a thread besides the one that Acquired a lock tries to Release it
- Example of using locks for mutual exclusion (here, "milk" is a lock):

milk–>Acquire(); if (noMilk) buy milk; milk–>Release();

Thread A

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milk->Acquire(); if (noMilk) buy milk; milk->Release();

Thread B

 The test in threads/threadtest.cc should work exactly the same if locks are used instead of semaphores

Condition Variables

- Condition variables coordinate events
- Operations on condition variables (Nachos syntax):
 - Condition(*name) create a new instance of class Condition (a condition variable) with the specified name
 - After creating a new condition, the <u>programmer</u> must call Lock::Lock() to create a lock that will be associated with that condition variable
 - Condition::Wait(conditionLock) release the lock and wait (sleep); when the thread wakes up, immediately try to re-acquire the lock; return when it has the lock
 - Condition::Signal(conditionLock) if threads are waiting on the lock, wake up <u>one</u> of those threads and put it on the ready list; otherwise do nothing

Locks vs. Condition Variables

■ Consider the following code:

- Queue::Remove will only return an item if there's already one in the queue
- If the queue is empty, it might be more desirable for Queue::Remove to wait until there is something to remove
 - Can't just go to sleep if it sleeps while holding the lock, no other thread can access the shared queue, add an item to it, and wake up the sleeping thread
 - Solution: condition variables will let a thread sleep <u>inside</u> a critical section, by releasing the lock while the thread sleeps Spring 2000, Ledure 10

Condition Variables (cont.)

Operations (cont.):

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- Condition::Broadcast(conditionLock) if threads are waiting on the lock, wake up <u>all</u> of those threads and put them on the ready list; otherwise do nothing
- Important: a thread <u>must</u> hold the lock before calling Wait, Signal, or Broadcast
- Can be implemented:
 - Carefully by higher-level constructs (create and queue threads, sleep and wake up threads as appropriate)
 - Carefully by binary semaphores (create and queue semaphores as appropriate, use P and V to synchronize)
 - Does this work? More on this in a few minutes...
 - Carefully by lower-level constructs, much like semaphores are implemented

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Using Locks and Condition Variables	Comparing Semaphores and Condition Variables
 Associated with a data structure is both a lock and a condition variable 	Semaphores and condition variables are pretty similar — perhaps we can build condition variables out of semaphores
 Before the program performs an operation on the data structure, it acquires the lock 	■ Does this work?
 If it needs to wait until another operation puts the data structure into an appropriate state, it uses the condition variable to wait 	Condition::Wait() { Condition::Signal() { sema->P(); sema->V(); }
 Unbounded-buffer producer-consumer: Lock *lk; int avail = 0; Condition *c; 	 No, we're going to use these condition operations inside a lock. What happens if we use semaphores inside a lock?
/* consumer */ /* producer */ while (1) {	How about this?
<pre>while (1) {</pre>	 Condition::Wait() { Condition::Signal() { lock->Release(); sema->V(); sema->P(); } lock->Acquire(); } How do semaphores and condition variables differ with respect to keeping track of history?
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Comparing Semaphores and Condition Variables (cont.)	Two Kinds of Condition Variables
and Condition Variables (cont.) Condition::Wait() { Condition::Signal() { lock->Release(); sema->V();	 Two Kinds of Condition Variables Hoare-style (named after C.A.R. Hoare, used in most textbooks including OSC):
and Condition Variables (cont.) Condition::Wait() { Condition::Signal() {	 Hoare-style (named after C.A.R. Hoare, used in most textbooks including OSC): When a thread performs a Signal(), it gives up the lock (and the CPU)
and Condition Variables (cont.)Condition::Wait() {Condition::Signal() {lock->Release();sema->V();sema->P();}	 Hoare-style (named after C.A.R. Hoare, used in most textbooks including OSC): When a thread performs a Signal(), it gives up the lock (and the CPU) The waiting thread is picked as the next thread that gets to run
 and Condition Variables (cont.) Condition::Wait() { Condition::Signal() { lock->Release(); sema->V(); sema->P(); } lock->Acquire(); } Semaphores have a value, CVs do not! On a <u>semaphore</u> signal (a V), the value of the semaphore is always incremented, 	 Hoare-style (named after C.A.R. Hoare, used in most textbooks including OSC): When a thread performs a Signal(), it gives up the lock (and the CPU) The waiting thread is picked as the next thread that gets to run Previous example uses Hoare-style CVs Mesa-style (used in Mesa, Nachos, and
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 and Condition Variables (cont.) Condition::Wait() { Condition::Signal() { lock->Release(); sema->V(); sema->P(); } lock->Acquire(); } Semaphores have a value, CVs do not! On a <u>semaphore</u> signal (a V), the value of the semaphore is always incremented, even if no one is waiting Later on, if a thread does a semaphore wait (a P), the value of the semaphore is decremented and the thread <u>continues</u> On a <u>condition variable</u> signal, if no one is waiting, the signal has no effect 	 Hoare-style (named after C.A.R. Hoare, used in most textbooks including OSC): When a thread performs a Signal(), it gives up the lock (and the CPU) The waiting thread is picked as the next thread that gets to run Previous example uses Hoare-style CVs Mesa-style (used in Mesa, Nachos, and most real operating systems): When a thread performs a Signal(), it keeps the lock (and the CPU) The waiting thread gets put on the ready gueue with no special priority There is no guarantee that it will be picked as the next thread that gets to run
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 and Condition Variables (cont.) Condition::Wait() { Condition::Signal() { lock->Release(); sema->V(); sema->P(); } lock->Acquire(); } Semaphores have a value, CVs do not! On a <u>semaphore</u> signal (a V), the value of the semaphore is always incremented, even if no one is waiting Later on, if a thread does a semaphore is decremented and the thread <u>continues</u> On a <u>condition variable</u> signal, if no one is waiting, the signal has no effect Later on, if a thread does a condition 	 Hoare-style (named after C.A.R. Hoare, used in most textbooks including OSC): When a thread performs a Signal(), it gives up the lock (and the CPU) The waiting thread is picked as the next thread that gets to run Previous example uses Hoare-style CVs Mesa-style (used in Mesa, Nachos, and most real operating systems): When a thread performs a Signal(), it keeps the lock (and the CPU) The waiting thread gets put on the ready queue with no special priority There is no guarantee that it will be picked as the next thread that gets to run Wore yet, another thread may even run