Details of Semaphore Operation

- Semaphore "s" is initially 1
- Before entering the critical section, a thread calls "P(s)" or "wait(s)"
 - wait (s):
 - \blacksquare s = s 1
 - \blacksquare if (s < 0)

block the thread that called wait(s) on a queue associated with semaphore s

otherwise

let the thread that called wait(s) continue into the critical section

- After leaving the critical section, a thread calls "V(s)" or "signal(s)"
 - signal (s):
 - \blacksquare s = s + 1
 - if $(s \le 0)$, then

wake up one of the threads that called wait(s), and run it so that it can continue into the critical section

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Two Versions of Semaphores

■ Semaphores from last time (simplified):

```
wait (s):signal (s):s = s - 1s = s + 1if (s < 0)</td>if (s \le 0)block the thread<br/>that called wait(s)wake up one of<br/>the waiting threadsotherwisecontinue into CS
```

■ "Classical" version of semaphores:

```
wait (s):signal (s):if (s \leq 0)if (a thread is waiting)block the thread<br/>that called wait(s)wake up one of<br/>the waiting threadss = s - 1s = s + 1continue into CS
```

■ Do both work? What is the difference??

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Semaphores in Nachos

- The class Semaphore is defined in threads/synch.h and synch.cc
 - The classes Lock and Condition are also defined, but their member functions are empty (implementation left as exercise)
- Interesting functions:
 - Semaphores:
 - Semaphore::Semaphore() creates a semaphore with specified name & value
 - Semaphore::P() semaphore wait
 - Semaphore::V() semaphore signal
 - Locks:
 - Lock::Acquire()
 - Lock::Release()
 - Condition variables:
 - Condition::Wait()
 - Condition::Signal()

Semaphores in Nachos

```
void
Semaphore::P()
  IntStatus oldLevel = interrupt->
     SetLevel(IntOff); // disable interrupts
  while (value == 0) {
                           // sema not avail
     queue->
                           // so go to sleep
        Append((void *)currentThread);
     currentThread->Sleep();
  }
                    // semaphore available,
  value--;
                    // consume its value
  (void) interrupt->
                      // re-enable interrupts
     SetLevel(oldLevel);
```

Semaphores in Nachos (cont.)

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From Semaphores to Locks and Condition Variables

- A semaphore serves two purposes:
 - Mutual exclusion protect shared data
 - mutex in Coke machine
 - milk in Too Much Milk
 - Always a binary semaphore
 - Synchronization temporally coordinate events (one thread waits for something, other thread signals when it's available)
 - fullSlot and emptySlot in Coke machine
 - Either a binary or counting semaphore
- Idea two separate constructs:
 - Locks provide mutually exclusion
 - Condition variables provide synchronization
 - Like semaphores, locks and condition variables are language-independent, and are available in many programming environments

The Coke Machine (Bounded-Buffer Producer-Consumer)

```
/* number of full slots (Cokes) in machine */
semaphore fullSlot = 0;
/* number of empty slots in machine */
semaphore emptySlot = 100;
/* only one person accesses machine at a time */
semaphore mutex = 1;
DeliveryPerson()
    emptySlot->P();
                            /* empty slot avail? */
    mutex->P();
                            /* exclusive access */
    put 1 Coke in machine
    mutex->V():
    fullSlot->V();
                            /* another full slot! */
}
ThirstyPerson()
                            /* full slot (Coke)? */
    fullSlot->P();
                            /* exclusive access */
    mutex->P();
    get 1 Coke from machine
    mutex->V();
    emptySlot->V();
                            /* another empty slot! */
}
```

Locks

- Locks provide mutually exclusive access to shared data:
 - A lock can be "locked" or "unlocked" (sometimes called "busy" and "free")
- Operations on locks (Nachos syntax):
 - Lock(*name) create a new (initially unlocked) Lock with the specified name
 - Lock::Acquire() wait (block) until the lock is unlocked; then lock it
 - Lock::Release() unlock the lock; then wake up (signal) any threads waiting on it in Lock::Acquire()
- Can be implemented:
 - Trivially by binary semaphores (create a private lock semaphore, use P and V)
 - By lower-level constructs, much like semaphores are implemented

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Locks (cont.)

■ Conventions:

- Before accessing shared data, call Lock::Acquire() on a specific lock
 - Complain (via ASSERT) if a thread tries to Acquire a lock it already has
- After accessing shared data, call Lock:: Release() on that same lock
 - Complain if a thread besides the one that Acquired a lock tries to Release it
- Example of using locks for mutual exclusion (here, "milk" is a lock):

Thread A Thread B

milk->Acquire(); milk->Acquire(); if (noMilk) if (noMilk)
buy milk; buy milk; buy milk; milk->Release();

 The test in threads/threadtest.cc should work exactly the same if locks are used instead of semaphores

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Condition Variables

- Condition variables coordinate events
- Operations on condition variables (Nachos syntax):
 - Condition(*name) create a new instance of class Condition (a condition variable) with the specified name
 - After creating a new condition, the <u>programmer</u> must call Lock::Lock() to create a lock that will be associated with that condition variable
 - Condition::Wait(conditionLock) release the lock and wait (sleep); when the thread wakes up, immediately try to re-acquire the lock; return when it has the lock
 - Condition::Signal(conditionLock) if threads are waiting on the lock, wake up one of those threads and put it on the ready list; otherwise do nothing

Locks vs. Condition Variables

Consider the following code:

```
Queue::Add() {
    lock->Acquire();
    add item
    lock->Release();
}

lock->Release();

remove item
lock->Release();
return item;
}
```

- Queue::Remove will only return an item if there's already one in the queue
- If the queue is empty, it might be more desirable for Queue::Remove to wait until there is something to remove
 - Can't just go to sleep if it sleeps while holding the lock, no other thread can access the shared queue, add an item to it, and wake up the sleeping thread
 - Solution: condition variables will let a thread sleep <u>inside</u> a critical section, by releasing the lock while the thread sleeps

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Condition Variables (cont.)

- Operations (cont.):
 - Condition::Broadcast(conditionLock) if threads are waiting on the lock, wake up <u>all</u> of those threads and put them on the ready list; otherwise do nothing
- Important: a thread must hold the lock before calling Wait, Signal, or Broadcast
- Can be implemented:
 - Carefully by higher-level constructs (create and queue threads, sleep and wake up threads as appropriate)
 - Carefully by binary semaphores (create and queue semaphores as appropriate, use P and V to synchronize)
 - Does this work? More on this in a few minutes...
 - Carefully by lower-level constructs, much like semaphores are implemented

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Using Locks and Condition Variables

- Associated with a data structure is both a lock and a condition variable
 - Before the program performs an operation on the data structure, it acquires the lock
 - If it needs to wait until another operation puts the data structure into an appropriate state, it uses the condition variable to wait
- Unbounded-buffer producer-consumer:

```
Lock *lk:
                       int avail = 0:
Condition *c:
                       /* consumer */
/* producer */
                       while (1) {
while (1) {
                           Ik-> Acquire();
    lk->Acquire( );
                           if (avail==0)
                               c->Wait(lk);
    produce next item
    avail++;
                           consume next item
    c->Signal(lk)
                           avail--:
    lk->Release();
                           lk->Release();
}
                       }
```

Comparing Semaphores and Condition Variables (cont.)

- Semaphores have a value, CVs do not!
- On a <u>semaphore</u> signal (a V), the value of the semaphore is always incremented, even if no one is waiting
 - Later on, if a thread does a semaphore wait (a P), the value of the semaphore is decremented and the thread continues
- On a <u>condition variable</u> signal, if no one is waiting, the signal has no effect
 - Later on, if a thread does a condition variable wait, it <u>waits</u> (it always waits!)
 - It doesn't matter how many signals have been made beforehand

Comparing Semaphores and Condition Variables

- Semaphores and condition variables are pretty similar — perhaps we can build condition variables out of semaphores
- Does this work?

```
Condition::Wait() {
    sema->P();
}
Condition::Signal() {
    sema->V();
}
```

- No, we're going to use these condition operations inside a lock. What happens if we use semaphores inside a lock?
- How about this?

```
Condition::Wait() {
    lock->Release();
    sema->P();
    lock->Acquire();
}
```

 How do semaphores and condition variables differ with respect to keeping track of history?

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Two Kinds of Condition Variables

- Hoare-style (named after C.A.R. Hoare, used in most textbooks including *OSC*):
 - When a thread performs a Signal(), it gives up the lock (and the CPU)
 - The waiting thread <u>is picked as the next</u> thread that gets to run
 - Previous example uses Hoare-style CVs
- Mesa-style (used in Mesa, Nachos, and most real operating systems):
 - When a thread performs a Signal(), it keeps the lock (and the CPU)
 - The waiting thread <u>gets put on the ready</u> <u>queue</u> with no special priority
 - There is <u>no guarantee</u> that it will be picked as the next thread that gets to run
 - Wore yet, another thread may even run and acquire the lock before it does!
 - When using Mesa-style CVs, <u>always</u> surround the Wait() with a "while" loop

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