Communication Models in Distributed Systems

- Peer-to-peer
 - Producer / consumer
- Client / server
 - Clients ask dedicated server to perform some specific service
- Central coordinator

(many-to-one)

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- Nodes send information to coordinator; coordinator makes decision
- Central point of failure
- Distributed consensus (one-to-many)
 - Nodes send information to each other; group as a whole reaches a consensus
 - Large amount of communication required

Client / Server Model using Message Passing



- Client / server model
 - Server = process (or collection of processes) that provides a service
 - Example: name service, file service
 - Client -- process that uses the service
 - Request / reply protocol:
 - Client sends request message to server, asking it to perform some service
 - Server performs service, sends reply message containing results or error code

The Producer-Consumer Problem

- One process is a producer of information; another is a consumer of that information
- Solution when the two processes have a shared memory in common:



Message Passing using Send & Receive

- Blocking send:
 - send(destination-process, message)
 - Sends a message to another process, then blocks (i.e., gets suspended by OS) until message is received
- Blocking receive:
 - receive(source-process, message)
 - Blocks until a message is received (may be minutes, hours, ...)
- Producer-Consumer problem:

/* producer */ repeat forever

produce item nextp

repeat forever receive(producer,nextc) ... consume item nextc

send(consumer, nextp) end repeat

end repeat

/* consumer */

Buffering

- Link may be able to temporarily queue some messages during communication
- Zero capacity:

(queue of length 0)

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- Blocking communication
- Sender must wait until receiver receives the message — this synchronization to exchange data is called a *rendezvous*
- Bounded capacity: (queue of length *n*)
 - If receiver's queue is not full, new message is put on queue, and sender can continue executing immediately
 - If queue is full, sender must block until space is available in the queue
- Unbounded capacity: (infinite queue)
 - Non-blocking communication
 - Sender can always continue

Direct vs. Indirect Communication

- Direct communication explicitly name the process you're communicating with
 - send(*destination-process*, *message*)
 - receive(*source-process*, *message*)
 - Variation: receiver may be able to use a "wildcard" to receive from any source
 - Receiver <u>can not</u> distinguish between multiple "types" of messages from sender
- Indirect communication communicate using mailboxes (owned by receiver)
 - send(*mailbox*, *message*)
 - receive(mailbox, message)
 - Variation: ... "wildcard" to receive from any source into that mailbox
 - Receiver <u>can</u> distinguish between multiple "types" of messages from sender
 - Some systems use "tags" instead of mailboxes

Non-blocking Send & Receive

- Non-blocking send:
 - Sends, then goes on to next instruction without waiting for an acknowledgment
 - Advantage: sending process can execute in parallel with message transmission
 - Problem: must avoid modifying message buffer until message has been received (but how do you know?)
 - 1.Copy message from user space to kernel space, then let process continue
 - 2. Keep message in user space, have kernel send interrupt when message has been received (difficult to program)
- Non-blocking receive:
 - Receive returns with buffer, but doesn't know if there's a message there or not
 - Must poll or receive interrupt when message is ready and process should perform a receive (difficult to program)

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LAM / MPI

- MPI = Message Passing Interface
- LAM = Local Area Multicomputer
 - Implementation of MPI from the OSC that "simulates" a multicomputer
- See AOS class web page
 - "Using LAM/MPI in the KSU MCS Dept."
 - "MAN T&EC MPI Tutorial"
 - Other information is optional
- MPI uses the SPMD (Same Program, Different Data) programming model
 - Same program runs on all machines
 - May choose to have one program run "master" code, and others run "worker / slave" code

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