

Nachos

- Nachos is an instructional operating system developed at UC Berkeley
- Nachos consists of two main parts:
 - Operating system
 - This is the part of the code that you will study and modify
 - This code is in the **threads**, **userprog**, and **network** directories
 - We will not study user programs, so you can ignore files in the **userprog** directory
 - Machine emulator — simulates a (slightly old) MIPS CPU, registers, memory, timer (clock), console, disk drive, and network
 - You will study this code, but will not be allowed to modify it
 - This code is in the **machine** directory
- The OS and machine emulator run together as a single UNIX process

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Preparing for the First Project

- Copy the files and compile Nachos
 - See “Getting Started” (online)
 - Threads version, then network version
- Start reading:
 - Read Nachos “Overview paper” (online)
 - Read Section 2 “Nachos Machine” and Section 3 “Nachos Threads” in Narten’s “A Road Map Through Nachos” (online)
 - Read about threads, synchronization, interrupts, and networking in Kalra’s “Salsa — An OS Tutorial” (online)
 - Start looking at the code in the **threads**, **machine** and **network** directories
 - Road Map plus printouts of all code are available in the MCS office for \$4.50
- If you are not familiar with C++ or the gdb debugger, see the class web page

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Preparing for the First Project (cont.)

- Compiling the code
 - Nachos source code is available in ~walker/pub
 - Read ~walker/pub/README
 - Decide where you want to work, so you can copy files from the appropriate directory into your account
 - ~walker/pub/nachos-3.4-hp
 - For HP workstations (aegis, intrepid)
 - Recommended
 - ~walker/pub/nachos-3.4-sparc
 - For Sun workstations (nimitz)
 - ~walker/pub/nachos-3.4-orig
 - The original, unmodified version
 - Read “Project 1 — Getting Started” on the class web page to find out how to copy the necessary files to your account, and compile an executable copy of Nachos into the **threads** directory

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Nachos — The Emulated Machine

- Code is in the **machine** directory
- **machine.h**, **machine.cc** — emulates the part of the machine that executes user programs: main memory, processor registers, etc.
- **mipssim.cc** — emulates the integer instruction set of a MIPS R2/3000 CPU.
- **interrupt.h**, **interrupt.cc** — manages enabling and disabling interrupts as part of the machine emulation.
- **timer.h**, **timer.cc** — emulates a clock that periodically causes an interrupt to occur.
- **stats.h** — collects interesting statistics.

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Nachos — The Operating System

- For now, we will mostly be concerned with code in the **threads** directory
- **main.cc, threadtest.cc** — a simple test of the thread routines.
- **system.h, system.cc** — Nachos startup/shutdown routines.
- **thread.h, thread.cc** — thread data structures and thread operations such as thread fork, thread sleep and thread finish.
- **scheduler.h, scheduler.cc** — manages the list of threads that are ready to run.
- **list.h, list.cc** — generic list management.
- **utility.h, utility.cc** — some useful definitions and debugging routines.

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Nachos Threads

- As distributed, Nachos does not support multiple processes, only threads
 - All threads share / execute the same code (the Nachos source code)
 - All threads share the same global variables (have to worry about synch.)
- Threads can be in one of 4 states:
 - JUST_CREATED — exists, has not stack, not ready yet
 - READY — on the ready list, ready to run
 - RUNNING — currently running (variable `currentThread` points to currently running thread)
 - BLOCKED — waiting on some external even, probably should be on some event waiting queue

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Scheduling in Nachos

- The Nachos scheduler is non-preemptive FCFS — chooses next process when:
 - Current thread calls `Thread::Sleep()` (to block (wait) on some event)
 - Current thread calls `Thread::Yield()` to explicitly yield the CPU
- `main()` (in `threads/main.cc`) calls `Initialize()` (in `threads/system.cc`)
 - which starts scheduler, an instance of class `Scheduler` (defined in `threads/scheduler.h` and `scheduler.cc`)
- Interesting functions:
 - Mechanics of running a thread:
 - `Scheduler::ReadyToRun()` — puts a thread at the tail of the ready queue
 - `Scheduler::FindNextToRun()` — returns thread at the head of the ready queue
 - `Scheduler::Run()` — switches to thread

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Scheduling in Nachos (cont.)

```
Scheduler::Scheduler ( )
{
    readyList = new List;
}

void
Scheduler::ReadyToRun (Thread *thread)
{
    DEBUG('t',
        "Putting thread %s on ready list.\n",
        thread->getName());
    thread->setStatus(READY);
    readyList->Append((void *)thread);
}

Thread *
Scheduler::FindNextToRun ( )
{
    return (Thread *)readyList->Remove();
}
```

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Scheduling in Nachos (cont.)

```
void
Scheduler::Run (Thread *nextThread)
{
    Thread *oldThread = currentThread;

    oldThread->CheckOverflow();
    currentThread = nextThread;
    currentThread->setStatus(RUNNING);

    DEBUG('t', "Switching from thread \"%s\"
to thread \"%s\"\n",oldThread->getName(),
    nextThread->getName());
    SWITCH(oldThread, nextThread);
    DEBUG('t', "Now in thread \"%s\"\n",
    currentThread->getName());

    if (threadToBeDestroyed != NULL) {
        delete threadToBeDestroyed;
        threadToBeDestroyed = NULL;
    }
}
```

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Working with a Non-Preemptive Scheduler

- The Nachos scheduler is non-preemptive FCFS — chooses next process when:
 - Current thread calls Thread::Sleep() (to block (wait) on some event)
 - Current thread calls Thread::Yield() to explicitly yield the CPU
- Some interesting functions:
 - Thread::Fork() — create a new thread to run a specified function with a single argument, and put it on the ready queue
 - Thread::Yield() — if there are other threads waiting to run, suspend this thread and run another
 - Thread::Sleep() — this thread is waiting on some event, so suspend it, and hope someone else wakes it up later
 - Thread::Finish() — terminate the currently running thread

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Manipulating Threads in Nachos

```
void
Thread::Fork(VoidFunctionPtr func, int arg)
{
    DEBUG('t',"Forking thread \"%s\" with
    func = 0x%x, arg = %d\n",
    name, (int) func, arg);

    StackAllocate(func, arg);

    IntStatus oldLevel = interrupt->
    SetLevel(IntOff);
    scheduler->ReadyToRun(this);
    (void) interrupt->SetLevel(oldLevel);
}
```

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Manipulating Threads in Nachos (cont.)

```
void
Thread::Yield ()
{
    Thread *nextThread;

    IntStatus oldLevel = interrupt->
    SetLevel(IntOff);

    ASSERT(this == currentThread);
    DEBUG('t', "Yielding thread \"%s\"\n",
    getName());

    nextThread = scheduler->
    FindNextToRun();
    if (nextThread != NULL) {
        scheduler->ReadyToRun(this);
        scheduler->Run(nextThread);
    }
    (void) interrupt->SetLevel(oldLevel);
}
```

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Manipulating Threads in Nachos (cont.)

```
void
Thread::Sleep ()
{
    Thread *nextThread;

    ASSERT(this == currentThread);
    ASSERT(interrupt->getLevel() == IntOff);
    DEBUG('t', "Sleeping thread \"%s\"\n",
        getName());

    status = BLOCKED;
    while ((nextThread = scheduler->
        FindNextToRun()) == NULL)
        interrupt->Idle();

    scheduler->Run(nextThread);
}
```

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Semaphores in Nachos

- The class Semaphore is defined in **threads/synch.h** and **synch.cc**
 - The classes Lock and Condition are also defined, but their member functions are empty (implementation left as exercise)
- Interesting functions:
 - Semaphores:
 - Semaphore::Semaphore() — creates a semaphore with specified name & value
 - Semaphore::P() — semaphore wait
 - Semaphore::V() — semaphore signal
 - Locks:
 - Lock::Acquire()
 - Lock::Release()
 - Condition variables:
 - Condition::Wait()
 - Condition::Signal()

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Networking in Nachos

- Low-level emulation of the physical network is defined in **machine/network.h** and **network.cc**
 - Provides ordered, unreliable, fixed-size packet delivery to other Nachos machines
 - Packets can be dropped (user-controllable), but are never corrupted
- High-level protocols for communication between multiple Nachos machines are defined in **network/post.h** and **post.cc**
 - An instance of class PostOffice manages a set of MailBoxes for each machine
 - PostOffice::Send() sends a message to a specific machine and mailbox
 - PostOffice::Receive() retrieves a message, or waits if none is available
 - Could provide reliable delivery of arbitrary-size messages, but currently does **not** (see Spring'97 AOS Project 1)

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