Dealing with Deadlock (Review)

- *The Ostrich Approach* stick your head in the sand and ignore the problem
- Deadlock avoidance consider resources and requests, and only fulfill requests that will not lead to deadlock
 - ✗ Too hard for centralized systems, even harder in distributed systems!!
- Deadlock prevention eliminate one of the 4 deadlock conditions
- Deadlock detection and recovery detect, then break the deadlock
 - X More difficult when state is distributed
 - Must avoid reporting false deadlock
- ➡ In distributed systems, we typically assume single resource instances

Distributed Deadlock Detection

- Path-pushing
 - WFG is disseminated as *paths* sequences of edges
 - Deadlock if process detects local cycle
- Edge-chasing
 - Probe messages circulate
 - Blocked processes forward probe to processes holding requested resources
 - Deadlock if initiator receives own probe
- Diffusion

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- Query messages sent to dependent set
- Active processes discard query, blocked processes forward query under certain conditions, reply under other conditions
- Deadlock if initiator receives replies to all its queries

Deadlock Detection in a Distributed Environment (Review)

- Centralized algorithms
 - Coordinator maintains global WFG and searches it for cycles
 - Ho and Ramamoorthy's two-phase and one-phase algorithms
- Distributed algorithms
 - Global WFG, with responsibility for detection spread over many sites
 - Obermarck's path-pushing
 - Chandy, Misra, and Haas's edge-chasing
- Hierarchical algorithms
 - Hierarchical organization, site detects deadlocks involving only its descendants
 - Menasce and Muntz's algorithm
 - Ho and Ramamoorthy's algorithm

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Distributed Deadlock Detection (Obermarck's Path-Pushing, 1982)

- Individual sites maintain local WFGs
 - Nodes for local processes
 - Node "Pex" represents external processes
- Deadlock detection:
 - If a site Si finds a cycle that <u>does not</u> involve Pex, it has found a deadlock
 - If a site Si finds a cycle that <u>does</u> involve Pex, there is the possibility of a deadlock
 - It sends a message containing its detected cycle to any sites involved in Pex
 - If site Sj receives such a message, it updates its local WFG graph, and searches it for a cycle
 - If Sj finds a cycle that <u>does not</u> involve its Pex, it has found a deadlock
 - If Sj finds a cycle that <u>does</u> involve its Pex, it sends out a message...

X Can report false deadlock

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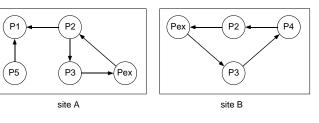
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Distributed Deadlock Detection (Obermarck's Path-Pushing) (cont.)

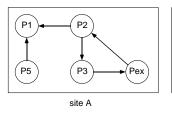
Example:

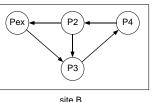
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Initial state:



Site A detects cycle, sends message describing that cycle to Site B:





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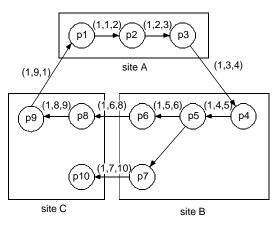
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Site B updates its WFG, finds cycle not involving $Pex \Rightarrow deadlock$

Distributed Deadlock Detection (Chandy, Misra, and Haas's Edge-Chasing) (cont.)

Example where p1 initiates deadlock detection by sending a probe:



- ✓ Doesn't report false deadlock (why not?)
- Easy to implement, small messages, relatively small number of messages
- ✓ Don't have to collect and maintain WFGs

Distributed Deadlock Detection (Chandy, Misra, and Haas's Edge-Chasing, 1983)

- When a process has to wait for a resource (blocks), it sends a *probe* message to process holding the resource
 - Process can request (and can have to wait for) multiple resources at once
 - Probe message contains 3 values:
 - ID of process that blocked
 - ID of process sending message
 - ID of process message was sent to
- When a blocked process receives a probe, it propagates the probe to the process(es) holding resources that it has requested
 - ID of blocked process stays the same, other two values updated as appropriate
 - If the blocked process receives its own probe, there is a deadlock

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Distributed Deadlock Detection (Evaluation of Algorithms)

- Distributed deadlock detection
 - Sites share responsibility for WFG and deadlock detection
 - ✓ No single point of failure
 - Robust multiple sites can detect the same deadlock
 - X Avoiding false deadlock is hard
- Obermarck's path-pushing
 - n(n-1)/2 messages to detect deadlock
 n sites
 - size of a message is O(n)
- Chandy, Misra, and Haas's edge chasing:
 - m(n-1)/2 messages to detect deadlock
 m processes, n sites
 - size of a message is 3 integers

Hierarchical Deadlock Detection

- Sites are organized hierarchically
 - A site is only responsible for detecting deadlocks involving its children sites
- Menasce and Muntz, 1979
 - Sites (called *controllers*) are organized as a tree
 - Leaf controllers manage resources
 - Each maintains a local WFG concerned only about its own resources
 - Interior controllers are responsible for deadlock detection
 - Each maintains a global WFG that is the union of the WFGs of its children
 - Detects deadlock among its children
 - Whenever a controller changes its WFG due to a resource request, it propagates that change to its parent
 - Parent updates its WFG, and searches it for cycles, propagates changes upward

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Hierarchical Deadlock Detection (cont.)

- Ho and Ramamoorthy, 1982
 - Sites are grouped into disjoint clusters
 - Periodically, a site is chosen as a *central* control site
 - Central control site chooses a control site for each cluster
 - Control site collects status tables from its cluster, and uses the Ho and Ramamoorthy one-phase centralized deadlock detection algorithm to detect deadlock in that cluster
 - All control sites then forward their status information and WFGs to the central control site, which combines that information into a global WFG and searches it for cycles
 - Control sites detect deadlock in clusters
 - Central control site detects deadlock
 <u>between</u> clusters

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Perspective

- Correctness of algorithms
 - There are few formal methods to prove the correctness of deadlock detection algorithms — we usually use informal or intuitive arguments
- Performance
 - Usually measured as the number of messages exchanged to detect deadlock
 - Deceptive since message are also exchanged when there is no deadlock
 - Doesn't account for size of the message
 - Should also measure:
 - Deadlock persistence time (measure of how long resources are wasted)
 - Tradeoff with communication overhead
 - Storage overhead (graphs, tables, etc.)
 - Processing overhead to search for cycles
 - Time to optimally recover from deadlock

After Deadlock Detection: Deadlock Recovery

- How often does deadlock detection run?
 - After every resource request?
 - Less often (e.g., every hour or so, or whenever resource utilization gets low)?
- What if OS detects a deadlock?
 - Terminate a process
 - All deadlocked processes
 - One process at a time until no deadlock
 - Which one?
 - One with most resources?
 - One with less cost?
 - » CPU time used, needed in future
 - » Resources used, needed
 - That's a choice similar to CPU scheduling
 - Is it acceptable to terminate process(es)?
 - May have performed a long computation
 - » Not ideal, but OK to terminate it
 - Maybe have updated a file or done I/O
 - » Can't just start it over again!

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After Deadlock Detection: Deadlock Recovery (cont.)

- Any less drastic alternatives?
 - Preempt resources
 - One at a time until no deadlock
 - Which "victim"?
 - Again, based on cost, similar to CPU scheduling
 - Is rollback possible?
 - Preempt resources take them away
 - Rollback "roll" the process back to some safe state, and restart it from there
 - » OS must *checkpoint* the process frequently write its state to a file
 - Could roll back to beginning, or just enough to break the deadlock
 - » This second time through, it has to wait for the resource
 - » Has to keep multiple checkpoint files, which adds a lot of overhead
 - Avoid starvation
 - May happen if decision is based on same cost factors each time
 - Don't keep preempting same process (i.e., set some limit)

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