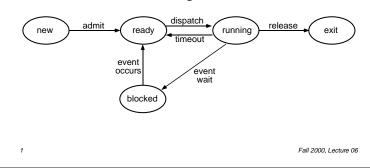
## A Five-State Process Model (Review)

- The not-running state in the two-state model has now been split into a ready state and a blocked state
  - Running currently being executed
  - Ready prepared to execute
  - Blocked waiting for some event to occur (for an I/O operation to complete, or a resource to become available, etc.)
  - New just been created
  - Exit just been terminated
- State transition diagram:



## UNIX Process Model (cont.)

- Start in Created, go to either:
  - Ready to Run, in Memory
  - or Ready to Run, Swapped (Out) if there isn't room in memory for the new process
  - Ready to Run, in Memory is basically same state as Preempted (dotted line)
    - Preempted means process was returning to user mode, but the kernel switched to another process instead
- When scheduled, go to either:
  - User Running (if in user mode)
  - or Kernel Running (if in kernel mode)
  - Go from U.R. to K.R. via system call
- Go to Asleep in Memory when waiting for some event, to RtRiM when it occurs
- Go to Sleep, Swapped if swapped out Fall 2000, Lecture 06

## **UNIX Process Model**

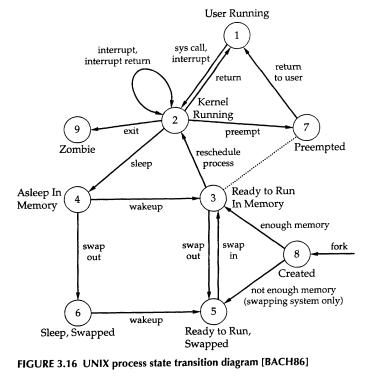


Figure from *Operating Systems*, 2nd edition, Stallings, Prentice Hall, 1995 Original diagram from *The Design of the UNIX Operating System*, M. Bach, Prentice Hall, 1986 *Fall 2000, Lecture 06* 

# **Process Creation in UNIX**

- One process can create another process, perhaps to do some work for it
  - The original process is called the parent
  - The new process is called the *child*
  - The child is an (almost) identical copy of parent (same code, same data, etc.)
  - The parent can either wait for the child to complete, or continue executing in parallel (*concurrently*) with the child
- In UNIX, a process creates a child process using the system call fork()
  - In child process, fork() returns 0
  - In parent process, fork() returns process id of new child
- Child often uses exec() to start another completely different program

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#### Example of UNIX Process Creation #include <sys/types.h> #include <stdio.h> /\* global (external) variable \*/ int a = 6; int main(void) { /\* local variable \*/ int b; /\* process id \*/ pid\_t pid; b = 88; printf("..before fork\n"); pid = fork();if (pid == 0) { /\* child \*/ a++; b++; /\* parent \*/ } else wait(pid); printf("..after fork, a = %d, b = %d n", a, b; exit(0); } aegis> fork ...before fork ..after fork, a = 7, b = 89 ...after fork, a = 6, b = 88Fall 2000, Lecture 06 5 6

## **Schedulers**

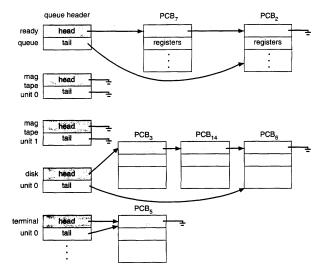
- Medium-term scheduler (demand paging)
  - On time-sharing systems, does some of what long-term scheduler used to do
  - May swap processes out of memory temporarily
  - May suspend and resume processes
  - Goal: balance load for better throughput
- Short-term scheduler (CPU scheduler)
  - Executes frequently, about one hundred times per second (every 10ms)
  - Runs whenever:
    - Process is created or terminated
    - Process switches from running to blocked
    - Interrupt occurs
  - Selects process from those that are ready to execute, allocates CPU to that process

# Context Switching

- Stopping one process and starting another is called a context switch
  - When the OS stops a process, it stores the hardware registers (PC, SP, etc.) and any other state information in that process' PCB
  - When OS is ready to execute a waiting process, it loads the hardware registers (PC, SP, etc.) with the values stored in the new process' PCB, and restores any other state information
  - Performing a context switch is a relatively expensive operation
    - However, time-sharing systems may do 100-1000 context switches a second
    - Why so often?
    - Why not more often?

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## **Ready Queue and** Various I/O Device Queues



From Operating System Concepts, Silberschatz & Galvin., Addison-Wesley, 1994

- OS organizes all waiting processes (their PCBs, actually) into a number of queues
  - Queue for ready processes
  - Queue for processes waiting on each device (e.g., mouse) or type of event (e.g., message)

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